

Service Manual

TOYOTA

ORDER NO.
CRT3251

SCION AUDIO SYSTEM SINGLE CD DECK

DEH-M8047ZT_{UC}



VEHICLE	DESTINATION	PRODUCED AFTER	TOYOTA PART No.	ID No.	PIONEER MODEL No.
xA, xB, tC	U.S.A., CANADA	May 2004	86120-0W100	T1804	DEH-M8047ZT/UC

**This service manual should be used together with the manual(s) listed below.
For the parts numbers, adjustments, etc. which are not shown in this manual,
refer to the following manual(s).**

Model No.	Order No.	Mech.Module	Remarks
DEH-M8037ZT/UC	CRT3062		
CX-3057	CRT3026	S10MP3	CD Mech. Module:Circuit Description, Mech. Description, Disassembly

EXPLODED VIEWS AND PARTS LIST

PACKING(Page 5)

● PACKING SECTION PARTS LIST

Mark	No.	Description	DEH-M8037ZT/UC	DEH-M8047ZT/UC
	8	Contain Box	CHL5058	CHL5227
	11	Owner's Manual	CRB1826	CRB1933

EXTERIOR(Page 6)

● EXTERIOR SECTION PARTS LIST

Mark	No.	Description	DEH-M8037ZT/UC	DEH-M8047ZT/UC
	6	CD Mechanism Module(S10MP3)	CXK5680	CXK5682
	8	Case	CNB2842	CNB3036
	12	Main Unit	CWM8737	CWM9479
	50	Keyboard Unit	CWM8738	CWM9481
	58	Grille Unit	CXC1323	CXC3124

CD MECHANISM MODULE(Page 8)

● CD MECHANISM MODULE SECTION PARTS LIST

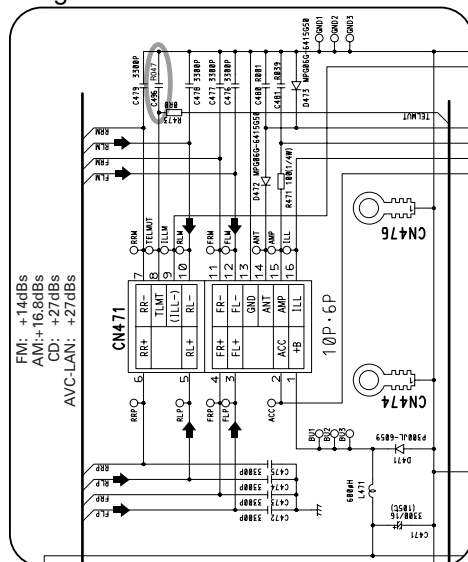
Mark	No.	Description	DEH-M8037ZT/UC	DEH-M8047ZT/UC
	1	CD Core Unit(S10MP3)	CWX2810	CWX3054

ELECTRICAL PARTS LIST(Page 38)

Main Unit

Circuit Symbol & No.	Part Name	DEH-M8037ZT/UC	DEH-M8047ZT/UC
IC701	IC	PD5861A	PEG003A
R764		RS1/16S102J	RS1/16S152J
R765		RS1/16S102J	RS1/16S152J
C496		Not used	CKSQYB473K50

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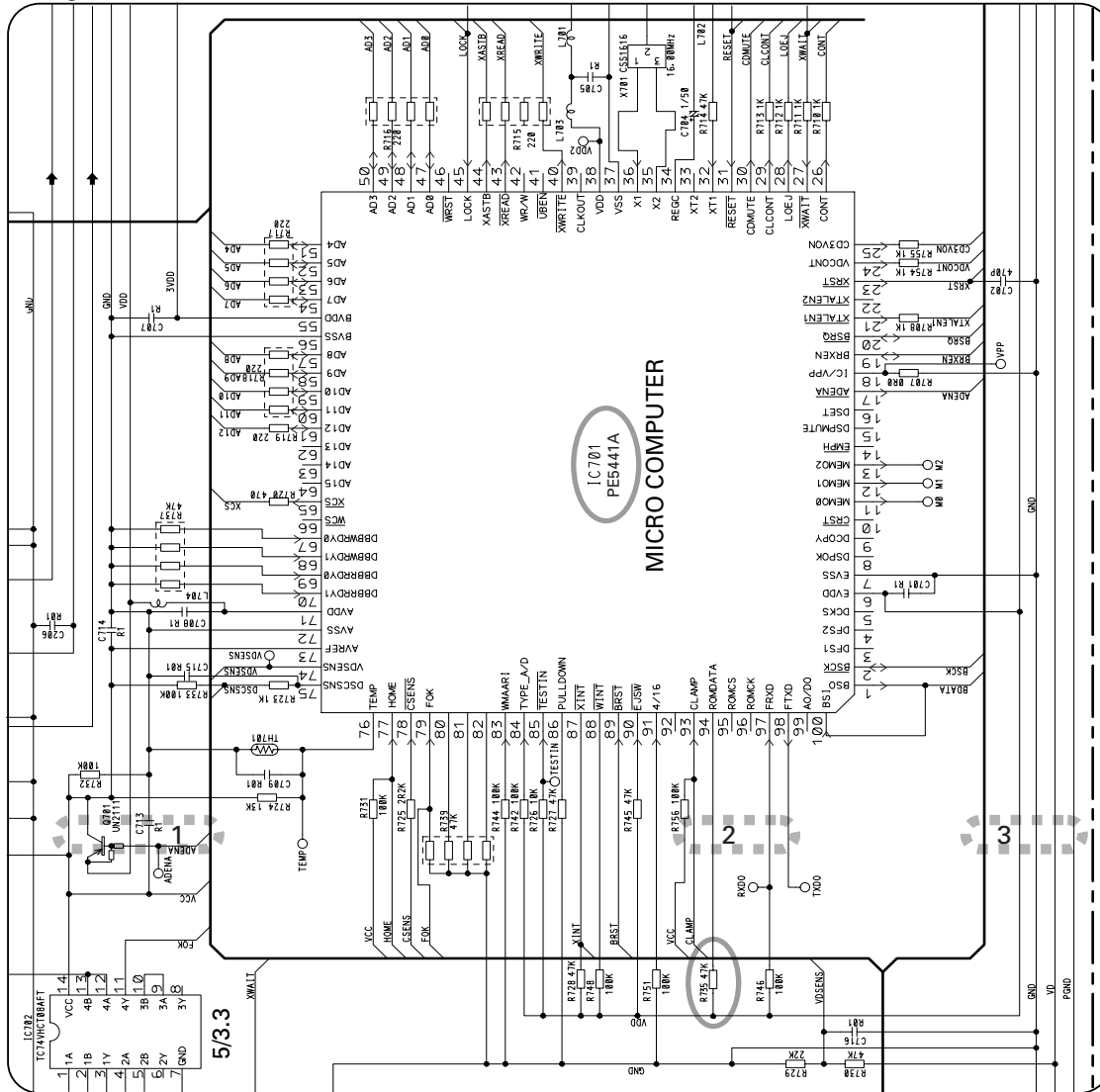
Keyboard Unit

Circuit Symbol & No.	Part Name	DEH-M8037ZT/UC	DEH-M8047ZT/UC
S901-S906	Switch	CSG1154	CSG1169
S907,S908	Switch	CSG1154	CSG1171
S909-S916	Switch	CSG1154	CSG1169
S917,S918	Switch	CSG1154	CSG1171
S919-S924	Switch	CSG1154	CSG1169

CD Core Unit (S10MP3)

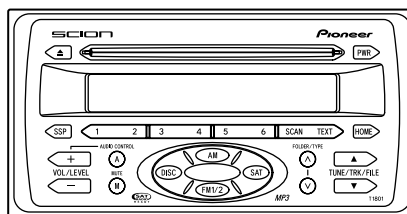
Circuit Symbol & No.	Part Name	DEH-M8037ZT/UC	DEH-M8047ZT/UC
IC701	IC	PE5370B	PE5441A
R735		Not used	RS1/16SS473J

Page 23 6-A



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ORDER NO.
CRT3062

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DEH-M8037ZT_{UC}

VEHICLE	DESTINATION	PRODUCED AFTER	TOYOTA PART No.	ID No.	PIONEER MODEL No.
xA, xB	U.S.A.	April 2003	86120-0W080	T1801	DEH-M8037ZT/UC

● This service manual should be used together with the following manual(s):

Model No.	Order No.	Mech. Module	Remarks
CX-3057	CRT3026	S10MP3	CD Mech. Module:Circuit Description, Mech.Description, Disassembly



For details, refer to "Important symbols for good services".

PIONEER CORPORATION 4-1, Meguro 1-Chome, Meguro-ku, Tokyo 153-8654, Japan
PIONEER ELECTRONICS (USA) INC. P.O.Box 1760, Long Beach, CA 90801-1760 U.S.A.
PIONEER EUROPE NV Haven 1087 Keetberglaan 1, 9120 Melsele, Belgium
PIONEER ELECTRONICS ASIACENTRE PTE.LTD. 253 Alexandra Road, #04-01, Singapore 159936

[Important symbols for good services]

In this manual, the symbols shown-below indicate that adjustments, settings or cleaning should be made securely. When you find the procedures bearing any of the symbols, be sure to fulfill them:

1. Product safety



You should conform to the regulations governing the product (safety, radio and noise, and other regulations), and should keep the safety during servicing by following the safety instructions described in this manual.

2. Adjustments



To keep the original performances of the product, optimum adjustments or specification confirmation is indispensable. In accordance with the procedures or instructions described in this manual, adjustments should be performed.

3. Cleaning



For optical pickups, tape-deck heads, lenses and mirrors used in projection monitors, and other parts requiring cleaning, proper cleaning should be performed to restore their performances.

4. Shipping mode and shipping screws



To protect the product from damages or failures that may be caused during transit, the shipping mode should be set or the shipping screws should be installed before shipping out in accordance with this manual, if necessary.

5. Lubricants, glues, and replacement parts



Appropriately applying grease or glue can maintain the product performances. But improper lubrication or applying glue may lead to failures or troubles in the product. By following the instructions in this manual, be sure to apply the prescribed grease or glue to proper portions by the appropriate amount. For replacement parts or tools, the prescribed ones should be used.

● CD Section Precaution



1. Before disassembling the unit, be sure to turn off the power. Unplugging and plugging the connectors during power-on mode may damage the ICs inside the unit.
2. To protect the pickup unit from electrostatic discharge during servicing, take an appropriate treatment (shorting-solder) by referring to "the DISASSEMBLY" on page 56.
3. After replacing the pickup unit, be sure to check the grating. (See p.49.)

SAFETY INFORMATION

This service manual is intended for qualified service technicians; it is not meant for the casual do-it-yourselfer.

Qualified technicians have the necessary test equipment and tools, and have been trained to properly and safely repair complex products such as those covered by this manual.

Improperly performed repairs can adversely affect the safety and reliability of the product and may void the warranty. If you are not qualified to perform the repair of this product properly and safely; you should not risk trying to do so and refer the repair to a qualified service technician.

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A

1. SPECIFICATIONS

General

Power source 13.2 V DC
(10.5 – 16.0 V allowable)
Grounding system Negative type
Max. current consumption 15 A
Backup current 0.3 mA or less
Dimensions (W × H × D)
. 200 × 100 × 165 mm
Weight 1.8 kg

Audio

Tone controls
(Bass) Frequency : 55 Hz
Level : +11 dB -13 dB
(Treble) Frequency : 14080 Hz
Level : +8 dB -10 dB
Maximum power output 40 W × 4
Load impedance 4 Ω

CD player

System Compact disc audio system
Usable discs Compact disc
Signal format
Sampling frequency 44.1 kHz
Number of quantization bits
. 16; linear
Number of channels 2 (stereo)
MP3 decoding format
. MPEG1 & 2 Audio Layer 3

AM tuner

Frequency range 530 – 1710 kHz

FM tuner

Frequency range 87.75 – 107.9 MHz

B

C

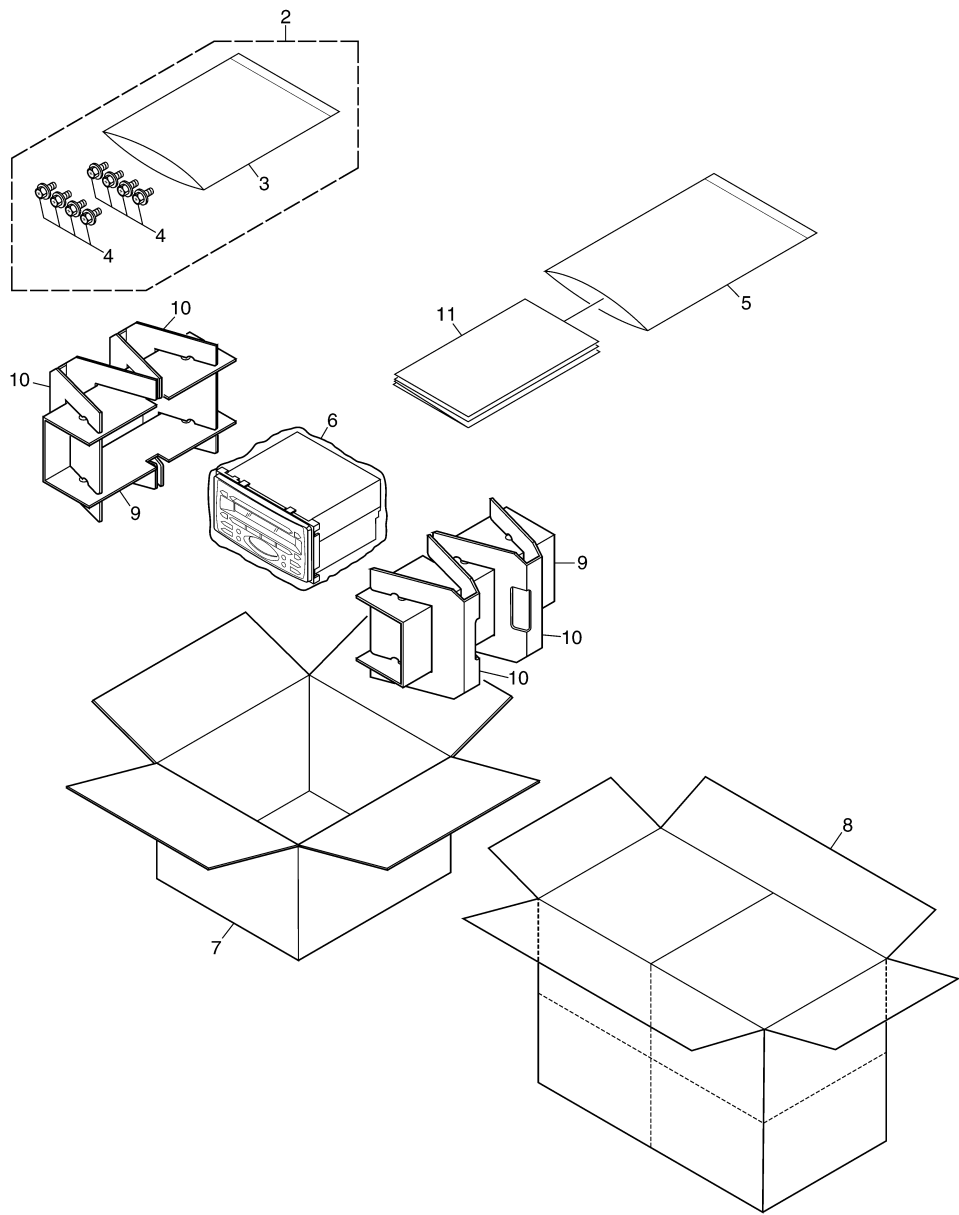
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2. EXPLODED VIEWS AND PARTS LIST

2.1 PACKING



- NOTE:**
- Parts marked by “*” are generally unavailable because they are not in our Master Spare Parts List.
 - Screws adjacent to ▽ mark on the product are used for disassembly.
 - For the applying amount of lubricants or glue, follow the instructions in this manual.
(In the case of no amount instructions, apply as you think it appropriate.)

● **PACKING SECTION PARTS LIST**

Mark No.	Description	Part No.	Mark No.	Description	Part No.
1		*	6 Polyethylene Bag	CEG1322
2	Screw Assy	CEA3954	7	Carton	CHA3274
* 3	Polyethylene Bag	CEG-127	8	Contain Box	CHL5058
4	Screw	HMF50P080FTC	9	Protector	CHP2140
* 5	Polyethylene Bag	CEG1116	10	Protector	CHP2141
			11	Owner's Manual (English)	CRB1826

2.2 EXTERIOR

A

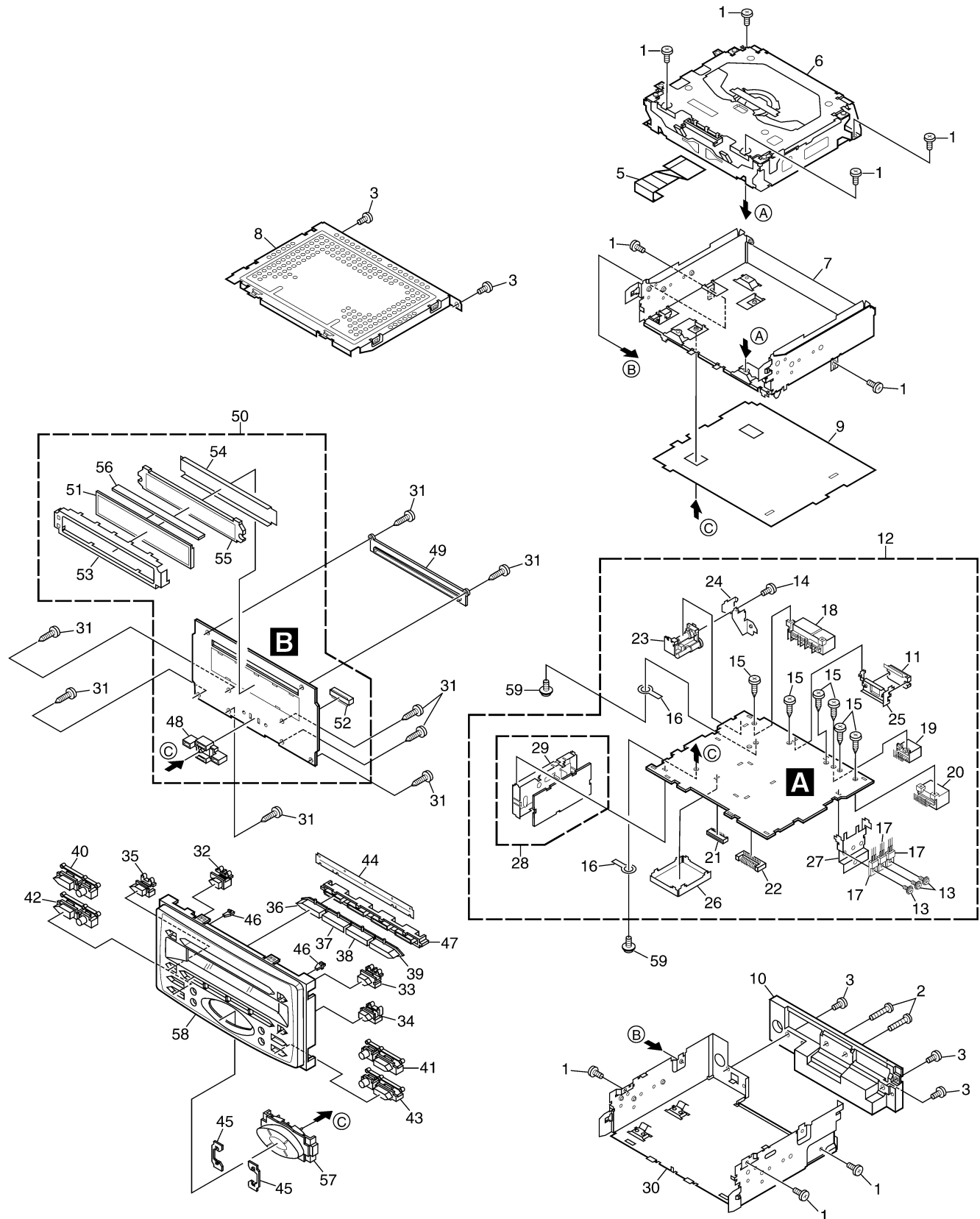
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● EXTERIOR SECTION PARTS LIST

Mark No.	Description	Part No.	Mark No.	Description	Part No.	
1	Screw	BSZ26P050FTC	51	LCD	CAW1809	A
2	Screw	BSZ26P140FTC	52	Connector(CN901)	CKS4671	
3	Screw	BSZ30P080FTC	53	Holder	CND1423	
4		54	Sheet	CNM8437	
5	Connector	CDE7172	55	Lighting Conductor	CNV7540	
6	CD Mechanism Module(S10MP3)	CXK5680	56	Connector	CNV7557	
7	Chassis	CNA2618	57	Button Unit(SOURCE)	CXC1081	
8	Case	CNB2842	58	Grille Unit	CXC1323	
9	Insulator	CNM8107	59	Screw	ISS26P055FTC	
10	Heat Sink	CNR1683				B
11	IC(IC801)	TDA7386				
12	Main Unit	CWM8737				
13	Screw	ASZ26P080FTC				
14	Screw	BMZ30P040FTC				
15	Screw(M3x6)	CBA1393				
16	Terminal(CN474,476)	CKF1064				
17	Transistor(Q431,441,850)	2SB1185				
18	Connector(CN471)	CKM1222				
19	Connector(CN473)	CKM1350				
20	Connector(CN472)	CKM1351				C
21	Connector(CN601)	CKS3837				
22	Connector(CN479)	CKS4670				
23	Connector(CN501)	CKX1064				
24	Holder	CNC9591				
25	Holder	CNC9592				
*	26 Shield	CNC9595				
	27 Holder	CND1460				
	28 FM/AM Tuner Unit	CWE1630				
	29 Holder	CNC8855				
	30 Chassis Unit	CXC1012				D
	31 Screw	BPZ20P100FTC				
	32 Button(EJECT)	CAC7884				
	33 Button(PWR)	CAC7885				
	34 Button(HOME)	CAC7887				
	35 Button(SSP)	CAC7889				
	36 Button(1,2)	CAC7890				
	37 Button(3,4)	CAC7891				
	38 Button(5,6)	CAC7892				
	39 Button(SCAN,TEXT)	CAC7893				
	40 Button(A)	CAC7894				E
	41 Button(UP)	CAC7895				
	42 Button(M)	CAC8074				
	43 Button(DOWN)	CAC8075				
	44 Cover	CNM7433				
	45 Cushion	CNM8306				
	46 Lighting Conductor	CNV7542				
	47 Holder	CNV7543				
	48 Holder	CNV7544				
	49 Guide	CNV7646				F
	50 Keyboard Unit	CWM8738				

2.3 CD MECHANISM MODULE

A

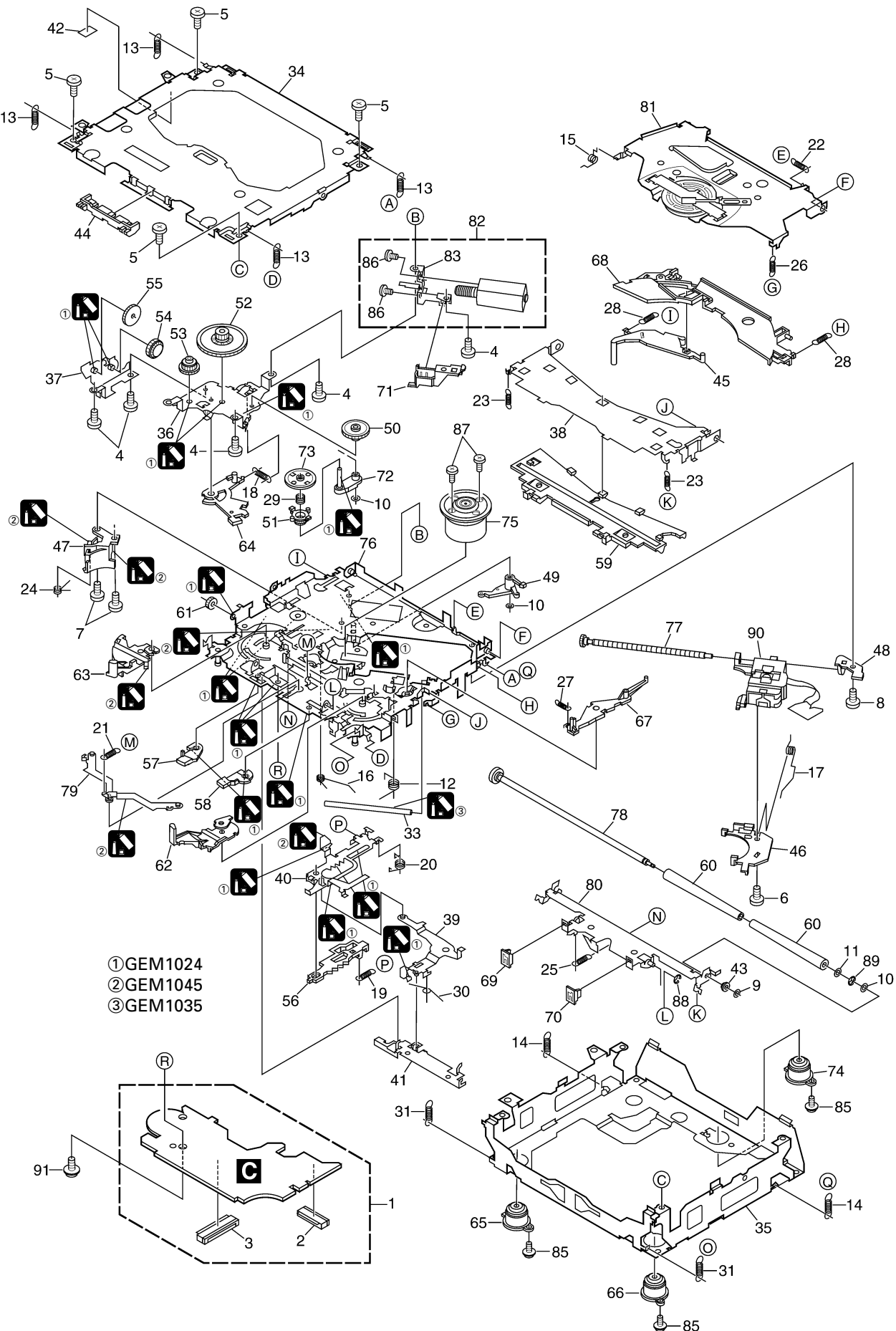
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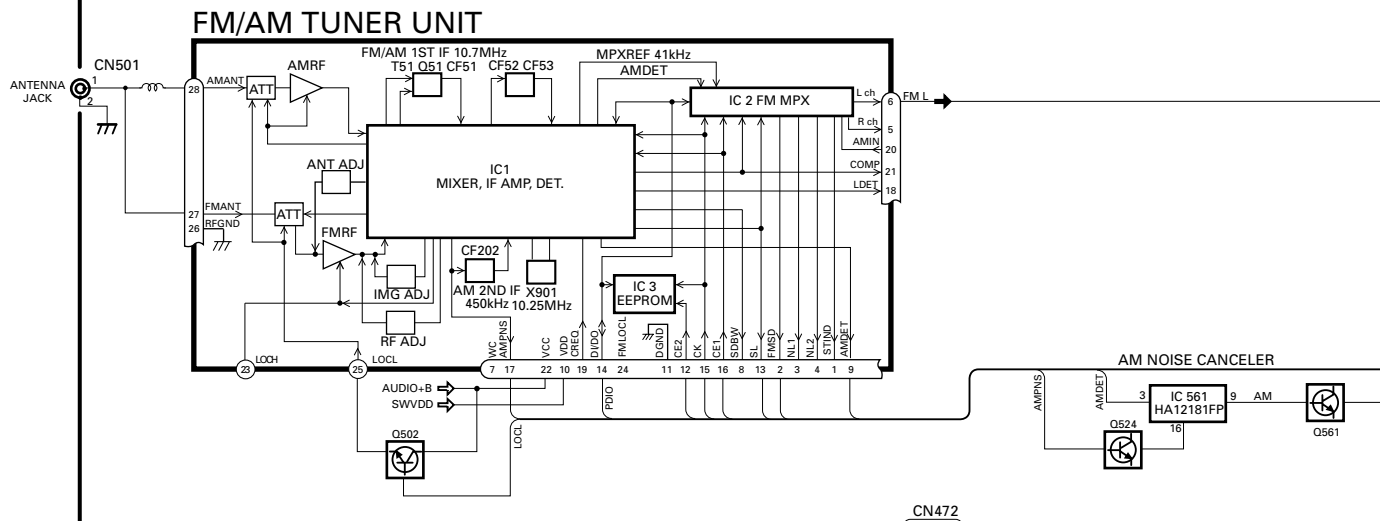
● CD MECHANISM MODULE SECTION PARTS LIST

Mark No.	Description	Part No.	Mark No.	Description	Part No.	
1	CD Core Unit(S10MP3)	CWX2810	46	Rack	CNV7199	
2	Connector(CN101)	CKS4182	47	Holder	CNV7201	
3	Connector(CN901)	CKS4017	48	Holder	CNV7202	
4	Screw	BMZ20P035FTC	49	Arm	CNV7203	
5	Screw	BSZ20P040FTC	50	Gear	CNV7207	
6	Screw(M2x4)	CBA1362	51	Gear	CNV7208	
7	Screw(M2x3)	CBA1511	52	Gear	CNV7209	
8	Screw(M2x3)	CBA1527	53	Gear	CNV7210	
9	Washer	CBF1037	54	Gear	CNV7211	
10	Washer	CBF1038	55	Gear	CNV7212	
11	Washer	CBF1060	56	Rack	CNV7214	
12	Spring	CBH2390	57	Arm	CNV7215	
13	Spring	CBH2606	58	Arm	CNV7216	
14	Spring	CBH2607	59	Guide	CNV7217	
15	Spring	CBH2608	60	Roller	CNV7218	
16	Spring	CBH2609	61	Gear	CNV7219	
17	Spring	CBH2610	62	Arm	CNV7221	
18	Spring	CBH2611	63	Arm	CNV7220	
19	Spring	CBH2612	64	Arm	CNV7222	
20	Spring	CBH2613	65	Damper	CNV7634	
21	Spring	CBH2614	66	Damper	CNV7633	
22	Spring	CBH2615	67	Arm	CNV7341	
23	Spring	CBH2616	68	Arm	CNV7342	
24	Spring	CBH2617	69	Guide	CNV7360	
25	Spring	CBH2620	70	Guide	CNV7361	
26	Spring	CBH2621	71	Holder	CNV7437	
27	Spring	CBH2641	72	Arm	CNV7444	
28	Spring	CBH2642	73	Gear	CNV7595	
29	Spring	CBH2643	74	Damper	CNV7632	
30	Spring	CBH2659	75	Motor Unit(M1)	CXB6007	
31	Spring	CBH2688	76	Chassis Unit	CXB8728	
32		77	Screw Unit	CXB8729	
33	Shaft	CLA3845	78	Gear Unit	CXB8731	
34	Frame	CNC9962	79	Arm Unit	CXB8732	
35	Frame	CNC9963	80	Arm Unit	CXB8735	
36	Bracket	CNC9966	81	Arm Unit	CXB8852	
37	Bracket	CNC9967	82	Motor Unit(M2)	CXB8933	
38	Arm	CNC9968	83	Bracket	CNC9985	
39	Arm	CNC9973	84		
40	Lever	CNC9983	85	Screw(M2x5)	EBA1028	
41	Lever	CNC9984	86	Screw	JFZ20P020FTC	
42	Sheet	CNM8134	87	Screw	JGZ17P022FTC	
43	Collar	CNV6906	88	Washer	YE15FTC	
44	Guide	CNV6925	89	Washer	YE20FTC	
45	Arm	CNV7198	90	Pickup Unit(Service)(P10)	CXX1664	
			91	Screw	IMS26P030FTC	

3. BLOCK DIAGRAM AND SCHEMATIC DIAGRAM

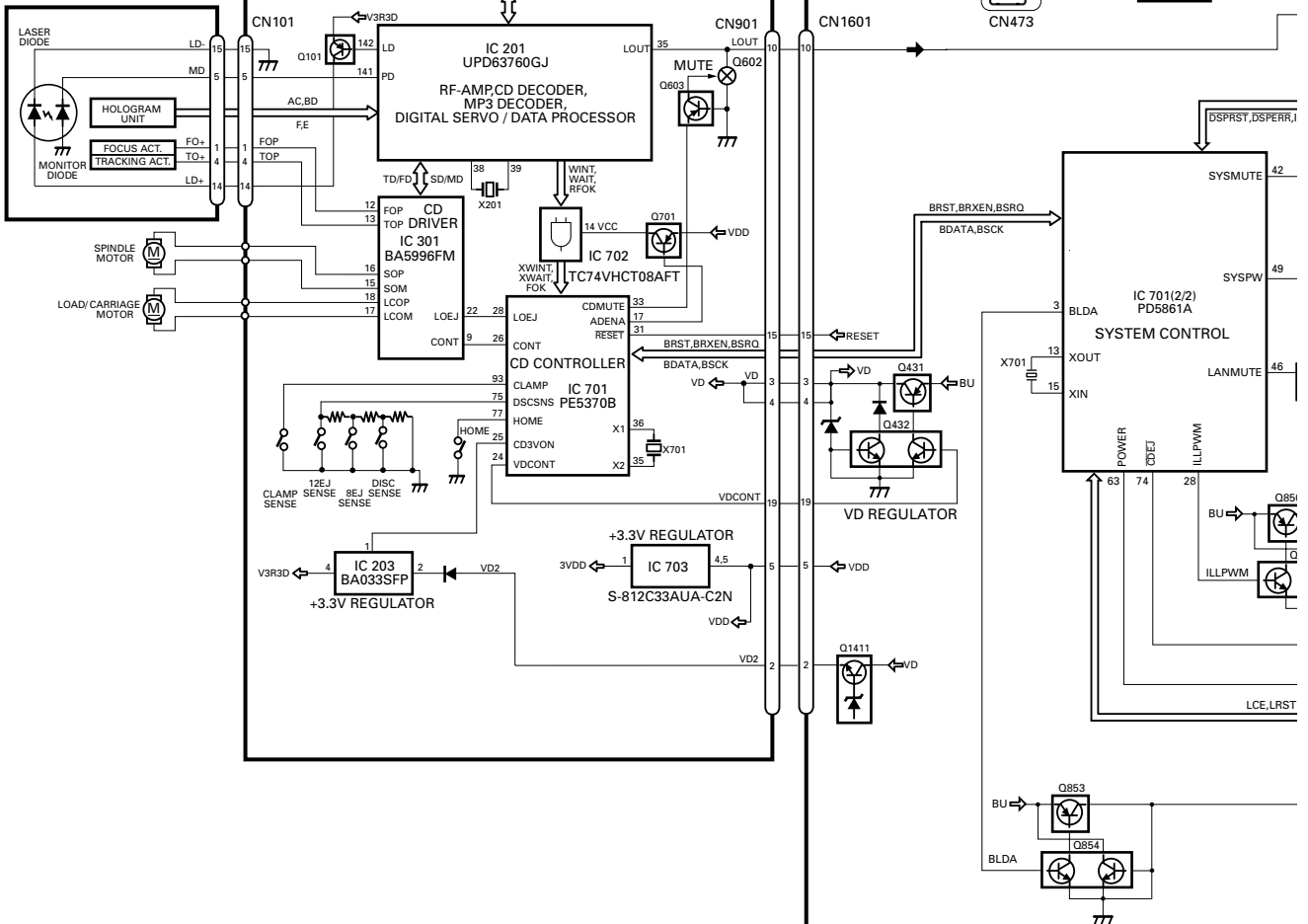
3.1 BLOCK DIAGRAM

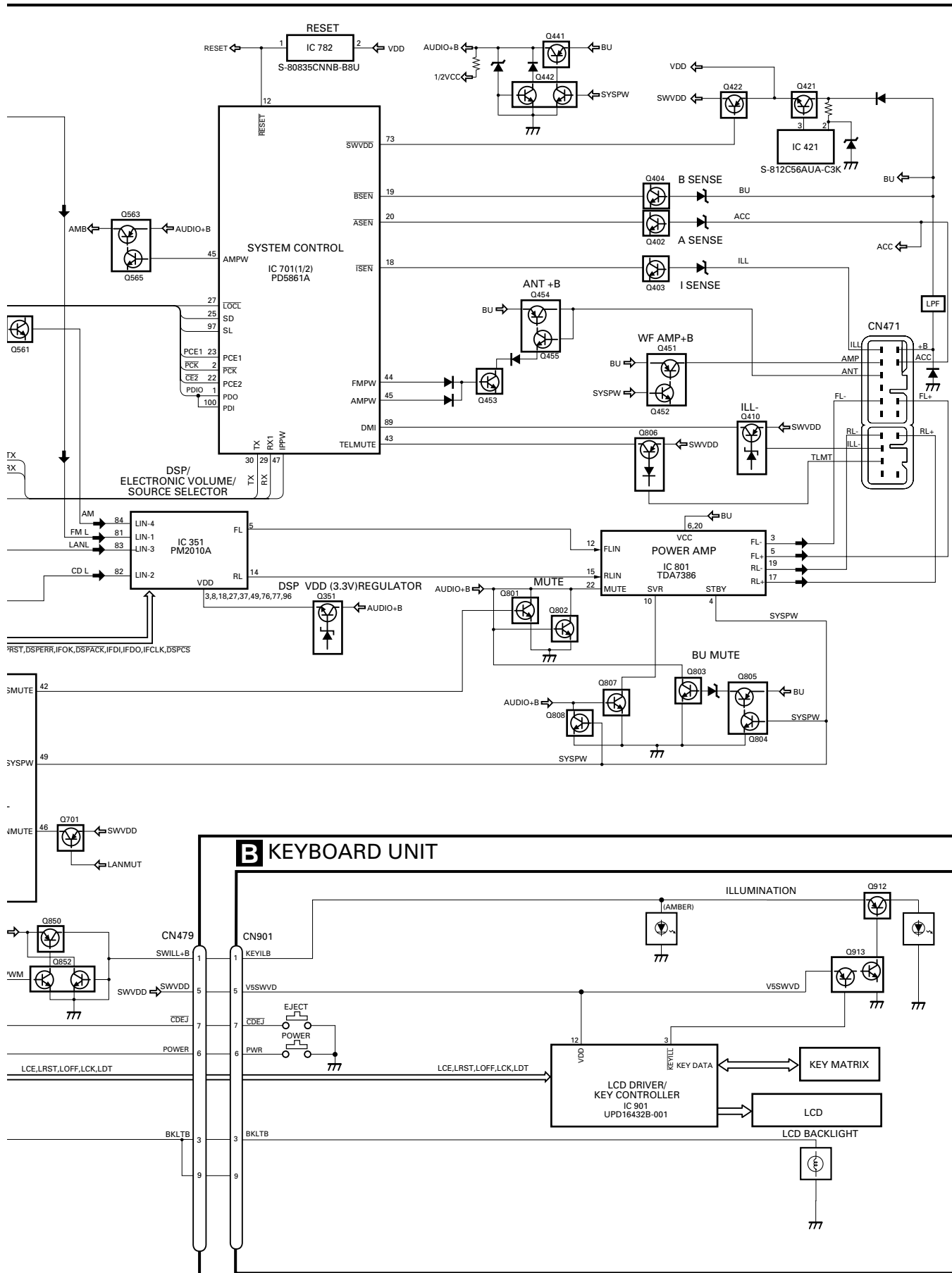
A MAIN UNIT



C CD CORE UNIT(S10MP3)

PICKUP UNIT (SERVICE)(P10)

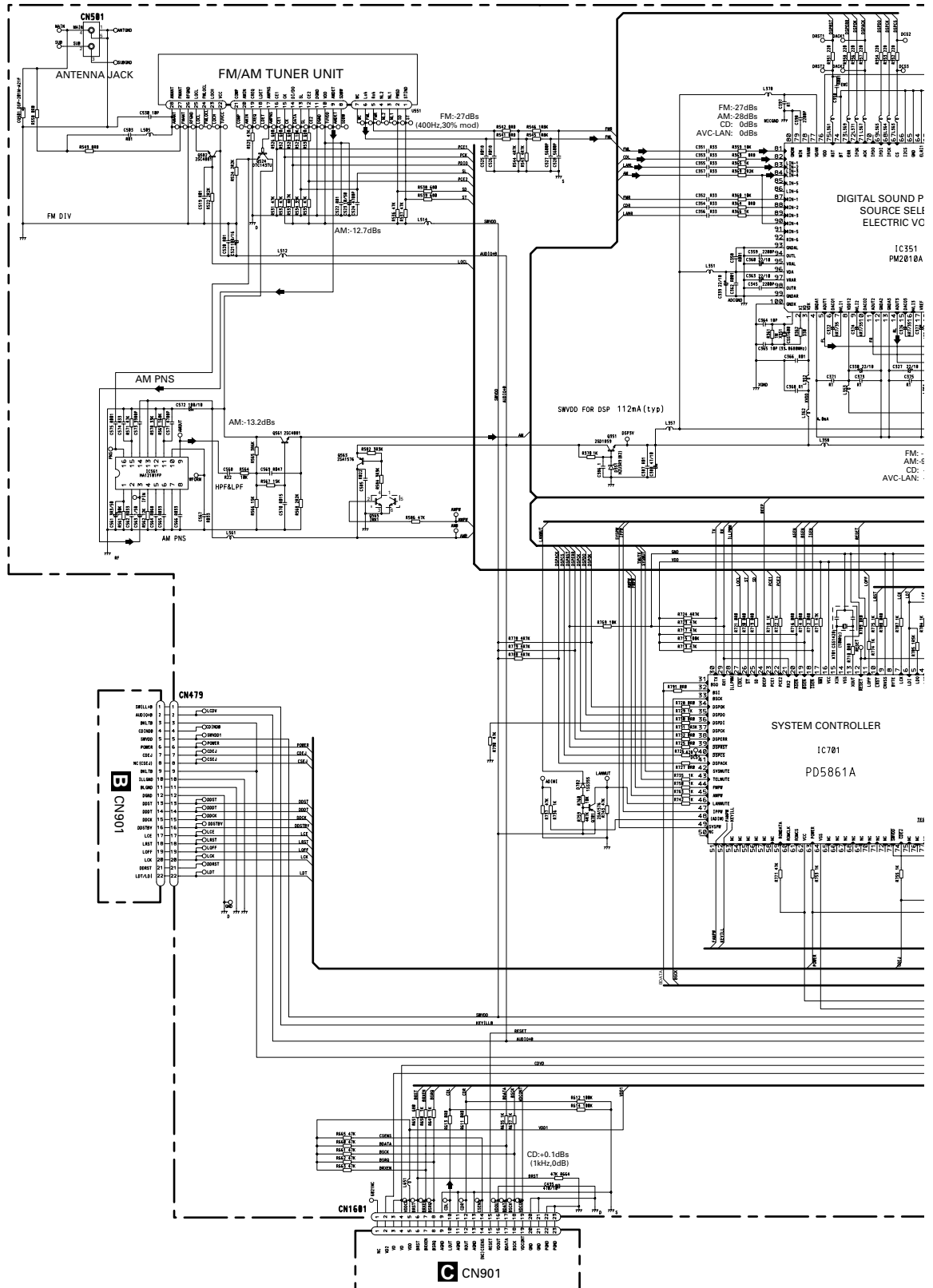
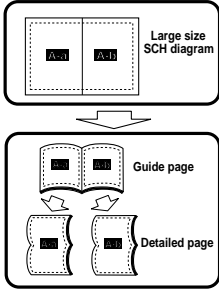




3.2 OVERALL CONNECTION DIAGRAM(GUIDE PAGE)

Note: When ordering service parts, be sure to refer to "EXPLODED VIEWS AND PARTS LIST" or "ELECTRICAL PARTS LIST".

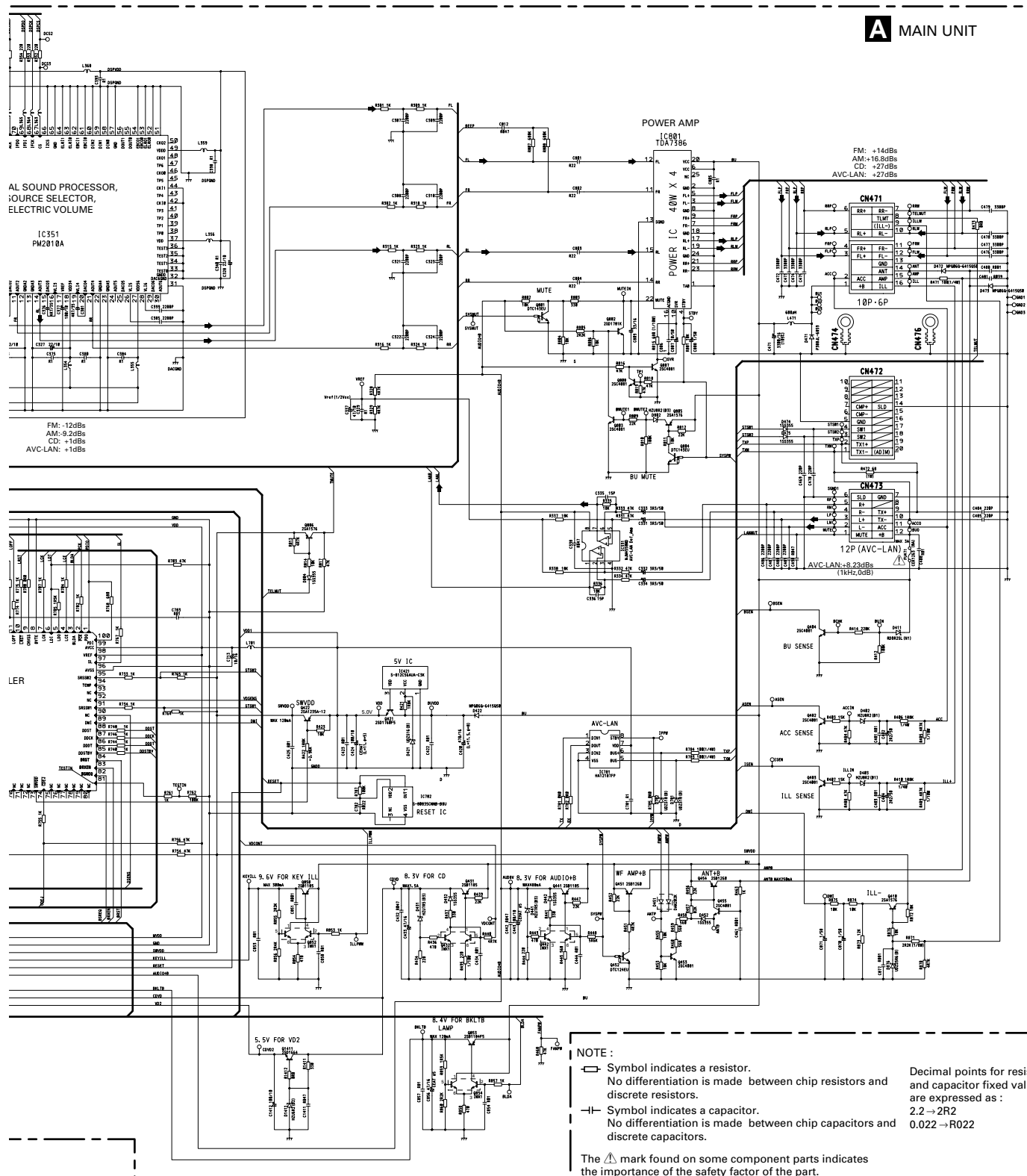
A-a



A

A-b

A



B

C

D

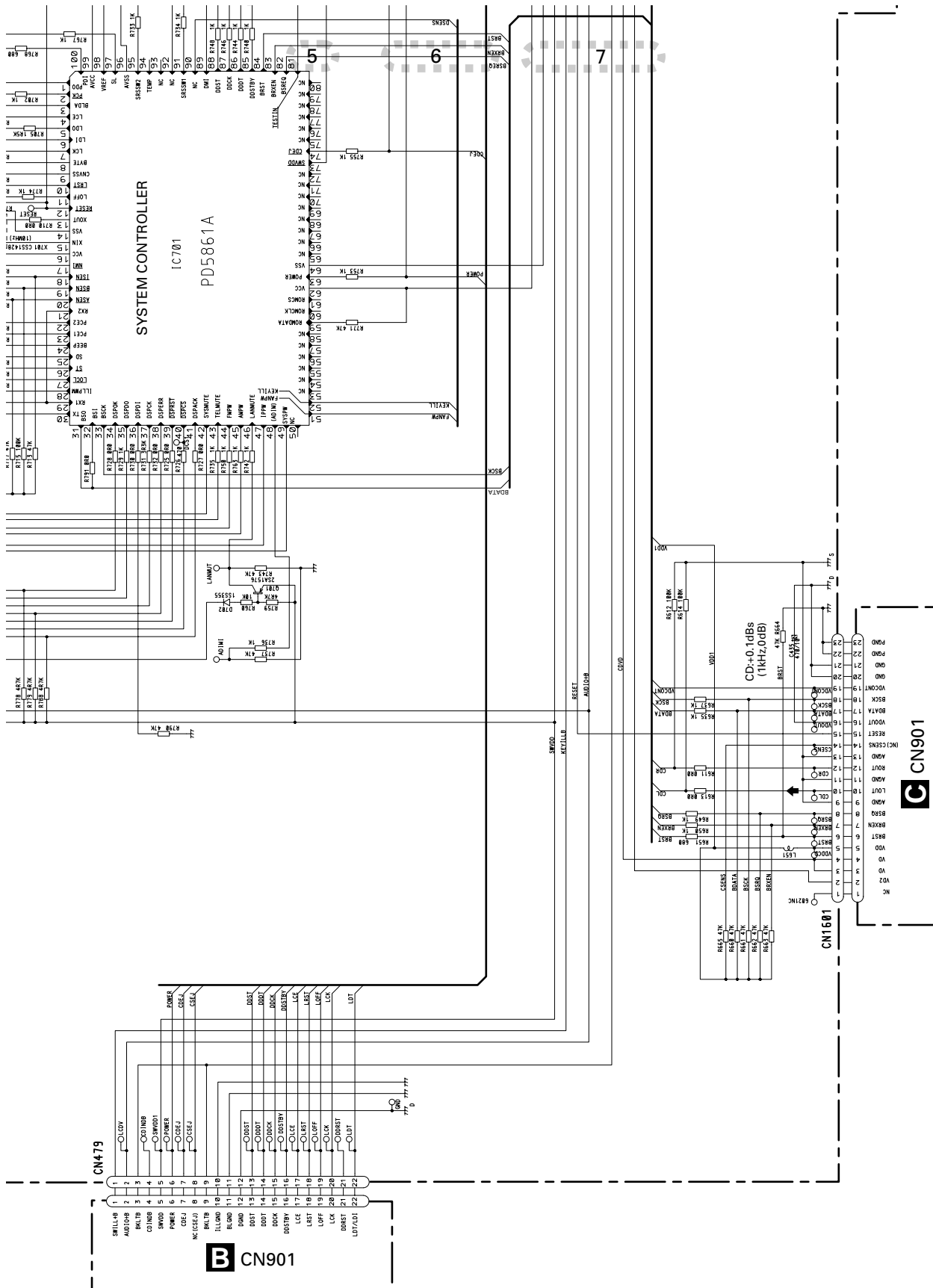
E

F

A-a

DEH-M8037ZT/UC



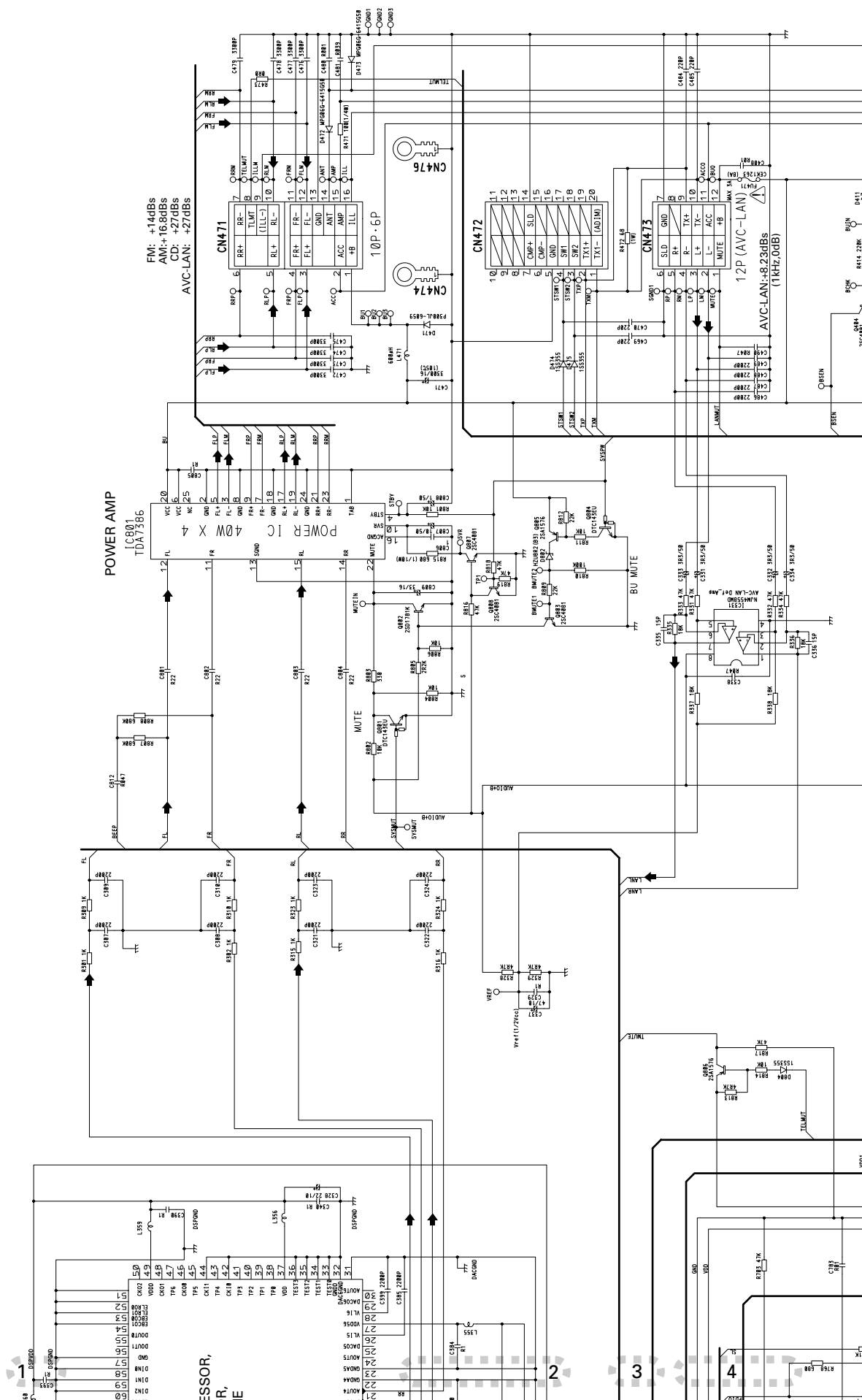


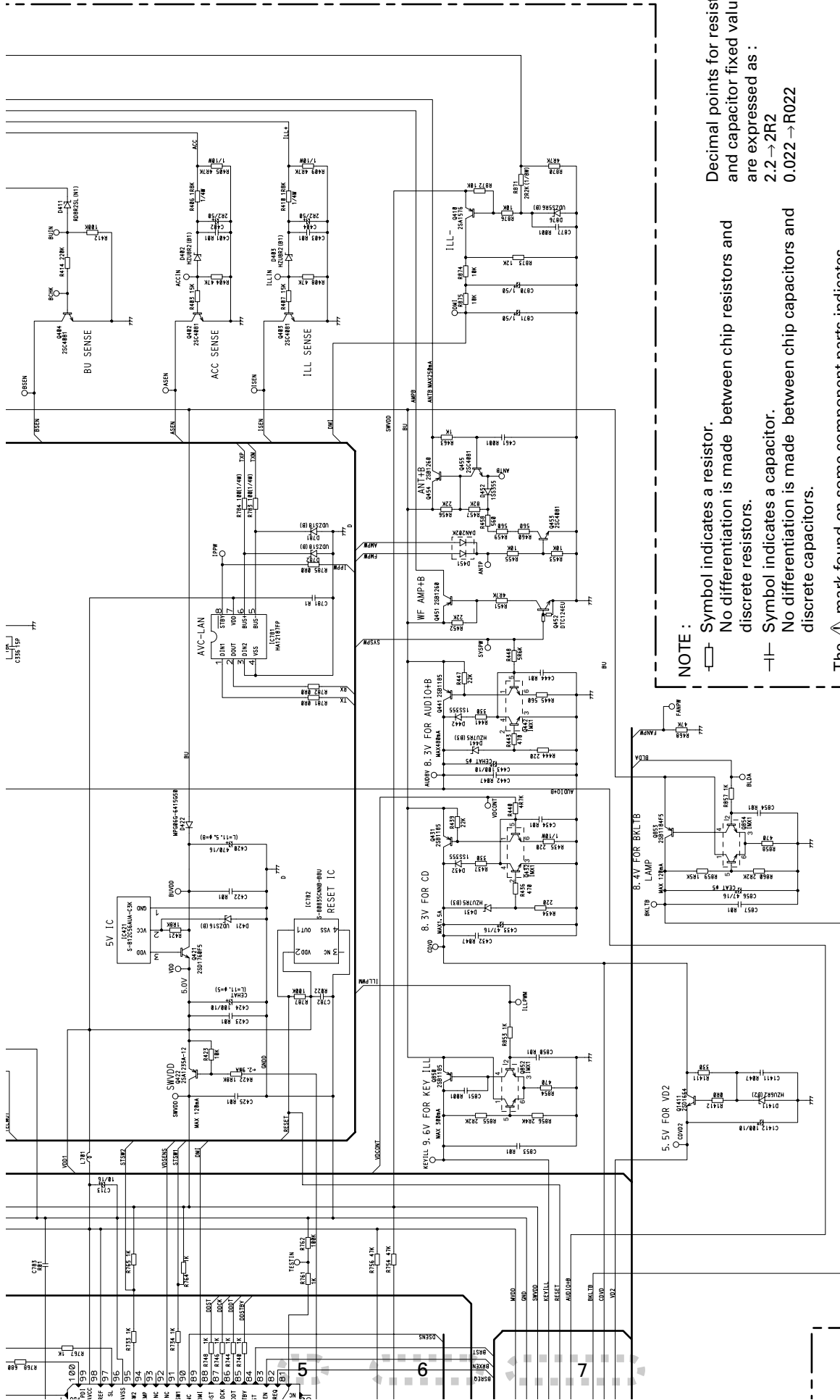
A-b

A-a

A-a

16





NOTE :

Symbol indicates a resistor.

No differentiation is made between chip resistors and discrete resistors.

Symbol indicates a capacitor.

No differentiation is made between chip capacitors and discrete capacitors.

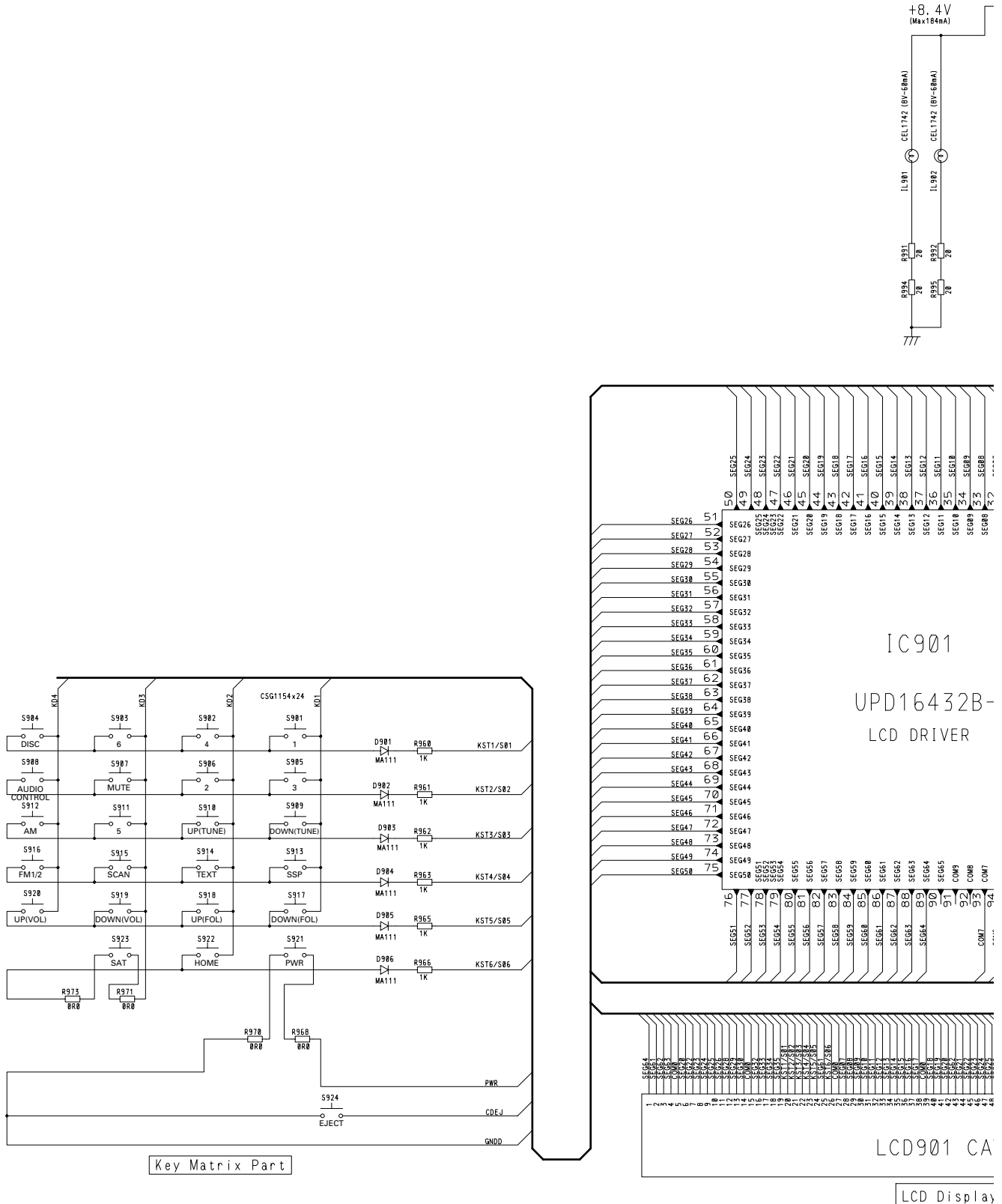
Decimal points for resistors and capacitor fixed value are expressed as :
2.2 → 2R2
0.022 → R022

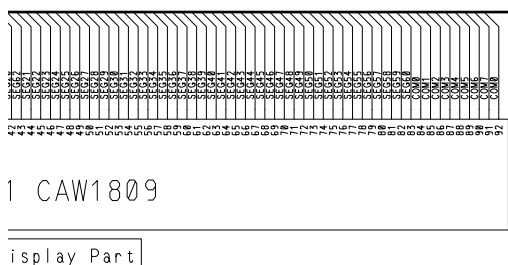
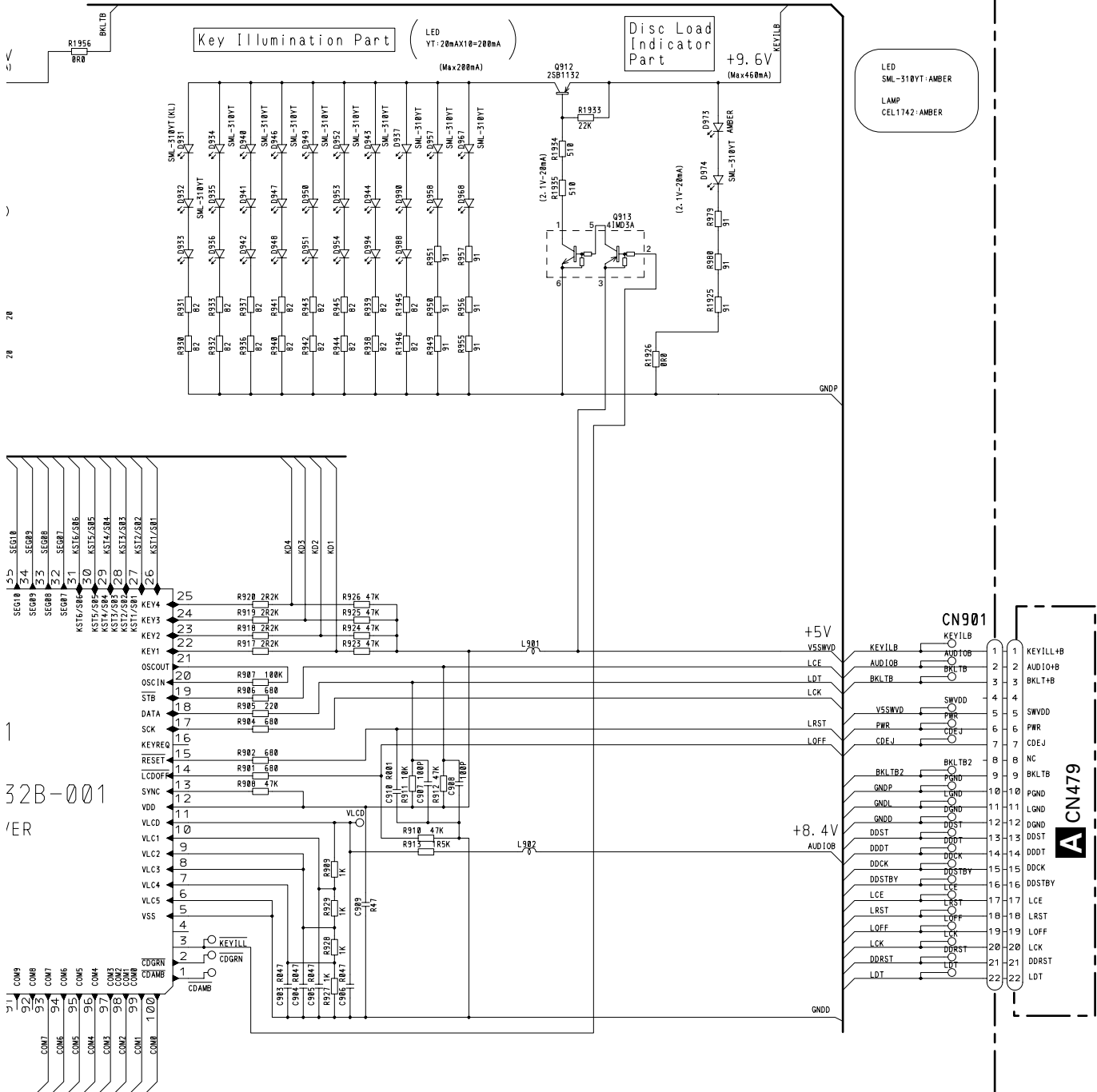
The Δ mark found on some component parts indicates the importance of the safety factor of the part. Therefore, when replacing, be sure to use parts of identical designation.

A-a	A-b
-----	-----

3.3 KEYBOARD UNIT

B KEYBOARD UNIT

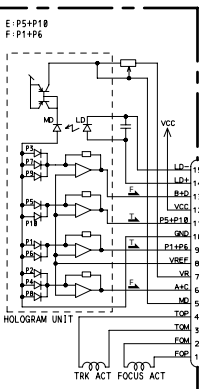




3.4 CD MECHANISM MODULE(GUIDE PAGE)

C-a

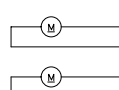
PICKUP UNIT (SERVICE)(P10)



F. ACT: Applying positive voltage to FOP, the lens moves DISC side.
T. ACT: Applying positive voltage to TOP, the lens moves outer circumference.

SWITCHES:
CD CORE UNIT(S10MP3)
S901: HOME SWITCH.....ON-OFF
S902: CLAMP SWITCH.....ON-OFF
S903: DSCSNS SWITCH.....ON-OFF
S904: 12EJ SWITCH.....ON-OFF
S905: 8EJ SWITCH.....ON-OFF
The underlined indicates the original switch position.

SPINDLE MOTOR M1 CXB6007



LOADING/CARRIAGE MOTOR M2 CXB8933



SW 3.3 REGULATOR

	LOAD	EJ	PLAY	OFF
CLCONT	H	H	L	L
LOEJ	L	H	-	-
CONT	L	L	H	L

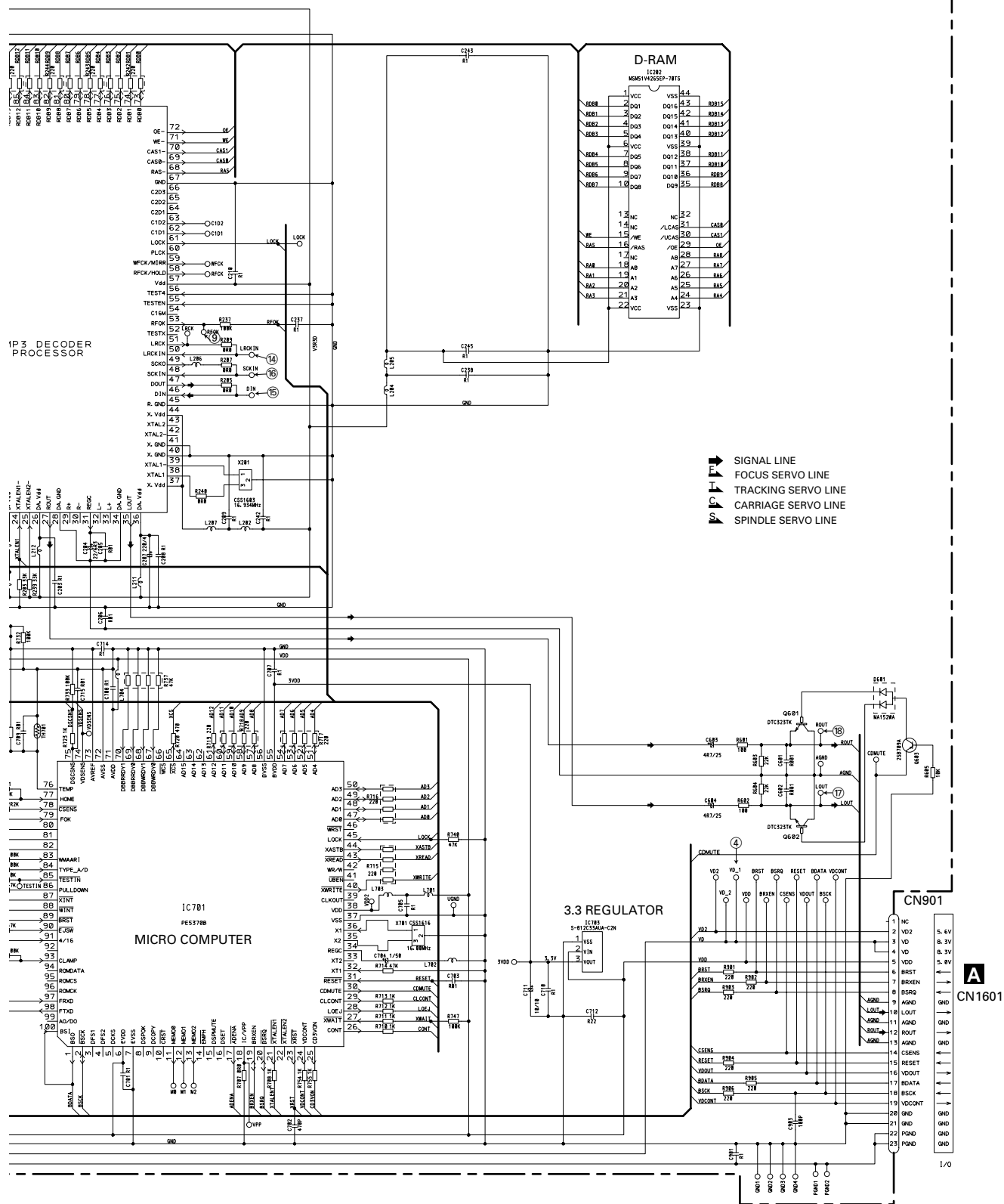
CD DRIVER



NOTE1) GND ... CD LSI, RFAMP, CPU
PGND ... Actuator, Motor Driver
AGND ... Audio
These GND's are not connected to each other on PCB.
PGND is connected to a floating mechanism part by a screw.

C-b

C CD CORE UNIT(S10MP3)



C

C-b

A

B

C

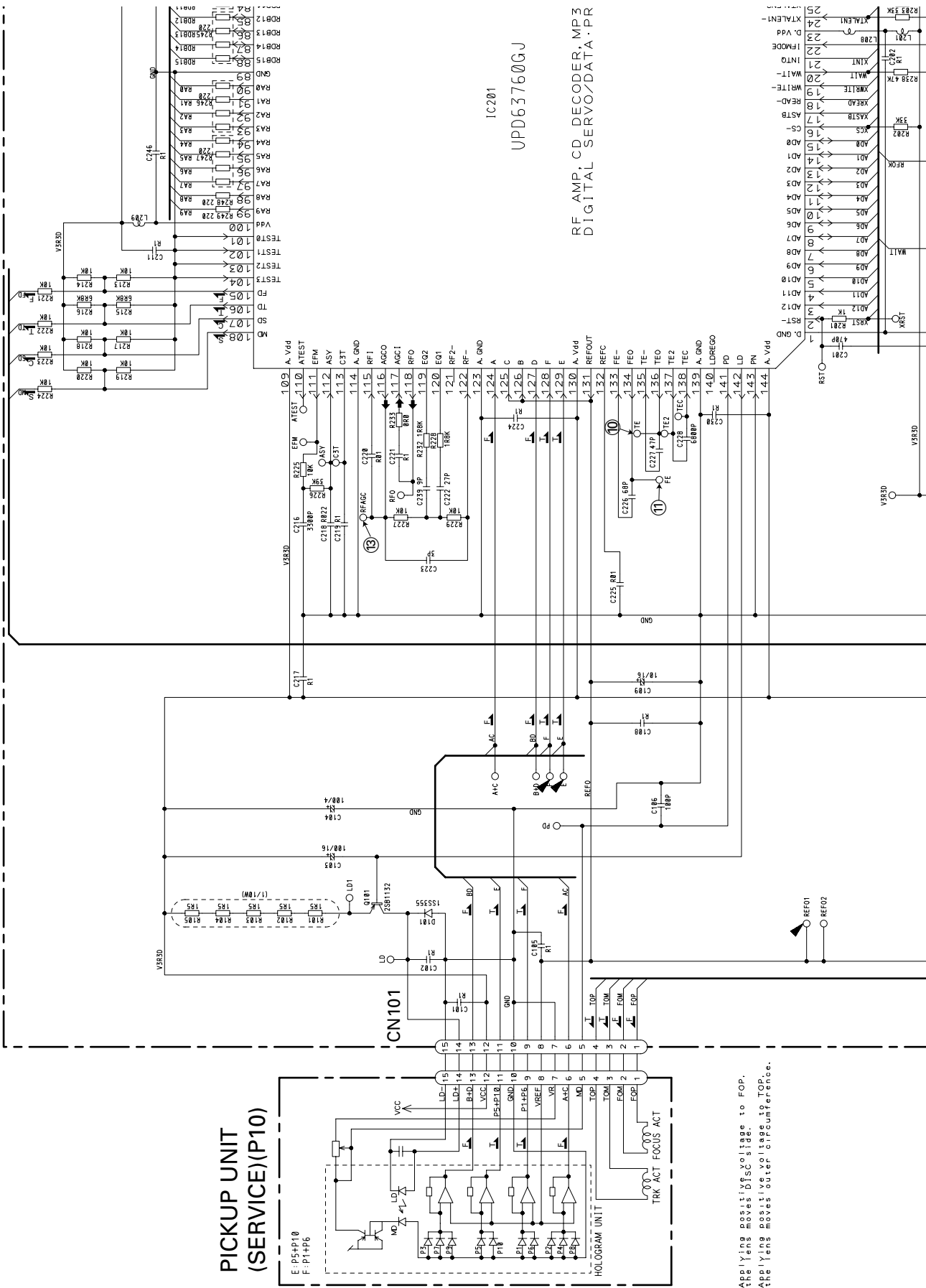
D

E

F

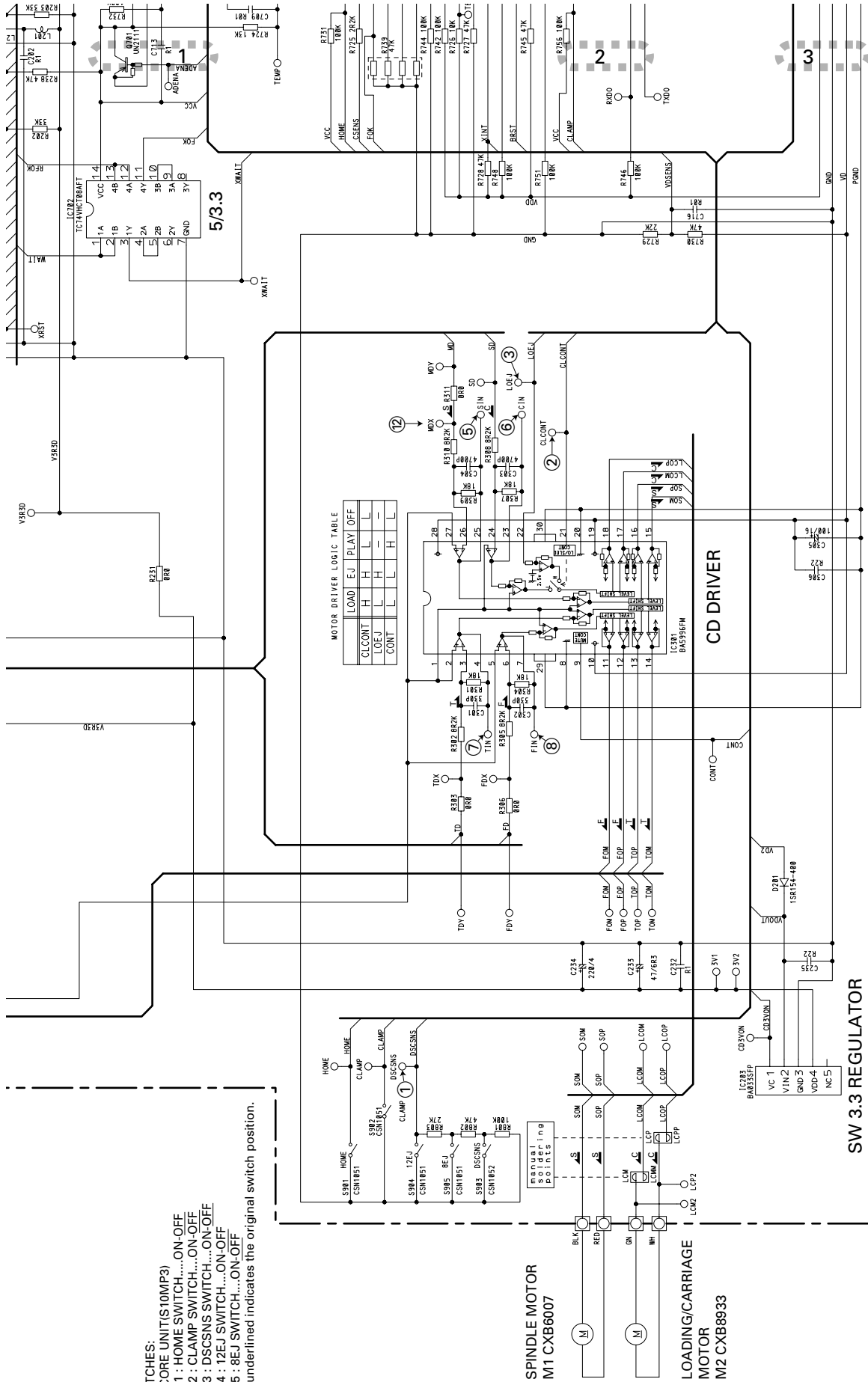
C-a C-b

C-a



F. ACT: Applying positive voltage to FOP.
T. ACT: Applying positive voltage to TOP.
The lens moves out to counterbalance.

SWITCHES:
 CD CORE UNIT(S10MP3)
 S901 : HOME SWITCH.....ON-OFF
 S902 : CLAMP SWITCH.....ON-OFF
 S903 : DSCSNS SWITCH.....ON-OFF
 S904 : 12EJ SWITCH.....ON-OFF
 S905 : 8EJ SWITCH.....ON-OFF
 The underlined indicates the original switch position.



Ⓢ Monitor land (ø1.2mm)
 # Monitor land (ø0.8mm)
 Land for manual soldering

NOTE1) GND ...CD LS1, RFAMP, CPU
 PGND ...Actuator, Motor Driver
 AGND ...Audio
 These GND's are not connected to each other on PCB.
 PGND is connected to a floating mechanism part by a screw.

C-b

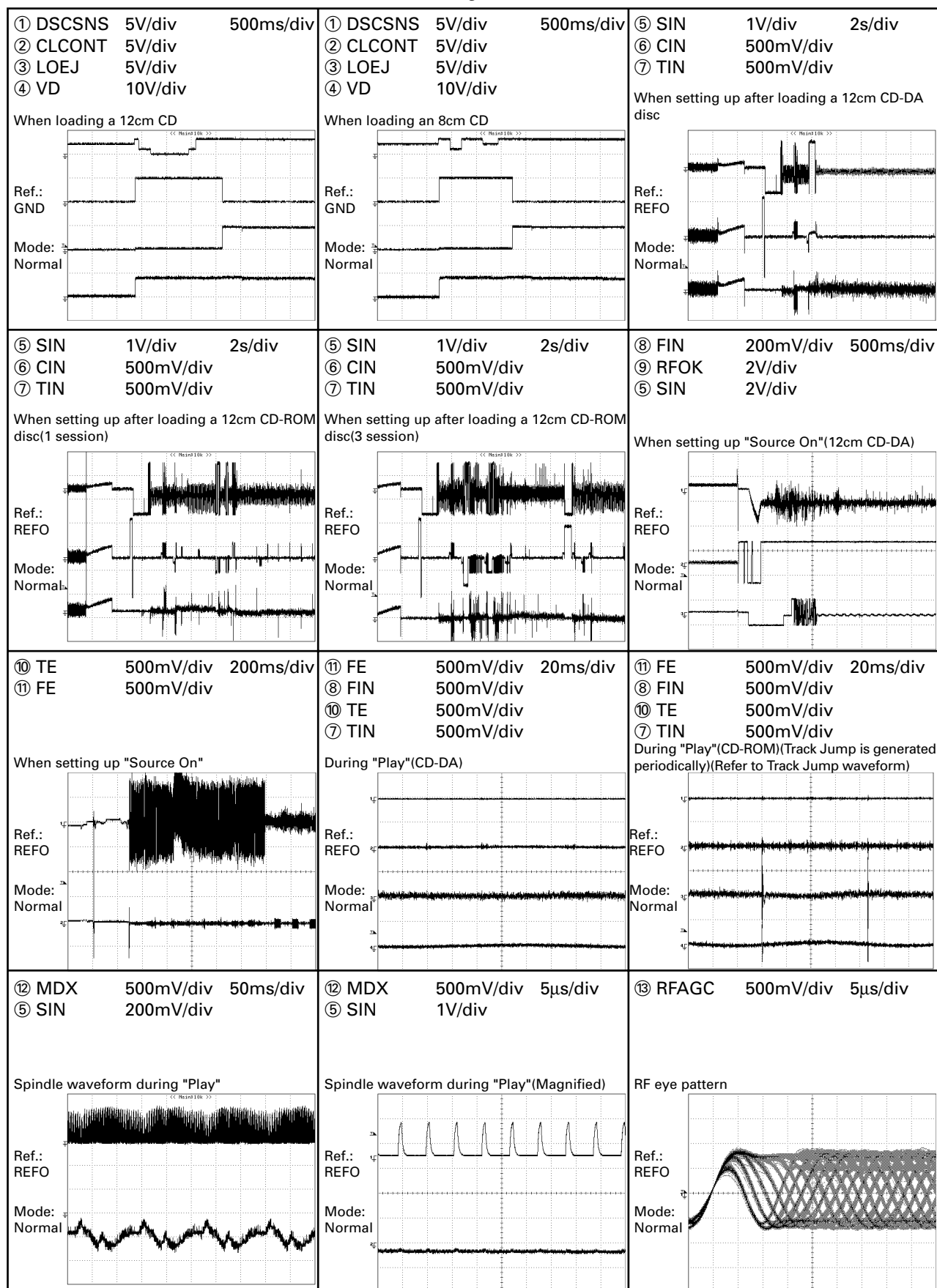
C-a C-b

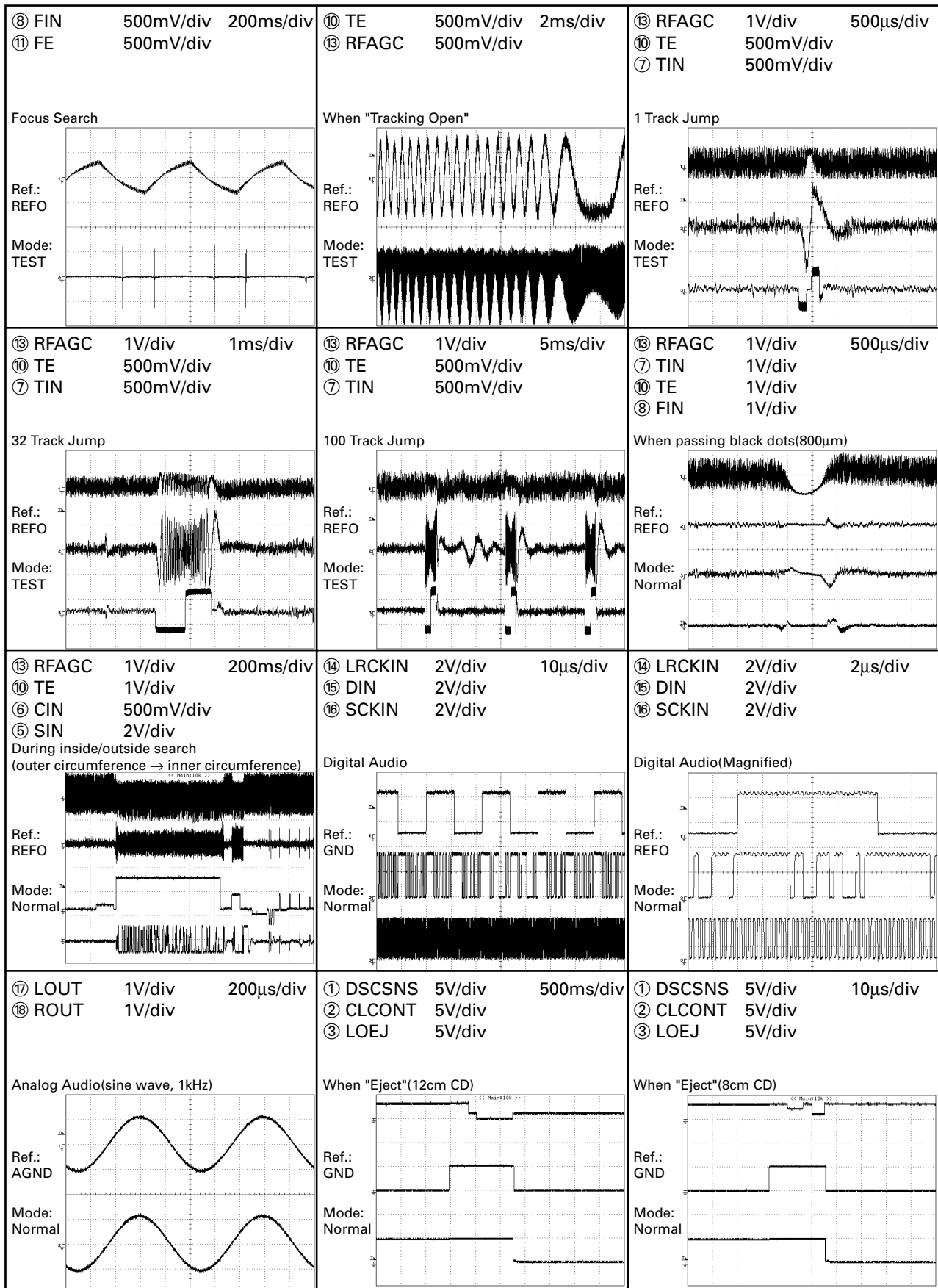
C-a



Waveforms

Note : 1. The encircled numbers denote measuring points in the circuit diagram.
2. Reference voltage REFO1(1.65V)

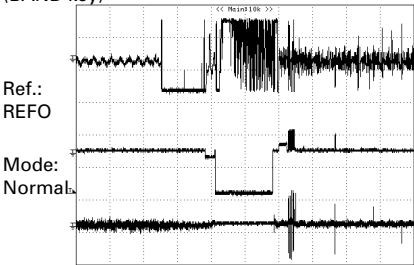




A

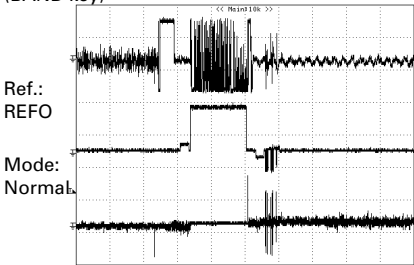
⑤ SIN 1V/div 500ms/div
⑥ CIN 500mV/div
⑦ TIN 500mV/div

When switching to CD-ROM from CD-DA
(BAND key)



⑤ SIN 1V/div 500ms/div
⑥ CIN 500mV/div
⑦ TIN 500mV/div

When switching to CD-DA from CD-ROM
(BAND key)



B

C

D

E

F



5



6



7



8



A



B



C



D



E



F



5



6



7



8



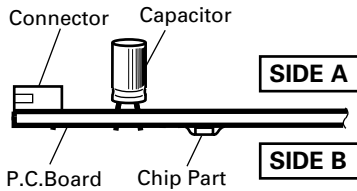
4. PCB CONNECTION DIAGRAM

4.1 MAIN UNIT

NOTE FOR PCB DIAGRAMS

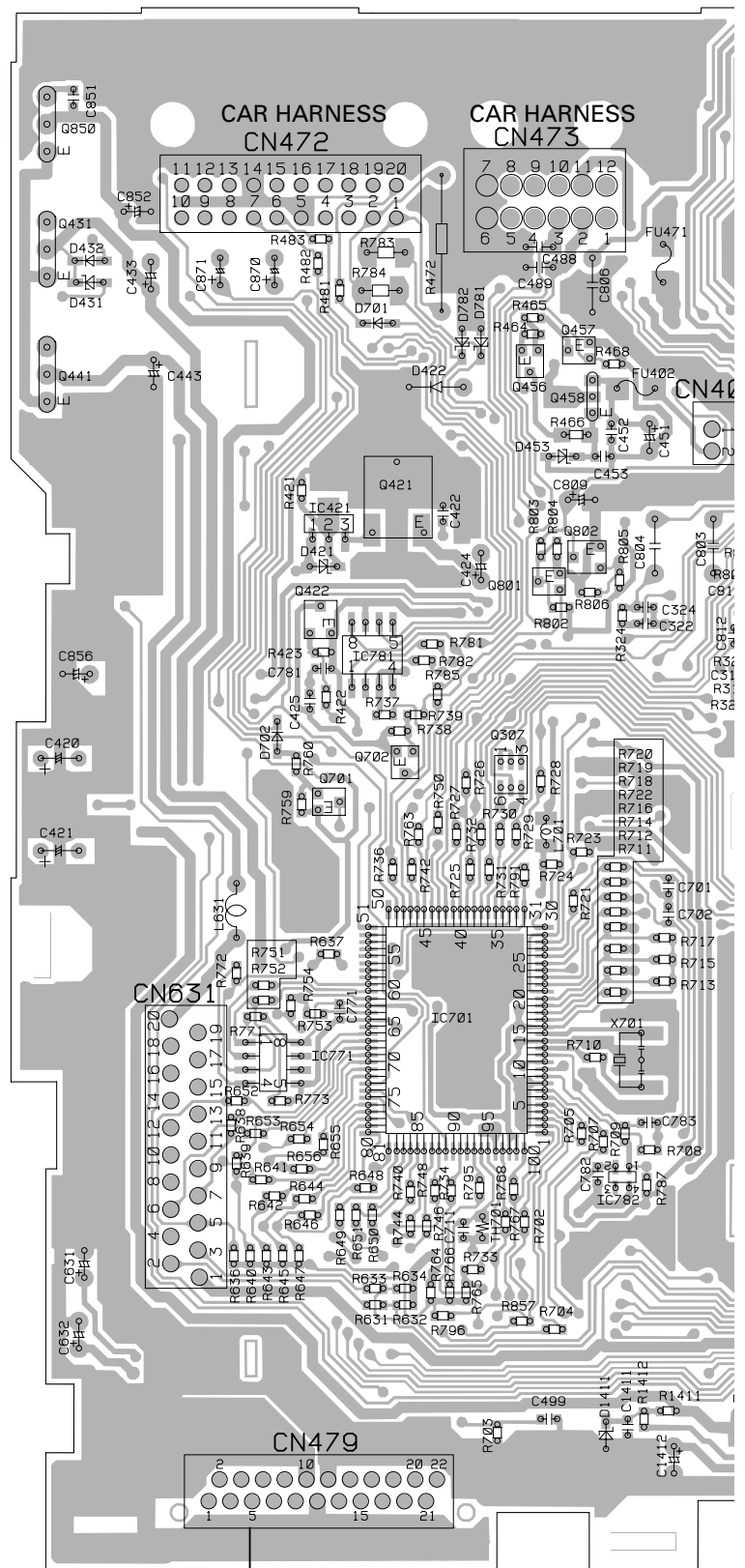
1.The parts mounted on this PCB include all necessary parts for several destination.
For further information for respective destinations, be sure to check with the schematic diagram.

2.Viewpoint of PCB diagrams



A MAIN UNIT

			IC, Q
			IC801
			Q850
			Q431
			Q451
			Q404
			Q805
			Q441
			Q456
			Q458
			Q804
			Q803
			Q402
			Q455
			Q807
			Q403
			Q452
			Q421
			Q808
			IC421
			Q802
			Q454
			Q453
			IC331
			Q422
			Q801
			IC781
			IC302
			IC301
			Q351
			Q563
			Q307
			Q565
			Q702
			Q564
			Q701
			IC501
			Q562
			IC562
			Q501
			IC701
			IC771
			IC351
			IC782
			IC561
			Q1411

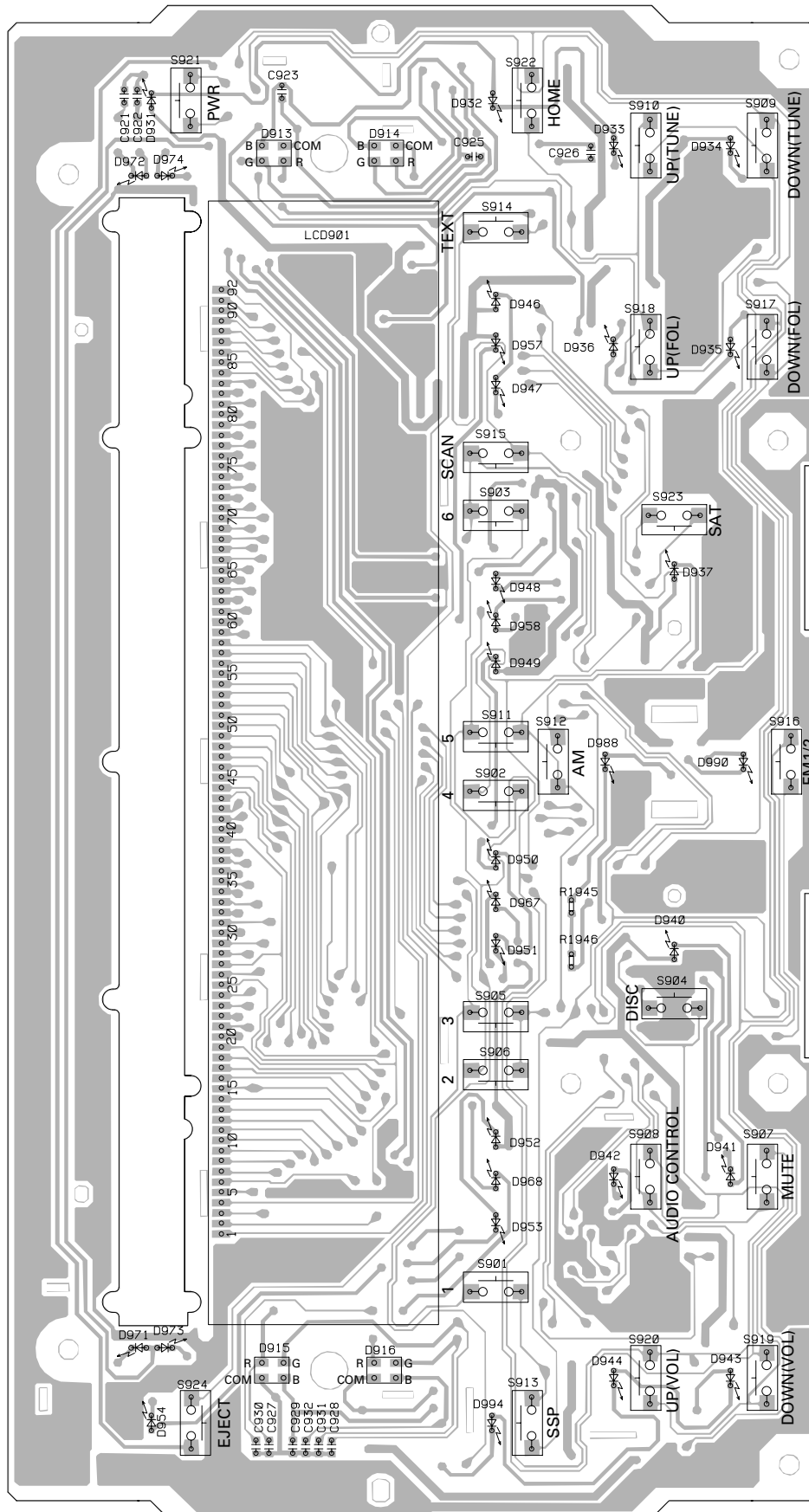


B CN901

4.2 KEYBOARD UNIT

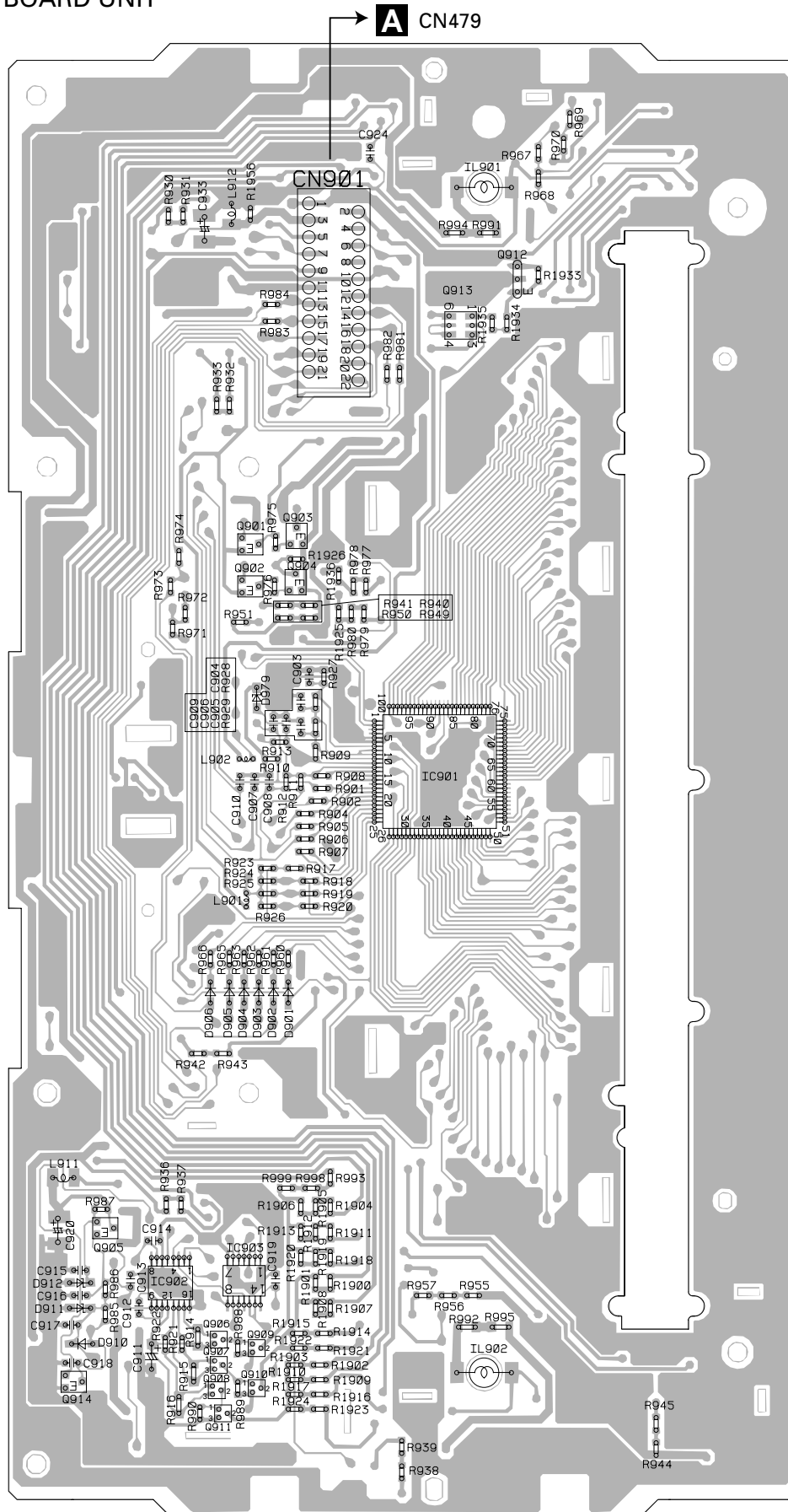
B KEYBOARD UNIT

SIDE A



B KEYBOARD UNIT

SIDE B



IC, Q

Q912
Q913

Q901 Q903
Q904
Q902

IC901

Q905 IC903
IC902

Q906 Q909
Q907
Q908 Q910
Q914
Q911

4.3 CD MECHANISM MODULE

C CD CORE UNIT(S10MP3)

SIDE A

IC, Q

M2
LOADING
/CARRIAGE MOTOR

M1
SPINDLE MOTOR

A CN1601

CN901

PICKUP UNIT
(SERVICE)(P10)

CN101

Q101

IC201

5. ELECTRICAL PARTS LIST

NOTES:

- Parts whose parts numbers are omitted are subject to being not supplied.
- The part numbers shown below indicate chip components.

Chip Resistor

RS1/OS○○○○J,RS1/○○S○○○○J

Chip Capacitor (except for CQS.....)

CKS....., CCS....., CSZS.....

====Circuit Symbol and No.====Part Name	Part No.	====Circuit Symbol and No.====Part Name	Part No.
A Unit Number : CWM8737 Unit Name : Main Unit		D 432 Diode	1SS355
MISCELLANEOUS		D 441 Diode	HZU7R5(B3)
IC 331 IC	NJM4558MD	D 442 Diode	1SS355
IC 351 IC	PM2010A	D 451 Diode	DAN202K
IC 421 IC	S-812C56AUA-C3K	D 452 Diode	1SS355
IC 561 IC	HA12181FP	D 471 Diode	P300JL-6059
IC 701 IC	PD5861A	D 472 Diode	MPG06G-6415G50
		D 473 Diode	MPG06G-6415G50
		D 474 Diode	1SS355
		D 475 Diode	1SS355
IC 781 IC	HA12187FP	D 702 Diode	1SS355
IC 782 IC	S-80835CNNB-B8U	D 781 Diode	UDZS18(B)
IC 801 IC	TDA7386	D 782 Diode	UDZS18(B)
Q 351 Transistor	2SD1859	D 802 Diode	HZU8R2(B3)
Q 402 Transistor	2SC4081	D 804 Diode	1SS355
Q 403 Transistor	2SC4081	D 876 Diode	UDZS5R6(B)
Q 404 Transistor	2SC4081	D 1411 Diode	HZU6R2(B2)
Q 410 Transistor	2SA1576	L 351 Inductor	CTF1379
Q 421 Transistor	2SD1760F5	L 352 Inductor	CTF1379
Q 422 Transistor	2SA1235A-12	L 353 Inductor	CTF1379
Q 431 Transistor	2SB1185	L 354 Inductor	CTF1379
Q 432 Transistor	IMX1	L 355 Inductor	CTF1379
Q 441 Transistor	2SB1185	L 356 Inductor	CTF1379
Q 442 Transistor	IMX1	L 357 Inductor	LCTA2R2J2520
Q 451 Transistor	2SB1260	L 358 Inductor	LCTA2R2J2520
Q 452 Transistor	DTC124EU	L 359 Inductor	CTF1379
Q 453 Transistor	2SC4081	L 360 Inductor	CTF1379
Q 454 Transistor	2SB1260	L 361 Inductor	CTF1379
Q 455 Transistor	2SC4081	L 362 Inductor	LCTA2R2J2520
Q 502 Transistor	2SC4081	L 363 Inductor	CTF1379
Q 524 Transistor	DTC143TU	L 364 Inductor	CTF1379
Q 561 Transistor	2SC4081	L 365 Inductor	CTF1379
Q 563 Transistor	2SA1576	L 367 Inductor	CTF1379
Q 565 Transistor	IMX1	L 369 Inductor	CTF1379
Q 701 Transistor	2SA1576	L 370 Inductor	CTF1379
Q 801 Transistor	DTC143EU	L 371 Inductor	CTF1379
Q 802 Transistor	2SD1781K	L 471 Choke Coil 600μH	CTH1221
Q 803 Transistor	2SC4081	L 505 Ferri-Inductor	LAU4R7K
Q 804 Transistor	DTC143EU	L 512 Inductor	LAU1R0K
Q 805 Transistor	2SA1576	L 514 Inductor	LAU1R0K
Q 806 Transistor	2SA1576	L 561 Ferri-Inductor	LAU4R7K
Q 807 Transistor	2SC4081	L 651 Inductor	LCYA2R2J2520
Q 808 Transistor	2SC4081	L 701 Inductor	LCTA150J2520
Q 850 Transistor	2SB1185	CG 501 Surge Protector	DSP-201M-A21F
Q 852 Transistor	IMX1	X 351 Radiator 33.8688MHz	CSS1600
Q 853 Transistor	2SB1184F5	X 701 Radiator 10.00MHz	CSS1428
Q 854 Transistor	IMX1	FU 471 Fuse	CEK1263
Q 1411 Transistor	2SD1664	FM/AM Tuner Unit	CWE1630
D 351 Diode	HZU3R9(B2)		
D 402 Diode	HZU8R2(B1)		
D 403 Diode	HZU8R2(B1)	R 301	RS1/16S102J
D 411 Diode	RD8R2SL(N1)	R 302	RS1/16S102J
D 421 Diode	UDZS16(B)	R 309	RS1/16S102J
D 422 Diode	MPG06G-6415G50	R 310	RS1/16S102J
D 431 Diode	HZU7R5(B3)	R 315	RS1/16S102J

RESISTORS

====Circuit Symbol and No.==Part Name

Part No.

====Circuit Symbol and No.==Part Name

Part No.

R 316	RS1/16S102J
R 323	RS1/16S102J
R 324	RS1/16S102J
R 328	RS1/16S472J
R 329	RS1/16S472J
R 331	RS1/16S473J
R 332	RS1/16S473J
R 333	RS1/16S473J
R 334	RS1/16S473J
R 335	RS1/16S183J
R 336	RS1/16S183J
R 337	RS1/16S183J
R 338	RS1/16S183J
R 351	RS1/16S221J
R 352	RS1/16S221J
R 353	RS1/16S221J
R 354	RS1/16S221J
R 356	RS1/16S221J
R 357	RS1/16S221J
R 358	RS1/16S221J
R 359	RS1/16S103J
R 360	RS1/16S103J
R 361	RS1/16S105J
R 362	RS1/16S331J
R 363	RS1/16S0R0J
R 364	RS1/16S0R0J
R 365	RS1/16S102J
R 366	RS1/16S102J
R 369	RS1/16S222J
R 370	RS1/16S102J
R 403	RS1/16S153J
R 404	RS1/16S473J
R 405	RS1/10S472J
R 406	RS1/4S182J
R 407	RS1/16S153J
R 408	RS1/16S473J
R 409	RS1/10S472J
R 410	RS1/4S182J
R 412	RS1/16S104J
R 414	RS1/16S224J
R 421	RS1/16S182J
R 422	RS1/16S182J
R 423	RS1/16S103J
R 434	RS1/16S221J
R 435	RS1/16S221J
R 436	RS1/16S471J
R 437	RS1/16S331J
R 439	RS1/16S223J
R 440	RS1/16S472J
R 441	RS1/16S331J
R 443	RS1/16S471J
R 444	RS1/16S221J
R 445	RS1/16S561J
R 447	RS1/16S223J
R 448	RS1/16S562J
R 451	RS1/16S472J
R 452	RS1/16S223J
R 453	RS1/16S103J
R 455	RS1/16S103J
R 456	RS1/16S223J
R 457	RS1/16S823J
R 458	RS1/16S561J
R 459	RS1/16S561J
R 460	RS1/16S561J
R 463	RS1/16S102J
R 468	RS1/16S473J
R 471	RS1/4S101J
R 472	RS1/PMF680J
R 473	RS1/16S0R0J
R 522	RS1/16S222J

R 524	RS1/16S222J
R 525	RS1/16S473J
R 526	RS1/16S681J
R 527	RS1/16S681J
R 528	RS1/16S681J
R 529	RS1/16S103J
R 530	RS1/16S681J
R 531	RS1/16S473J
R 532	RS1/16S473J
R 533	RS1/16S472J
R 534	RS1/16S393J
R 535	RS1/16S473J
R 536	RS1/16S473J
R 537	RS1/16S473J
R 538	RS1/16S681J
R 539	RS1/16S681J
R 541	RS1/16S0R0J
R 542	RS1/16S0R0J
R 543	RS1/16S472J
R 544	RS1/16S472J
R 545	RS1/16S182J
R 546	RS1/16S182J
R 549	RS1/16S0R0J
R 550	RS1/16S0R0J
R 561	RS1/16S104J
R 562	RS1/16S123J
R 564	RS1/16S103J
R 565	RS1/16S362J
R 566	RS1/16S153J
R 567	RS1/16S153J
R 568	RS1/16S222J
R 569	RS1/16S164J
R 570	RS1/16S333J
R 571	RS1/16S473J
R 582	RS1/16S332J
R 584	RS1/16S332J
R 586	RS1/16S473J
R 588	RS1/16S562J
R 611	RS1/16S0R0J
R 612	RS1/16S104J
R 613	RS1/16S0R0J
R 614	RS1/16S104J
R 631	RS1/16S392J
R 632	RS1/16S103J
R 633	RS1/16S392J
R 634	RS1/16S103J
R 635	RS1/16S102J
R 637	RS1/16S102J
R 649	RS1/16S102J
R 650	RS1/16S102J
R 651	RS1/16S681J
R 660	RS1/16S473J
R 661	RS1/16S473J
R 662	RS1/16S473J
R 663	RS1/16S473J
R 664	RS1/16S473J
R 665	RS1/16S473J
R 702	RS1/16S102J
R 703	RS1/16S473J
R 704	RS1/16S102J
R 705	RS1/16S152J
R 707	RS1/16S102J
R 708	RS1/16S0R0J
R 709	RS1/16S0R0J
R 710	RS1/16S0R0J
R 711	RS1/16S473J
R 712	RS1/16S0R0J
R 713	RS1/16S473J
R 714	RS1/16S0R0J
R 715	RS1/16S104J

A

B

C

D

E

F

====Circuit Symbol and No.==Part Name

Part No.

====Circuit Symbol and No.==Part Name

Part No.

A

R 716
R 717
R 718
R 719
R 720RS1/16S0R0J
RS1/16S473J
RS1/16S102J
RS1/16S0R0J
RS1/16S0R0JR 815
R 816
R 817
R 818
R 819RS1/10S681J
RS1/16S473J
RS1/16S473J
RS1/16S473J
RS1/16S473JR 721
R 722
R 723
R 724
R 725RS1/16S0R0J
RS1/16S102J
RS1/16S473J
RS1/16S472J
RS1/16S0R0JR 853
R 854
R 855
R 856
R 857RS1/16S102J
RS1/16S471J
RS1/16S222J
RS1/16S242J
RS1/16S102JR 726
R 727
R 728
R 729
R 730RS1/16S471J
RS1/16S0R0J
RS1/16S0R0J
RS1/16S102J
RS1/16S0R0JR 858
R 859
R 860
R 870
R 871RS1/16S471J
RS1/16S152J
RS1/16S222J
RS1/16S472J
RS1/8S222J

B

R 731
R 732
R 733
R 734
R 735RS1/16S332J
RS1/16S0R0J
RS1/16S102J
RS1/16S102J
RS1/16S102JR 872
R 873
R 874
R 875
R 876RS1/10S103J
RS1/16S123J
RS1/16S103J
RS1/16S103J
RS1/16S103JR 736
R 737
R 740
R 742
R 743RS1/16S102J
RS1/16S473J
RS1/16S102J
RS1/16S102J
RS1/16S473JR 1411
R 1412RS1/16S331J
RS1/16S0R0J

CAPACITORS

R 744
R 746
R 748
R 750
R 753RS1/16S102J
RS1/16S102J
RS1/16S102J
RS1/16S102J
RS1/16S102JC 307
C 308
C 309
C 310
C 321CKSRYB222K50
CKSRYB222K50
CKSRYB222K50
CKSRYB222K50
CKSRYB222K50

C

R 754
R 755
R 756
R 759
R 760RS1/16S473J
RS1/16S102J
RS1/16S473J
RS1/16S472J
RS1/16S103JC 322
C 323
C 324
C 327
C 328CKSRYB222K50
CKSRYB222K50
CKSRYB222K50
CEAL220M10
CEAL220M10R 761
R 762
R 763
R 764
R 765RS1/16S102J
RS1/16S104J
RS1/16S102J
RS1/16S102J
RS1/16S102JC 329
C 330
C 331
C 332
C 333CKSRYB104K25
CEAL220M10
CEJQ3R3M50
CEJQ3R3M50
CEJQ3R3M50

D

R 767
R 768
R 769
R 774
R 775RS1/16S102J
RS1/16S681J
RS1/16S103J
RS1/16S102J
RS1/16S102JC 334
C 335
C 336
C 337
C 338CEJQ3R3M50
CCSRCH150J50
CCSRCH150J50
CEJQ470M10
CKSRYB473K50R 778
R 779
R 781
R 782
R 783RS1/16S472J
RS1/16S472J
RS1/16S0R0J
RS1/16S0R0J
RS1/4S101JC 339
C 340
C 345
C 350
C 351CEAL220M10
CKSRYB104K25
CKSRYB222K50
CKSRYB102K50
CKSRYB334K10R 784
R 785
R 787
R 788
R 790RS1/4S101J
RS1/16S0R0J
RS1/16S104J
RS1/16S472J
RS1/16S473JC 352
C 353
C 354
C 355
C 356CKSRYB334K10
CKSRYB334K10
CKSRYB334K10
CKSRYB334K10
CKSRYB334K10

E

R 791
R 801
R 802
R 803
R 804RS1/16S0R0J
RS1/16S103J
RS1/16S103J
RS1/16S331J
RS1/16S103JC 357
C 358
C 359
C 360
C 362CKSRYB334K10
CKSRYB102K50
CKSRYB222K50
CEAL220M10
CKSRYB102K50R 805
R 806
R 807
R 808
R 809RS1/16S222J
RS1/16S103J
RS1/16S684J
RS1/16S684J
RS1/16S223JC 363
C 364
C 365
C 366
C 368CEAL220M10
CCSRCH100D50
CCSRCH100D50
CKSRYB103K50
CKSRYB104K25R 810
R 811
R 812
R 813
R 814RS1/16S104J
RS1/16S103J
RS1/16S223J
RS1/16S472J
RS1/16S103JC 371
C 372
C 373
C 374
C 375CKSRYB104K25
CEALNP4R7M35
CKSRYB104K25
CEALNP4R7M35
CKSRYB104K25

F

====Circuit Symbol and No.==Part Name

Part No.

C 376
C 377
C 380
C 381
C 384

CEALNP4R7M35
CEAL101M10
CKSRYB104K25
CEALNP4R7M35
CKSRYB104K25

C 385
C 386
C 387
C 388
C 390

CKSRYB222K50
CKSRYB105K10
CKSRYB103K50
CEJQ470M10
CKSRYB104K25

C 393
C 397
C 398
C 399
C 401

CKSRYB104K25
CKSRYB104K25
CKSRYB222K50
CKSRYB222K50
CKSRYB103K50

C 402
C 403
C 404
C 408
C 420

470μF/16V

CEJQ2R2M50
CKSRYB103K50
CEJQ2R2M50
CKSQYB103K50
CCH1459

C 422
C 423
C 424
C 425
C 432

CKSRYB103K50
CKSRYB103K50
CEHAT101M10
CKSRYB103K50
CKSRYB473K50

C 433
C 434
C 435
C 442
C 443

CEHAT470M16
CKSRYB103K50
CEAT471M10
CKSRYB473K50
CEHAT101M10

C 444
C 461
C 469
C 470
C 471

3300μF/16V

CKSRYB103K50
CKSRYB102K50
CCSRCH221J50
CCSRCH221J50
CCH1177

C 472
C 473
C 474
C 475
C 476

CKSQYB332K50
CKSQYB332K50
CKSQYB332K50
CKSQYB332K50
CKSQYB332K50

C 477
C 478
C 479
C 480
C 481

CKSQYB332K50
CKSQYB332K50
CKSQYB332K50
CKSQYB102K50
CKSQYB393K50

C 484
C 485
C 486
C 487
C 488

CCSQCH221J50
CCSQCH221J50
CKSQYB222K50
CKSQYB222K50
CKSQYB222K50

C 489
C 490
C 503
C 519
C 520

CKSQYB222K50
CKSQYB473K50
CKSQYB103K50
CKSRYB103K50
CKSRYB103K50

C 521
C 522
C 523
C 524
C 525

CEAT101M16
CKSRYB103K50
CEAT100M50
CKSRYB472K50
CKSRYB183K50

C 526
C 527
C 528
C 530
C 531

CKSRYB183K50
CKSRYB562K25
CKSRYB562K25
CCSRCH100D50
CKSRYB102K50

C 561
C 562
C 563
C 564
C 565

CEJQ3R3M50
CKSRYB333K25
CEJQNP1R0M50
CQMA683J50
CQMA333J50

====Circuit Symbol and No.==Part Name

Part No.

C 566
C 567
C 568
C 569
C 570

CQMA333J50
CQMA333J50
CKSRYB224K10
CKSRYB473K50
CKSRYB153K50

C 571
C 572
C 573
C 574
C 575

CKSRYB472K50
CEJQ101M10
CKSRYB392K50
CKSRYB334K10
CKSRYB102K50

C 585
C 713
C 781
C 782
C 783

CKSRYB223K50
CSZS100M16
CKSRYB104K25
CKSRYB223K50
CKSRYB103K50

C 801
C 802
C 803
C 804
C 805

CFTNA224J50
CFTNA224J50
CFTNA224J50
CFTNA224J50
CKSQYB104K25

C 806
C 807
C 808
C 809
C 812

CFTNA105J50
CEJQ100M50
CEJQ1R0M50
CEJQ330M16
CKSRYB473K50

C 850
C 851
C 853
C 854
C 856

CKSRYB103K50
CKSRYB102K50
CKSRYB103K50
CKSRYB103K50
CEJQ470M16

C 857
C 870
C 871
C 877
C 1411

CKSRYB103K50
CEJQ1R0M50
CEJQ1R0M50
CKSRYB102K50
CKSRYB473K50

C 1412

CEAT101M10

B Unit Number : CWM8738
Unit Name : Keyboard Unit

MISCELLANEOUS

IC 901 IC
Q 912 Transistor
Q 913 Transistor
D 901 Diode
D 902 Diode

UPD16432B-001
2SB1132
IMD3A
MA111
MA111

D 903 Diode
D 904 Diode
D 905 Diode
D 906 Diode
D 931 LED

MA111
MA111
MA111
MA111
SML-310YT(KL)

D 932 LED
D 933 LED
D 934 LED
D 935 LED
D 936 LED

SML-310YT
SML-310YT
SML-310YT
SML-310YT
SML-310YT

D 937 LED
D 940 LED
D 941 LED
D 942 LED
D 943 LED

SML-310YT
SML-310YT
SML-310YT
SML-310YT
SML-310YT

D 944 LED
D 946 LED
D 947 LED
D 948 LED
D 949 LED

SML-310YT
SML-310YT
SML-310YT
SML-310YT
SML-310YT

D 950 LED
D 951 LED
D 952 LED
D 953 LED
D 954 LED

SML-310YT
SML-310YT
SML-310YT
SML-310YT
SML-310YT

====Circuit Symbol and No.==Part Name

Part No.

====Circuit Symbol and No.==Part Name

Part No.

A

D 957 LED SML-310YT
 D 958 LED SML-310YT
 D 967 LED SML-310YT
 D 968 LED SML-310YT
 D 973 LED SML-310YT

R 939 RS1/16S820J
 R 940 RS1/16S820J
 R 941 RS1/16S820J
 R 942 RS1/16S820J
 R 943 RS1/16S820J

D 974 LED SML-310YT
 D 988 LED SML-310YT
 D 990 LED SML-310YT
 D 994 LED SML-310YT
 L 901 Inductor CTF1379

R 944 RS1/16S820J
 R 945 RS1/16S820J
 R 949 RS1/16S910J
 R 950 RS1/16S910J
 R 951 RS1/16S910J

L 902 Inductor CTF1379
 S 901 Switch CSG1154
 S 902 Switch CSG1154
 S 903 Switch CSG1154
 S 904 Switch CSG1154

R 955 RS1/16S910J
 R 956 RS1/16S910J
 R 957 RS1/16S910J
 R 960 RS1/16S102J
 R 961 RS1/16S102J

B

S 905 Switch CSG1154
 S 906 Switch CSG1154
 S 907 Switch CSG1154
 S 908 Switch CSG1154
 S 909 Switch CSG1154

R 962 RS1/16S102J
 R 963 RS1/16S102J
 R 965 RS1/16S102J
 R 966 RS1/16S102J
 R 968 RS1/16S0R0J

S 910 Switch CSG1154
 S 911 Switch CSG1154
 S 912 Switch CSG1154
 S 913 Switch CSG1154
 S 914 Switch CSG1154

R 970 RS1/16S0R0J
 R 971 RS1/16S0R0J
 R 973 RS1/16S0R0J
 R 979 RS1/16S910J
 R 980 RS1/16S910J

S 915 Switch CSG1154
 S 916 Switch CSG1154
 S 917 Switch CSG1154
 S 918 Switch CSG1154
 S 919 Switch CSG1154

R 991 RS1/10S200J
 R 992 RS1/10S200J
 R 994 RS1/10S200J
 R 995 RS1/10S200J
 R 1925 RS1/16S910J

C

S 920 Switch CSG1154
 S 921 Switch CSG1154
 S 922 Switch CSG1154
 S 923 Switch CSG1154
 S 924 Switch CSG1154

R 1926 RS1/16S0R0J
 R 1933 RS1/16S223J
 R 1934 RS1/16S511J
 R 1935 RS1/16S511J
 R 1945 RS1/16S820J

IL 901 Lamp 8V 60mA
 IL 902 Lamp 8V 60mA
 LCD

CEL1742
 CEL1742
 CAW1809

R 1946 RS1/16S820J
 R 1956 RS1/16S0R0J

RESISTORS

CAPACITORS

D

R 901 RS1/16S681J
 R 902 RS1/16S681J
 R 904 RS1/16S681J
 R 905 RS1/16S221J
 R 906 RS1/16S681J

C 903 CKSRYB473K50
 C 904 CKSRYB473K50
 C 905 CKSRYB473K50
 C 906 CKSRYB473K50
 C 907 CCSRCH101J50

R 907 RS1/16S104J
 R 908 RS1/16S473J
 R 909 RS1/16S102J
 R 910 RS1/16S473J
 R 911 RS1/16S103J

C 908 CCSRCH101J50
 C 909 CKSRYB474K10
 C 910 CKSRYB102K50

R 912 RS1/16S473J
 R 913 RS1/16S152J
 R 917 RS1/16S222J
 R 918 RS1/16S222J
 R 919 RS1/16S222J

MISCELLANEOUS

E

R 920 RS1/16S222J
 R 923 RS1/16S473J
 R 924 RS1/16S473J
 R 925 RS1/16S473J
 R 926 RS1/16S473J

IC 201 IC UPD63760GJ
 IC 202 IC MSM51V4265EP-70TS
 IC 203 IC BA033SFP
 IC 301 IC BA5996FM
 IC 701 IC PE5370B

R 927 RS1/16S102J
 R 928 RS1/16S102J
 R 929 RS1/16S102J
 R 930 RS1/16S820J
 R 931 RS1/16S820J

IC 702 IC TC74VHCT08AFT
 IC 703 IC S-812C33AUA-C2N
 Q 101 Transistor 2SB1132
 Q 601 Transistor DTC323TK
 Q 602 Transistor DTC323TK

R 932 RS1/16S820J
 R 933 RS1/16S820J
 R 936 RS1/16S820J
 R 937 RS1/16S820J
 R 938 RS1/16S820J

Q 603 Transistor 2SB709A
 Q 701 Transistor UN2111
 D 101 Diode 1SS355
 D 201 Diode 1SR154-400
 D 601 Diode MA152WA

F

====Circuit Symbol and No.====Part Name

Part No.

====Circuit Symbol and No.====Part Name

Part No.

L 201 Inductor
L 202 Inductor
L 204 Inductor
L 205 Inductor
L 206 Inductor

CTF1386
CTF1386
CTF1386
CTF1386
CTF1386

R 303
R 304
R 305
R 306
R 307

RS1/16SS0R0J
RS1/16SS183J
RS1/16SS822J
RS1/16SS0R0J
RS1/16SS183J

A

L 207 Inductor
L 208 Inductor
L 209 Inductor
L 211 Inductor
L 212 Inductor

CTF1386
CTF1386
CTF1386
CTF1386
CTF1386

R 308
R 309
R 310
R 311
R 601

RS1/16SS822J
RS1/16SS183J
RS1/16SS822J
RS1/16SS0R0J
RS1/16S101J

L 701 Inductor
L 702 Inductor
L 703 Inductor
L 704 Inductor
TH 701 Thermistor

CTF1386
LCYBR22J1608
CTF1386
CTF1386
CCX1037

R 602
R 603
R 604
R 605
R 707

RS1/16S101J
RS1/16S223J
RS1/16S223J
RS1/16SS103J
RS1/16SS0R0J

B

X 201 Ceramic Resonator 16.934MHz
X 701 Ceramic Resonator 16.00MHz
S 901 Switch(HOME)
S 902 Switch(CLAMP)
S 903 Spring Switch(DSCSNS)

CSS1603
CSS1616
CSN1051
CSN1051
CSN1052

R 708
R 710
R 711
R 712
R 713

RS1/16SS102J
RS1/16SS102J
RS1/16SS102J
RS1/16SS102J
RS1/16SS102J

S 904 Switch(12EJ)
S 905 Switch(8EJ)

CSN1051
CSN1051

R 714
R 715
R 716
R 717
R 718

RS1/16SS473J
RAB4CQ221J
RAB4CQ221J
RAB4CQ221J
RAB4CQ221J

RESISTORS

R 101
R 102
R 103
R 104
R 105

RS1/10S1R5J
RS1/10S1R5J
RS1/10S1R5J
RS1/10S1R5J
RS1/10S1R5J

R 719
R 720
R 723
R 724
R 725

RS1/16SS221J
RS1/16SS471J
RS1/16SS102J
RN1/16SE1302D
RS1/16SS222J

C

R 201
R 202
R 203
R 205
R 207

RS1/16SS102J
RS1/16SS333J
RS1/16SS333J
RS1/16SS0R0J
RS1/16SS0R0J

R 726
R 727
R 728
R 729
R 730

RS1/16SS103J
RS1/16SS473J
RS1/16SS473J
RS1/16SS223J
RS1/16SS473J

R 209
R 213
R 214
R 215
R 216

RS1/16SS0R0J
RS1/16SS1002D
RS1/16SS1002D
RS1/16SS6801D
RS1/16SS6801D

R 731
R 732
R 733
R 737
R 739

RS1/16SS104J
RS1/16SS104J
RS1/16SS104J
RAB4CQ473J
RAB4CQ473J

R 217
R 218
R 219
R 220
R 221

RS1/16SS1002D
RS1/16SS1002D
RS1/16SS1002D
RS1/16SS1002D
RS1/16SS103J

R 740
R 742
R 744
R 745
R 746

RS1/16SS473J
RS1/16SS104J
RS1/16SS104J
RS1/16SS473J
RS1/16SS104J

D

R 222
R 223
R 224
R 225
R 226

RS1/16SS103J
RS1/16SS103J
RS1/16SS103J
RS1/16SS103J
RS1/16SS393J

R 747
R 748
R 751
R 754
R 755

RS1/16SS104J
RS1/16SS104J
RS1/16SS104J
RS1/16SS102J
RS1/16SS102J

R 227
R 228
R 229
R 231
R 232

RS1/16SS103J
RS1/16SS182J
RS1/16SS103J
RS1/16SS0R0J
RS1/16SS182J

R 756
R 801
R 802
R 803
R 901

RS1/16SS104J
RS1/16SS104J
RS1/16SS473J
RS1/16SS273J
RS1/16SS221J

E

R 233
R 237
R 238
R 239
R 240

RS1/16SS0R0J
RS1/16SS104J
RS1/16SS473J
RS1/16SS333J
RS1/16SS0R0J

R 902
R 903
R 904
R 905
R 906

RS1/16SS221J
RS1/16SS221J
RS1/16SS221J
RS1/16SS221J
RS1/16SS221J

R 242
R 243
R 244
R 245
R 246

RAB4CQ221J
RAB4CQ221J
RAB4CQ221J
RAB4CQ221J
RAB4CQ221J

CAPACITORS

C 101
C 102
C 103
C 104
C 105

CKSSYB104K10
CKSSYB104K10
CEV101M16
CEV101M4
CKSSYB104K10

R 247
R 248
R 249
R 301
R 302

RAB4CQ221J
RS1/16SS221J
RS1/16SS221J
RS1/16SS183J
RS1/16SS822J

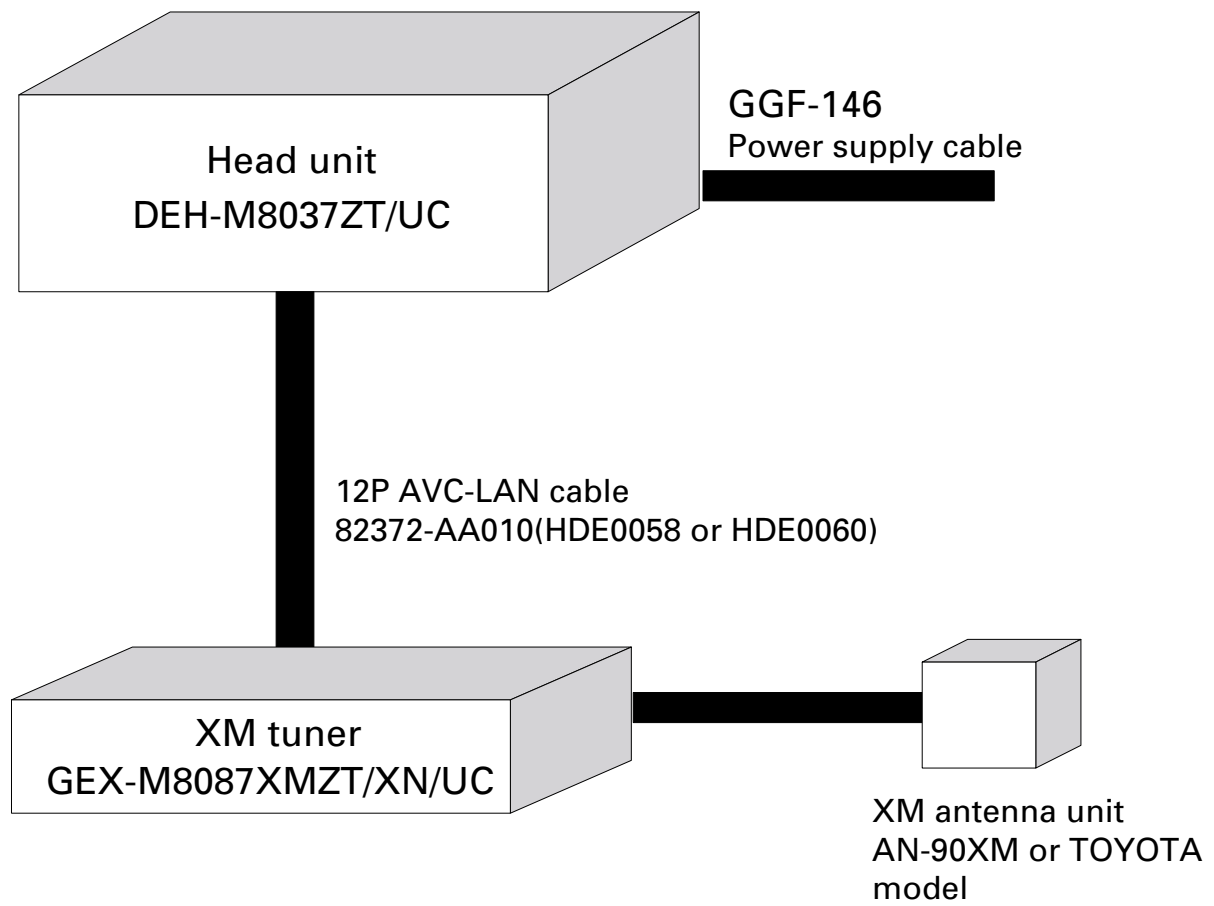
F

	====Circuit Symbol and No.====Part Name	Part No.
A	C 106	CCSRCH101J50
	C 108	CKSSYB104K10
	C 109	CEV100M16
	C 201	CKSSYB471K50
	C 202	CKSSYB104K10
	C 203	CKSSYB104K10
	C 204	CEV220M6R3
	C 205	CKSSYB103K16
	C 206	CKSSYB103K16
	C 207	CEV221M4
	C 208	CKSSYB104K10
	C 209	CKSSYB104K10
	C 210	CKSSYB104K10
	C 211	CKSSYB104K10
	C 216	CKSSYB332K50
B	C 217	CKSSYB104K10
	C 218	CKSSYB223K16
	C 219	CKSSYB104K10
	C 220	CKSSYB103K16
	C 221	CKSSYB104K10
	C 222	CCSSCH270J50
	C 223	CCSSCJ3R0C50
	C 224	CKSSYB104K10
	C 225	CKSSYB103K16
	C 226	CCSSCH680J50
	C 227	CCSSCH470J50
	C 228	CKSSYB682K25
	C 230	CKSSYB104K10
	C 232	CKSSYB104K10
	C 233	CCH1436
C	C 234	CEV221M4
	C 235	CKSRYB224K16
	C 237	CKSSYB104K10
	C 238	CKSSYB104K10
	C 239	CCSSCH9R0D50
	C 242	CKSSYB104K10
	C 243	CKSSYB104K10
	C 245	CKSSYB104K10
	C 246	CKSSYB104K10
	C 301	CKSSYB331K50
D	C 302	CKSSYB331K50
	C 303	CKSSYB472K25
	C 304	CKSSYB472K25
	C 305	CEV101M16
	C 306	CKSRYB224K16
	C 601	CCSRCH102J50
	C 602	CCSRCH102J50
	C 603	CCH1508
	C 604	CCH1508
	C 701	CKSSYB104K10
	C 702	CKSSYB471K50
	C 703	CKSSYB103K16
	C 704	CEV1R0M50
	C 705	CKSSYB104K10
	C 707	CKSSYB104K10
E	C 708	CKSSYB104K10
	C 709	CKSSYB103K16
	C 710	CKSSYB104K10
	C 711	CCH1349
	C 712	CKSRYB224K16
	C 713	CKSSYB104K10
	C 714	CKSSYB104K10
	C 715	CKSSYB103K16
	C 716	CKSSYB103K16
	C 901	CKSSYB104K10
	C 903	CCSRCH101J50

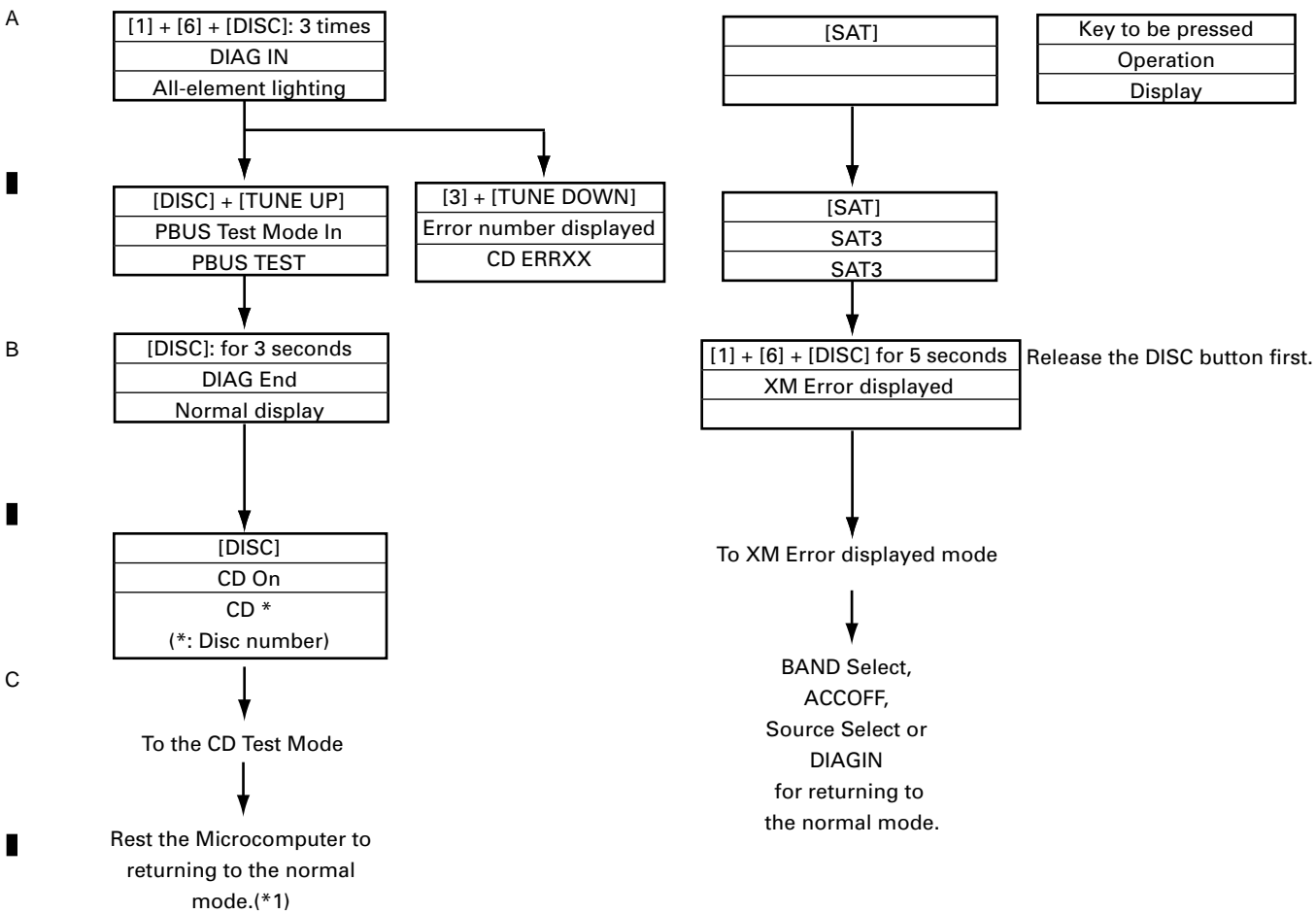
	====Circuit Symbol and No.====Part Name	Part No.
Miscellaneous Parts List		
	Pickup Unit(Service)(P10)	CXX1664
M 1	Motor Unit(SPINDLE)	CXB6007
M 2	Motor Unit(LOADING/CARRIAGE)	CXB8933

6. ADJUSTMENT

6.1 CONNECTION DIAGRAM



6.2 TEST MODE



Notes:

*1) Note that the test mode is cancelled in the system microcomputer by switching the ACC OFF and ON, but that it is not in the CD microcomputer. Use the reset function for complete cancellation of the test mode.

6.3 CD ADJUSTMENT

1) Cautions on adjustments

• In this product the single voltage (3.3V) is used for the regulator. The reference voltage is the REFO1 (1.65V) instead of the GND.

If you should mistakenly short the REFO1 with the GND during adjustment, accurate voltage will not be obtained, and the servo's misoperation will apply excessive shock to the pickup. To avoid such problems:

a. Do not mix up the REFO1 with the GND when connecting the (-) probe of measuring instruments. Especially on an oscilloscope, avoid connecting the (-) probe for CH1 to the GND.

b. In many cases, measuring instruments have the same potential as that for the (-) probe. Be sure to set the measuring instruments to the floating state.

c. If you have mistakenly connected the REFO1 to the GND, turn off the regulator or the power immediately.

• Before mounting and removing filters or leads for adjustment, be sure to turn off the regulator.

• For stable circuit operation, keep the mechanism operating for about one minute or more after the regulator is turned on.

• In the test mode, any software protections will not work. Avoid applying any mechanical or electrical shock to the mechanism during adjustment.

• The RFI and RFO signals with a wide frequency range are easy to oscillate. When observing the signals, insert a resistor of 1k ohms in series.

• The load and eject operation is not guaranteed with the mechanism upside down. If the mechanism is blocked due to mistaken eject operation, reset the product or turn off and on the ACC to restore it.

2) Test mode

This mode is used to adjust the CD mechanism module.

• To enter the test mode.

See page 46.

• To exit from the test mode.

Turn off the ACC and back up.

Notes:

a. During ejection, do not press any other keys than the EJECT key until the loaded disc is ejected.

b. If you have pressed the TUNE UP key or TUNE DOWN key during focus search, turn off the power immediately to protect the actuator from damage caused by the lens stuck.

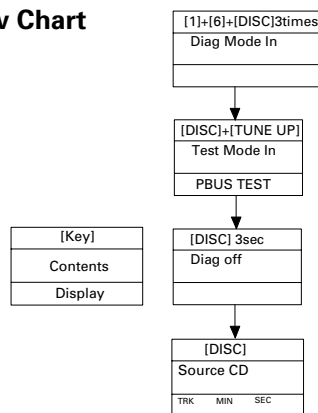
c. For the TR jump modes except 100TR, the track jump operation will continue even if the key is released.

d. For the CRG move and 100TR jump modes, the tracking loop will be closed at the same time when the key is released.

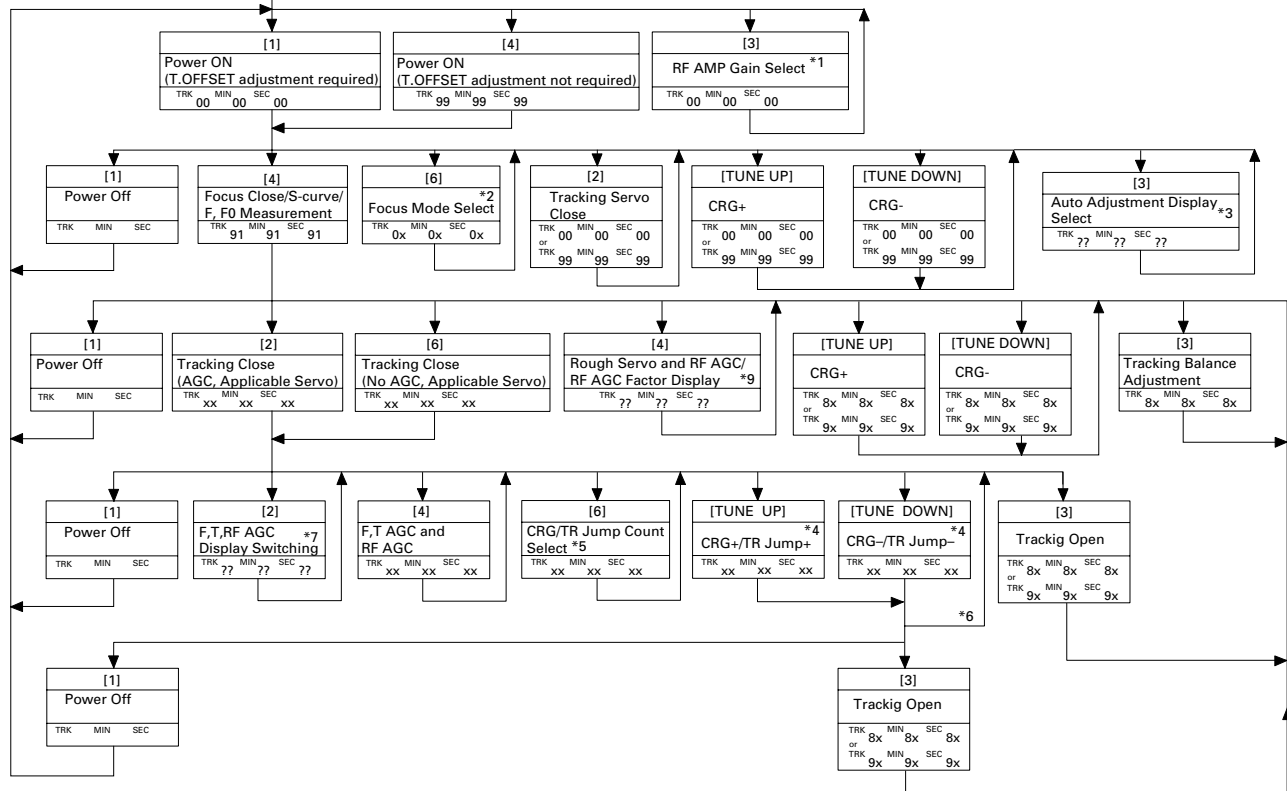
e. When the power is turned off and on, the jump mode is reset to the single TR (91), the RF amp gain is set to 0dB, and the auto-adjustment values are reset to the default settings.

Flow Chart

A



B



C

D

- *1) TYP → -6dB → -12dB
TRK MIN SEC TRK MIN SEC TRK MIN SEC
00 00 00 06 06 06 12 12 12
- *2) Focus Close → S.Curve Check → LD Off
TRK MIN SEC TRK MIN SEC TRK MIN SEC
00 00 00 01 01 01 02 02 02
(TRK MIN SEC 99 99 99)
- *3) F.Offset Display → RF Offset Display → T.Bal Display → Rough Servo.
(F.Cancel value = (Upper 8 bits of the setting (7[F][H] to 80[H] + 128)/4 = 63[D] to 32[D] to 00[D]).
- *4) Single TR / 4TR / 10TR / 32TR / 100TR
- *5) Single TR → 4 TR → 10 TR → 32 TR → 100 TR → CRG Move
9X(8X):91(81) 92(82) 93(83) 94(84) 95(85) 96(86)
- *6) Only for the CRG Move and 100TR modes
- *7) Track No. / Min / Sec → F.AGC Gain → T.AGC Gain → RF AGC Gain
(F.T. AGC Gain = (Current value/Initial value) x 20)
- *8) CRG motor voltage : 2 [V]
- *9) The first press displays the RF AGC coefficient. The second one or after performs the rough servo and RF AGC adjustments, and then displays the RF AGC coefficient.

F

[Key]	Operation
[1]	Test Mode Power ON/OFF
[TUNE UP]	CRG+/TR Jump+ (Toward outer perimeter)
[TUNE DOWN]	CRG-/TR Jump- (Toward inner perimeter)
[2]	Tracking close and AGC and Applicable servo / AGC , AGC display switching
[3]	RF gain select / Offset adjustment display/ Tracking balance adjustment / Tracking open
[4]	Focus Close, S.Curve / Rough Servo/ RF AGC / F,T, RF AGC
[6]	Focus mode select / Tracking close / CRG-TR jump select
[TEXT]	Focus open
[5]	Jump off

- In all TR Jump modes except for 100TR, track jump operation continues even after the key is released.
- In the CRG Move and 100TR Jump modes, the tracking servo loop closes at the same time when the key is released.
- When the power is turned off and on, the jump mode, the RF AMP gain setting, and the auto adjustment values are reset to the Single TR (91), 0dB, and the factory setting respectively.

Note: When you pressed the [TUNE UP] or [TUNE DOWN] key during the Focus Search, you must turn the power off immediately (otherwise, the lens can stick resulting in actuator damages).

6.4 CHECKING THE GRATING AFTER CHANGING THE PICKUP UNIT

• Note :

The grating angle of the PU unit cannot be adjusted after the PU unit is changed. The PU unit in the CD mechanism module is adjusted on the production line to match the CD mechanism module and is thus the best adjusted PU unit for the CD mechanism module. Changing the PU unit is thus best considered as a last resort. However, if the PU unit must be changed, the grating should be checked using the procedure below.

• Purpose :

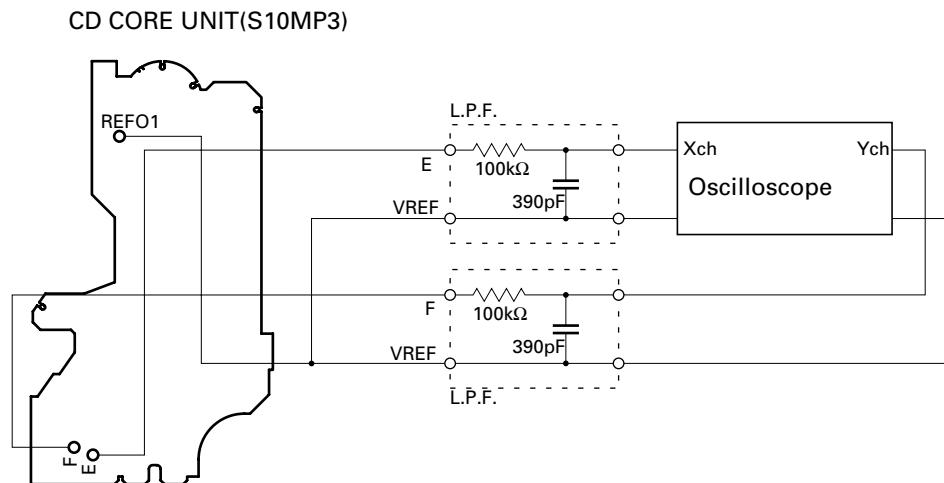
To check that the grating is within an acceptable range when the PU unit is changed.

• Symptoms of Mal-adjustment :

If the grating is off by a large amount symptoms such as being unable to close tracking, being unable to perform track search operations, or taking a long time for track searching.

• Method :

- | | |
|-----------------------|----------------------------|
| • Measuring Equipment | • Oscilloscope, Two L.P.F. |
| • Measuring Points | • E, F, REFO1 |
| • Disc | • ABEX TCD-782 |
| • Mode | • TEST MODE |



• Checking Procedure

1. In test mode, load the disc and switch the 3V regulator on.
2. Using the TUNE UP and TUNE DOWN buttons, move the PU unit to the innermost track.
3. Press key 4 to close focus, the display should read "91". Press key 3 to implement the tracking balance adjustment the display should now read "81". Press key 4. The display will change, returning to "81" on the fourth press.
4. As shown in the diagram above, monitor the LPF outputs using the oscilloscope and check that the phase difference is within 75° . Refer to the photographs supplied to determine the phase angle.
5. If the phase difference is determined to be greater than 75° try changing the PU unit to see if there is any improvement. If, after trying this a number of times, the grating angle does not become less than 75° then the mechanism should be judged to be at fault.

• Note

Because of eccentricity in the disc and a slight misalignment of the clamping center the grating waveform may be seen to "wobble" (the phase difference changes as the disc rotates). The angle specified above indicates the average angle.

• Hint

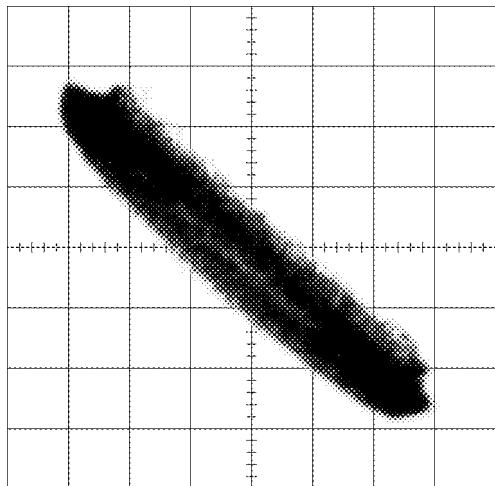
Reloading the disc changes the clamp position and may decrease the "wobble".

A Grating waveform

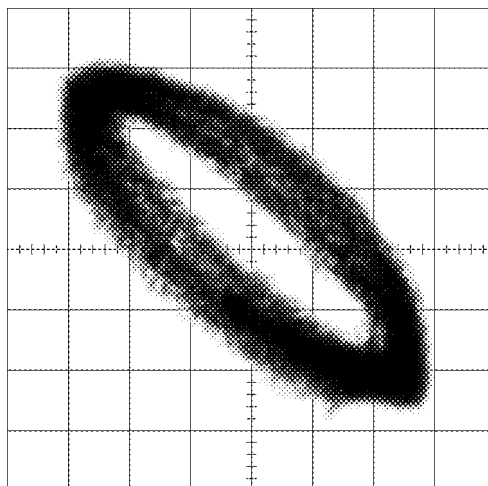
Ech → Xch 20mV/div, AC

Fch → Ych 20mV/div, AC

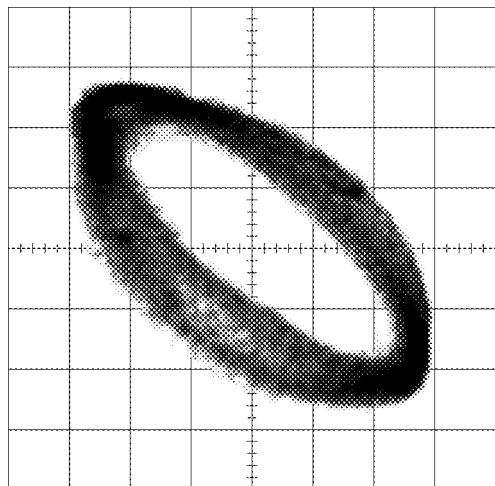
0°



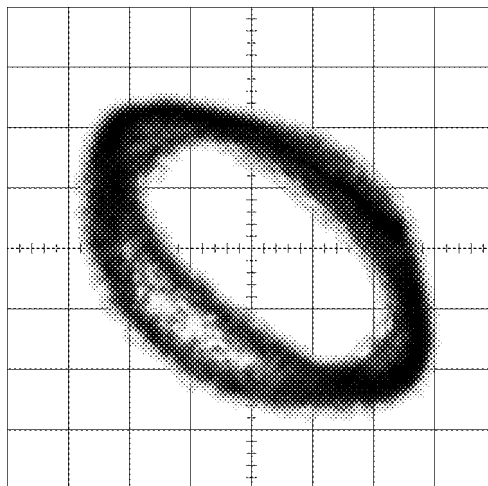
30°



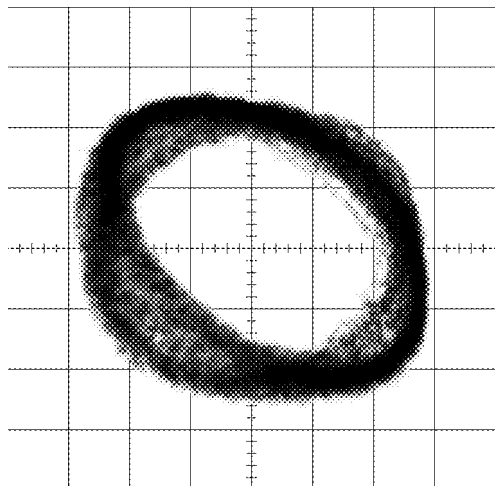
45°



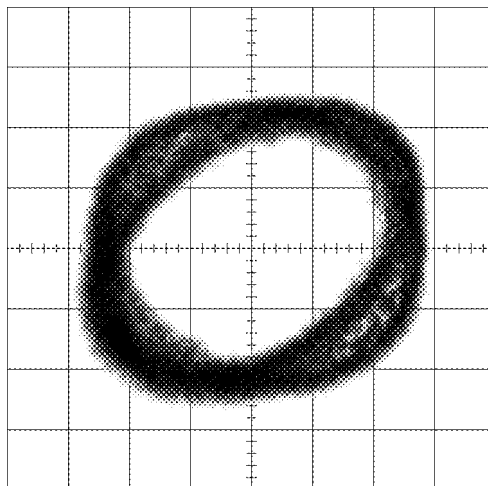
60°



75°



90°



6.5 ERROR MODE

● Error Messages

Error is displayed with number for Error cause when CD is inoperative or stops with Error during operation. The purpose is to reduce nonsense calls from users as well as to assist all related analysis and repair for defects at service station.

(1) Basic Display Method

1) When CSMOD (CD mode area for system) is SERRORM, Error code will be written in DMIN (minutes area for display), DSEC (seconds area for display). The same data shall be written in DMIN and DSEC. DTNO is blank as usual.

2) Display Example of Head Unit

The following is about LCD display ability. xx is Error number.

8 digits	6 digits	4 digits
ERROR-xx	ERR-xx	E-xx
	OR	
	Err-xx	

(2) Error Code List

No.	Classification	Contents	Details • Cause
10	Electricity	Carriage Home NG	CRG can't move to the inner. CRG can't move from the inner. → HOME SW failure, CRG movement failure.
11	Electricity	Focus Search NG	Focus can't be caught. → Back of Disc / Severe dirt and vibration.
12	Electricity	Spindle Lock NG Subcode NG RF-amp NG	Not spindle, lock. Wrong subcode (can't read). → Defective Spindle. Scratch and dirt on Disc. Intense vibration. The appropriate gain of the RF amp cannot be obtained. → Defective spindle. → Scratched or dirty disc. Severe vibration. Abnormal CD signals. → Blanc CD-R disc. Disc inserted upside down.
17	Electricity	Setup NG	AGC protection doesn't work, out of Focus soon. → Scratch on Disc/Severe dirt and vibration.
22	Disc	Impossible to play	There is no playable MP3 or WMA file present in a disc. → No MP3 or WMA file exists in a CD-ROM disc inserted.
23	Disc	File Format NG	Contents are stored in an incompatible file format. → The contents in a CD-ROM disc inserted are recorded in a file format other than ISO9660 Level-1 and 2.
30	Electricity	Search Time Out	Can't reach the target address. → Defective CRG/tracking, or scratch on Disc.
44	Disc	Impossible to play	There is no playable TRK No. present in a disc. → All TRK Nos. In a disc inserted are specified as a track which should be skipped, in the track skip information.
50	Mecha	Disc Load / Eject NG	Disc loading/ejection cannot be complete. → Foreign objects entered into the mechanism. Disc caught in between during loading/ejection.
A0	System	Power NG	Power supply (VD) isn't connected to the ground. → Defective SW transistor. Abnormal power (failed connector)

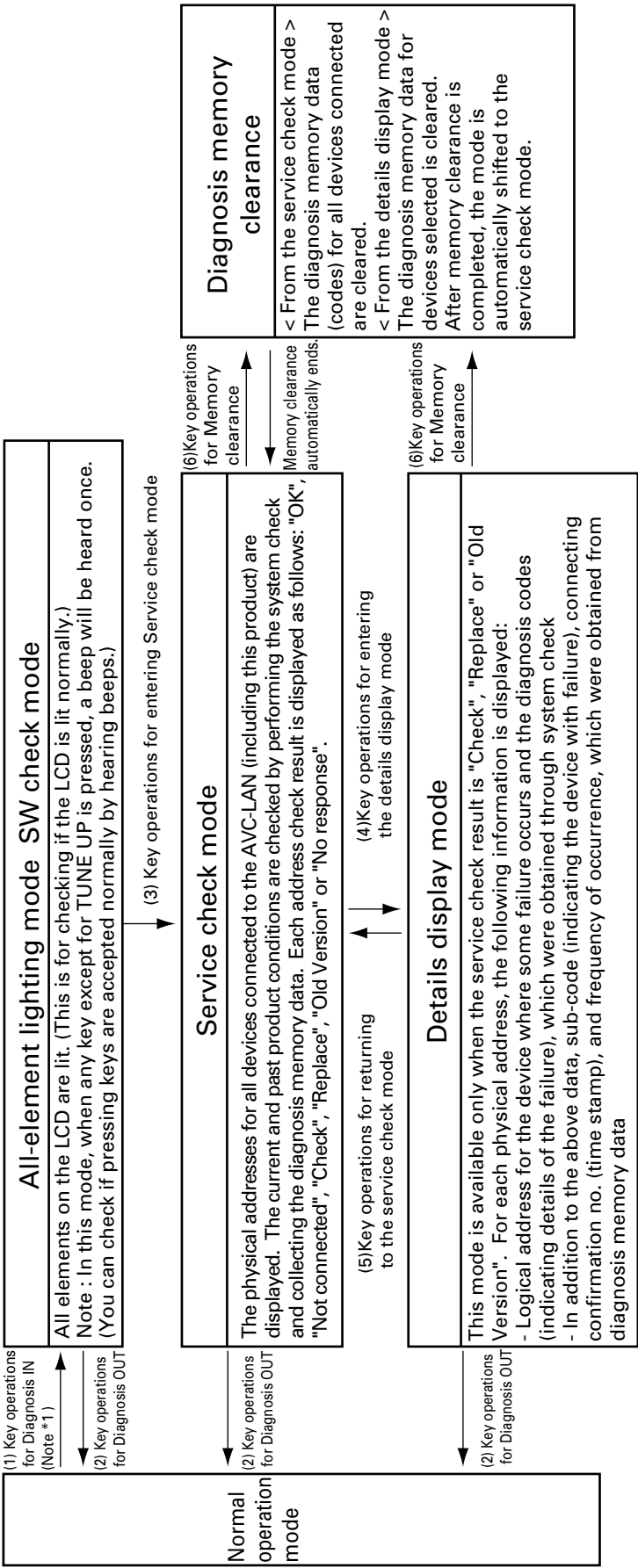
Note : Error doesn't display in mechanism only. (CD off causes mechanism off)

If TOC can't be read, error wouldn't occur, but mechanism still continues its operation.

The upper digits of error code is mainly classified by 3 kinds as follows:

1x: Setup related error, 3x: Search related error, Ax: Other errors.

●Operations and functions



●Key operations

(1) Diagnosis IN With three times of beep sound, the mode change operation completes.	While pressing the CH1 and CH6 buttons simultaneously, press the DISC button three times.
(2) Diagnosis OUT	Keep the DISC button pressed for 1.7 seconds or more and turn the ACC switch OFF.
(3) Entering the Service check mode. With a beep sound, the mode change completes.	Press the TUNE UP button.
(4) Entering the Details display mode.	Press the CH2 button.
(5) Returning to the service check mode.	Press the CH3 button.
(6) Clearing the Memory data	Keep the CH5 button pressed for 1.7 seconds or more.
Change the display (forward)	Press the TUNE UP button.
Change the display (backward)	Press the TUNE DOWN button.

Note *1: To enter the diagnosis IN mode, use the buttons on the head unit.

6.6 AVC-LAN DIAGNOSIS MODE

●Diagnosis mode display

Service check mode	Details display mode (only in case of "Replace", "Check", or "Old Version")
<p>After system check completes, the check results for the devices connected to the AVC-LAN are displayed in turn in order of physical address number as follows:</p> <ul style="list-style-type: none"> ◆"Physical address" ...The smallest physical address number is displayed first, whose check result will follow it. Ex. P190 Physical address number (radio cassette) The physical address is displayed. ◆"Check result" ...The check result is displayed. Ex. good Normal (OK) Replace EChn CHEC Old Old Version Details display mode ◆"Physical address" ...The next physical address number is displayed. ◆"Connecting confirmation no. (current)" ...The AVC-LAN time stamp is displayed. Ex. no01 The connecting confirmation number is displayed. The current connecting confirmation number (expressed in the hexadecimal number system by using 00 to FF) increases by one each time one minute passes. When 256 minutes pass, the indication returns to 00. 	<p>This mode is available only when the service check result is "Replace", "Check" or "Old Version". To select this mode, press the CH2 key.</p> <ul style="list-style-type: none"> ◆"Physical address (for selected devices)" The physical address number is displayed, whose check result details will follow it. Ex. P360 Physical address number (CD-CH) The detailed items depend on the data source. ◆"Diagnosis data source" The data was obtained from system check. Ex. SyS The data was obtained from system check. ◆"Logical address" The logical address number for the device with failure is displayed. Ex. 1L_63 Logical address number (CD-CH) The logical address is displayed. Serial number ◆"Diagnosis code" The diagnosis code indicates what problem occurs. Ex. 1d_45 Diagnosis code (abnormal EJECT) The diagnosis code is displayed. ◆"Connecting confirmation number (when some failure occurs)" Ex. no01 The connecting confirmation number (expressed in the hexadecimal number system by using 00 to FF) is displayed. The frequency of failures occurred Ex. 1c_15 The frequency of occurrence expressed in the decimal number system. The frequency of occurrence is displayed. <p>If there are two or more diagnosis codes, the diagnosis data display will continue.</p>

[illegible]

Diagnosis code table

Logical address name	Logical address	Diagnosis code	Diagnosis details
Communication control	01H	00	No diagnosis
		01	Abnormal reset
		10	Abnormal +B
		11	Abnormal ACC
		12	Abnormal MUTE
		13	Fuse broken
		20	Microcomputer - abnormal
		21	ROM - abnormal
		22	RAM - abnormal
		23	Bus - abnormal
		24	F-ROM - abnormal
		25	V-ROM - abnormal
		26	Gate allay abnormal
		27	Paint controller abnormal
		28	Backup memory abnormal
		29	Voice output controller abnormal
		2A	Internal power supply abnormal
		30	Sync signal abnormal (input)
		31	Sync signal abnormal (output)
		D0	ECU not connected
		D1	Transmission abnormal
		D2	Connecting confirmation: abnormal
		D4	Connecting confirmation: no response
		D5	Registered device data missing
		D6	(History of registered devices)
		D7	Master unavailable
		D8	Connecting confirmation: no response
		D9	Last mode abnormal
		DA	Command/order: no response
		DB	Mode status abnormal
		DC	Transmission fault
		DD	Master reset
		DE	Slave reset
		DF	Master abnormal
		E0	Registration completion acknowledgement error
		E1	Voice processor ON abnormal
		E2	ON/OFF command or parameter abnormal
		E3	Registration command transmission
		E4	Multiple frames intermit
		FF	Diagnosis - no response

Logical address name	Logical address	Diagnosis code	Diagnosis details
Radio	60H	10	AM tuner PLL unlocked
		11	FM tuner PLL unlocked
		40	No antenna connected
		41	Antenna power supply abnormal
		42	Tuner power supply abnormal
		43	AM tuner abnormal
		44	FM tuner abnormal
		45	SW tuner abnormal
		10	TV tuner PLL unlocked
		11	FRONTEND abnormal
TV tuner	40H	40	TV divergence shifting error
		41	TV - no reception
		42	VNR screen error
		43	No antenna connected
		44	Antenna power supply abnormal
		45	SEL + B current - small
		46	SEL + B current - large
		10	Belt broken
		40	Mechanical failure or cassette broken
		41	EJECT failure
Cassette tape	61H	42	TAPE jamming
		43	Dirty head
		44	Mech power supply abnormal
		10	CD Mech abnormal
		11	CD loading/unloading abnormal
		12	CD lead-in abnormal
		40	No disc loaded
		41	Incorrect disc
		42	Disc unreadable
		43	CD-ROM abnormal
CD	43H 62H 63H	44	CD abnormal
		45	EJECT abnormal
		46	Scratches or non-recorded side
		47	CD high temperature detected
		48	Excessive current detected
		50	Tray IN/OUT abnormal
		51	Elevator abnormal
		52	Clamp abnormal
		10	MD mech abnormal
		11	MD IN/OUT abnormal
MD-CH	64H 65H	12	MD lead-in abnormal
		40	No disc loaded
		41	Incorrect disc
		42	Disc unreadable
		43	MD-ROM abnormal
		44	MD abnormal
		45	EJECT error
		46	Scratches or non-recorded side
		47	MD high temperature detected
		48	Excessive current detected
		50	Tray IN/OUT abnormal
		51	Elevator abnormal
		52	Clamp abnormal

Logical address name	Logical address	Diagnosis code	Diagnosis details
Navigation /GPS	58H 80H	10	Gyroscope abnormal
		11	GPS receiver abnormal
		12	RTC abnormal
		13	SS section abnormal
		14	No Time updating
		15	TCXO abnormal
		16	PLL lock abnormal
		40	GPS antenna abnormal
		41	GPS antenna power supply abnormal
		42	Map disc reading abnormal
		43	SPD signal abnormal
		44	Player abnormal
		45	High temperature abnormal
		41	Antenna power supply abnormal
		45	Radio wave beacon - no antenna connected
		46	Optical beacon - no antenna connected
		47	No FM antenna connected
		4A	FM receiver abnormal
		4B	Radio wave beacon abnormal
		4C	Optical beacon abnormal
Voice control	88H	40	Voice-control activation SW abnormal
		41	Voice-control Microphone abnormal
Extended communication	02H	40	Multi-CD-CH (optical cable) abnormal
		41	Multi-CD-CH (optical cable) not connected
		42	Multi-CD-CH (CarNet) abnormal
		43	Multi-CD-CH (CarNet) not connected
		50	HIT64 communication not connected
		51	HIT64 communication abnormal
		52	HIT64 BRQ disconnection
		53	HIT64 BRQ short-circuit
		54	HIT64 disconnection
		55	CarNet communication not connected
Information display/front monitors	32H 34H	56	CarNet communication abnormal
		57	CarNet periodical communication abnormal
		10	Video circuit abnormal
		11	Back light abnormal (with no current)
		12	Back light abnormal (with excessive current)
		13	Panel open/close mechanical operation abnormal
		40	Front seat monitor abnormal
		41	Heater abnormal
		10	Panel SW abnormal
		11	Touch SW failure
SW, Audio SW, SW shifting, Command SW	21H 23H 24H 25H		
XM tuner	C0H	11	PLL Unlock
		12	CODEC Communication Error
		13	SSDEC Communication Error
		14	SSDEC No Response Error
		15	NVM Error
		16	CAP Error
		40	ANTENNA No Contact
		41	ANTENNA Short

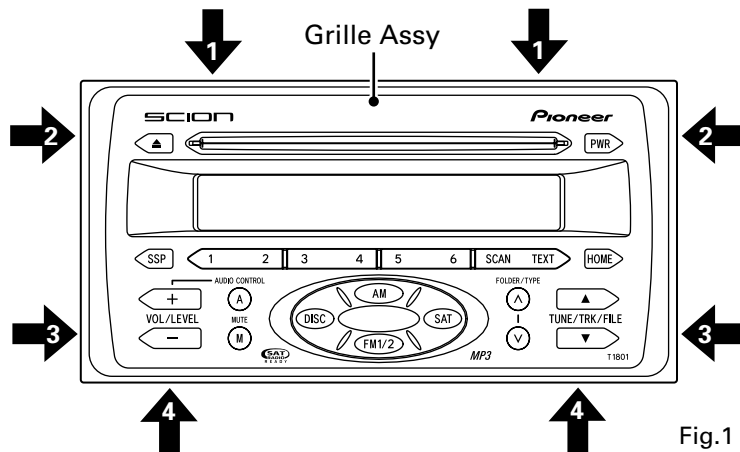
7. GENERAL INFORMATION

7.1 DIAGNOSIS

7.1.1 DISASSEMBLY

● Removing the Grille Assy (Fig.1)

- 1** Release the two latches.
- 2** Release the two latches.
- 3** Release the two latches.
- 4** Release the two latches and then remove the Grille Assy.



● Removing the Case (not shown)

1. Remove the two screws and then remove the Case.

● Removing the CD Mechanism Module (not shown)

1. Remove the four screws.
2. Disconnect the connector and then remove the CD Mechanism Module.

● Removing the Chassis (Fig.2)

- ➡ **1** Remove the two screws.
- ➡ **2** Remove the three screws and then remove the Heat Sink.
- ➡ **3** Remove the five screws and then remove the Chassis.

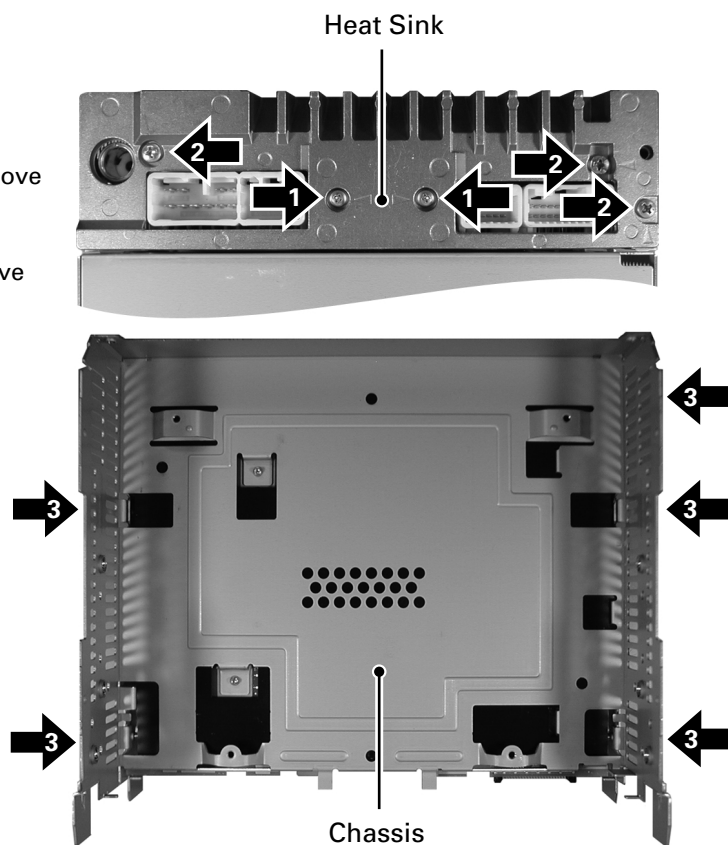


Fig.2

● Removing the Main Unit (Fig.3)

- ➡ **1** Straighten the tabs at five locations indicated.
- ➡ **2** Remove the two screws and then remove the Main Unit.

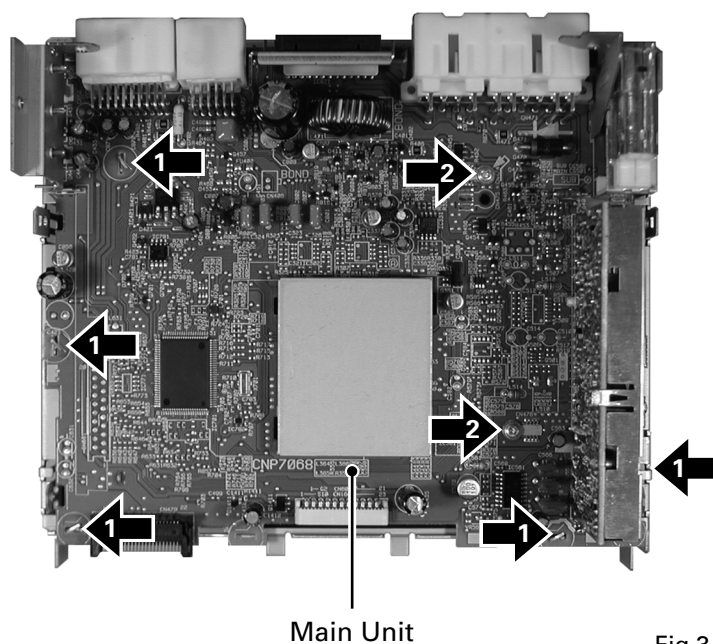
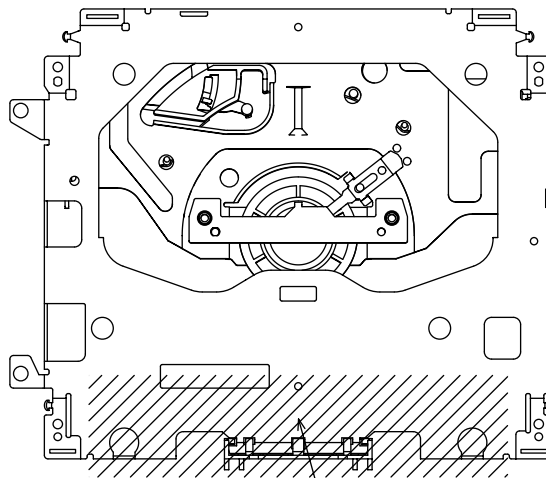


Fig.3

● How to hold the Mechanism Unit

1. Hold the top and bottom frame.
2. Do not squeeze top frame's front portion too tight, because it is fragile.

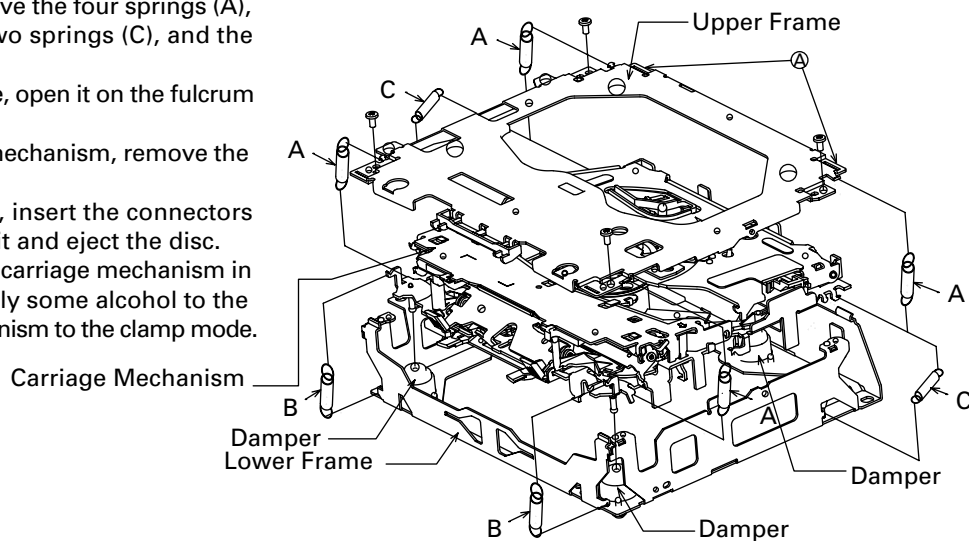


Do not squeeze.

● Removing the Upper and Lower Frames

1. With a disc clamped, remove the four springs (A), the two springs (B), the two springs (C), and the four screws.
2. To remove the upper frame, open it on the fulcrum A.
3. While lifting the carriage mechanism, remove the three dampers.
4. With the frames removed, insert the connectors coming from the main unit and eject the disc.

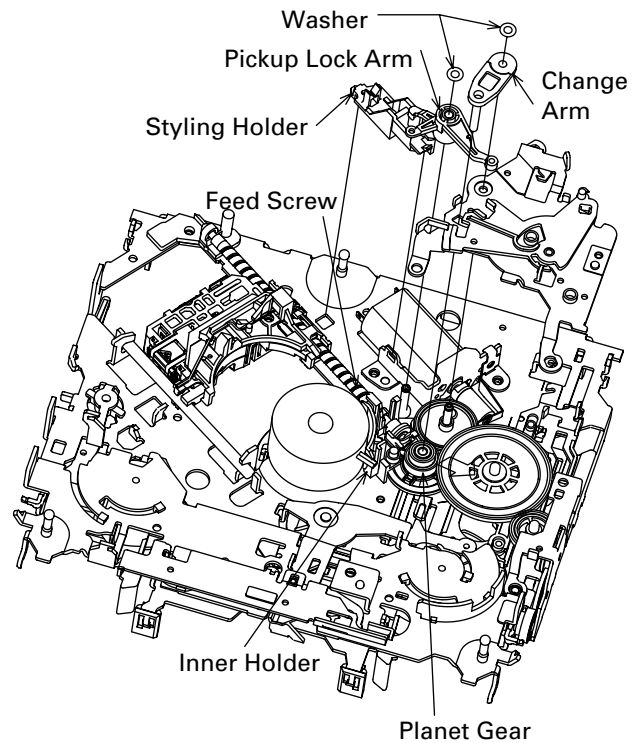
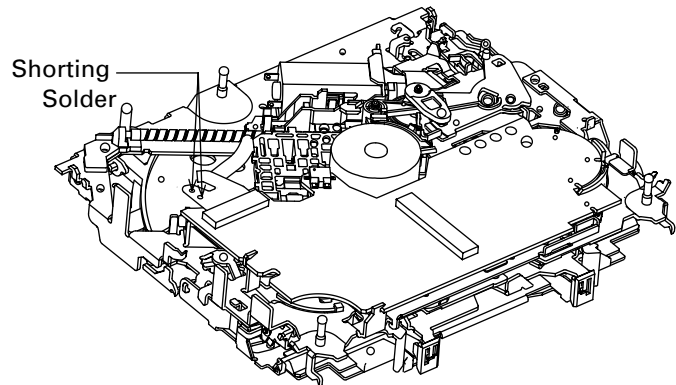
Caution: Before installing the carriage mechanism in the frames, be sure to apply some alcohol to the dampers and set the mechanism to the clamp mode.



● Removing the Pickup Unit

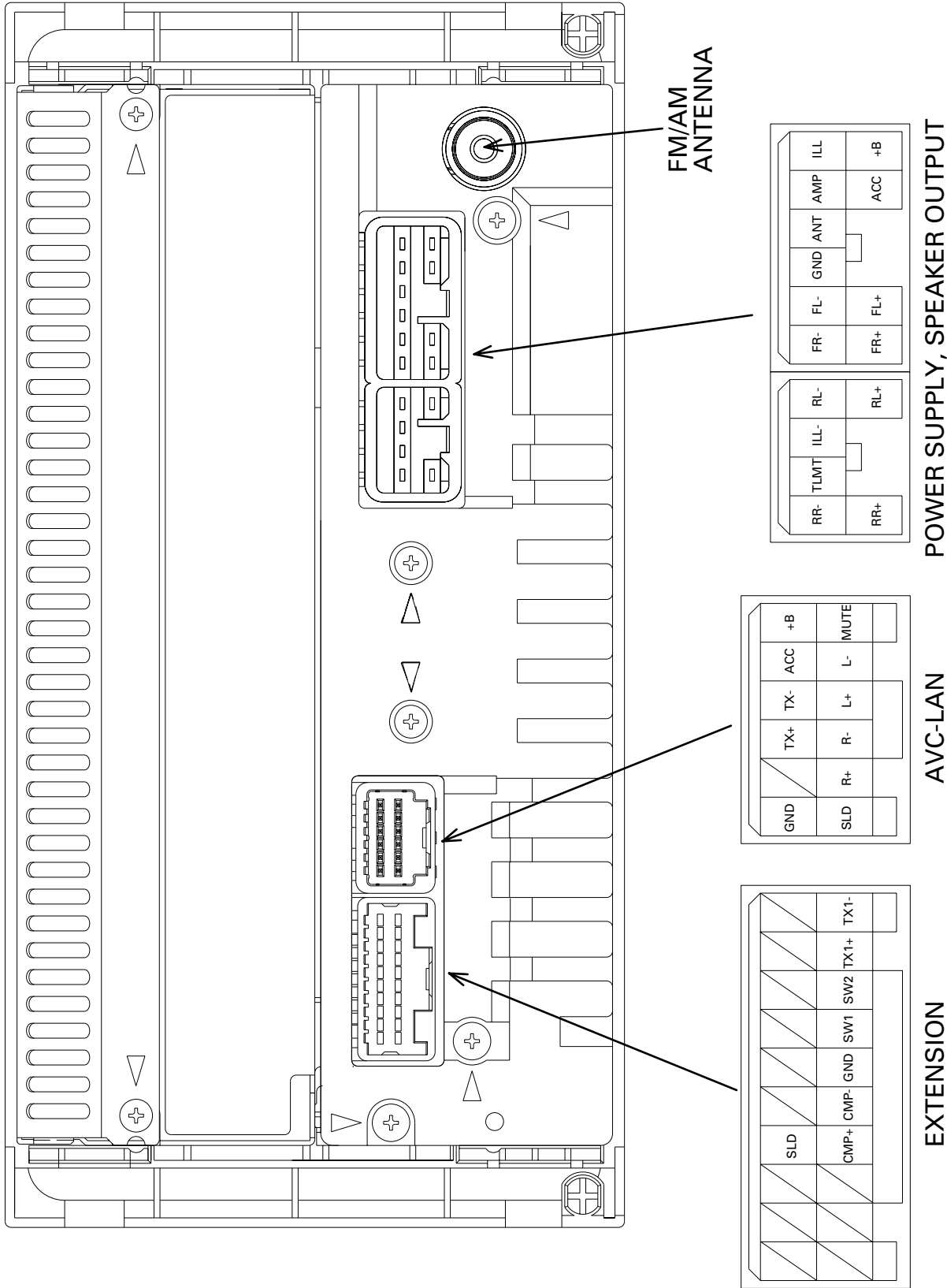
1. Apply shorting solder to the Pickup flexible cable. Disconnect the cable.
2. Set the mechanism to the clamp mode.
3. Remove the lead wires from the inner holder.
4. Remove the two washers, styling holder, change arm, and pickup lock arm.
5. While releasing from the hook of the inner holder, lift the end of the feed screw.

Caution: In assembling, move the planet gear to the load/eject position before setting the feed screw in the inner holder.



7.1.2 CONNECTOR FUNCTION DESCRIPTION

A
B
C
D
E
F



7.2 PARTS

7.2.1 IC

● Pin Functions (PD5861A)

Pin No.	Pin Name	I/O	Function and Operation
1	PDO	O	Tuner : Data output
2	PCK	O	Tuner : Serial clock output
3	BLDA	O	Dimmer control DA output for back light
4	LCE	O	LCD driver : Chip enable output
5	LDO	O	LCD driver : Data output
6	LDI	I	LCD driver : Data input
7	LCK	O	LCD driver : Clock output
8	BYTE	I	GND
9	CNVSS	I	GND
10	LRST	O	LCD driver : Reset output
11	LOFF	O	LCD driver : Off output
12	RESET	I	Reset input
13	XOUT	O	Crystal oscillating element connection pin
14	VSS		GND
15	XIN	I	Crystal oscillating element connection pin
16	VCC		Power supply terminal
17	NMI	I	Not used
18	ISEN	I	Illumination power sense input
19	BSEN	I	Back up power sense input
20	ASEN	I	ACC power sense input
21	RX2	I	IP-BUS : Data input
22	PCE2	O	Tuner : Chip enable 2 output
23	PCE1	O	Tuner : Chip enable 1 output
24	BEEP	O	Beep tone output
25	SD	I	Tuner : SD input
26	ST	I	Tuner : FM stereo input
27	LOCL	O	Local L output
28	ILLPWM	O	Phase width modulation output for illumination dimmer control
29	RX1	I	IP-BUS : Data input
30	TX	O	IP-BUS : Data output
31	BSO	O	P-BUS : Serial data output
32	BSI	I	P-BUS : Serial data input
33	BSCK	O	P-BUS : Serial clock output
34	DSPOK	I	DSP : Interface monitor input
35	DSPDO	O	DSP : Data output
36	DSPDI	I	DSP : Data input
37	DSPCK	O	DSP : Serial clock output
38	DSPERR	O	DSP : Error detect input
39	DSPRST	O	DSP : Reset output
40	DSPCS	O	DSP : Chip select output
41	DSPACK	I	DSP : Acknowledge input
42	SYSMUTE	O	System mute output
43	TELMUTE	I	Telephone mute input
44	FMPW	O	FM power supply control output
45	AMPW	O	AM power supply control output
46	LANMUTE	I	AVC-LAN mute input
47	IPPW	O	IP-BUS : Power supply control output for IP BUS interface IC
48	ADIN	O	ADIM signal output
49	SYSPW	O	System power supply control output
50	NC		Not used
51	FANPW	O	Not used
52	KEYILL	O	Key illumination control output
53-58	NC		Not used
59	ROMDATA	I/O	ROM correction data input / output
60	ROMCLK	O	ROM correction clock output
61	ROMCS	O	ROM correction chip select output
62	VCC		Power supply terminal

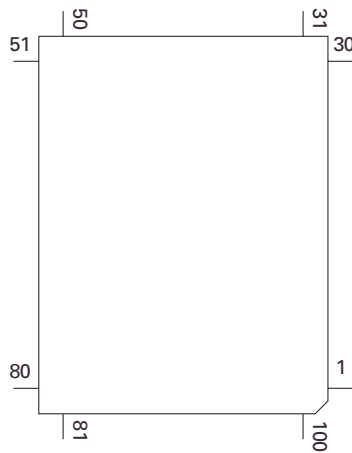
A

Pin No.	Pin Name	I/O	Function and Operation
63	POWER	I	POWER key input
64	VSS		GND
65-72	NC		Not used
73	SWVDD	O	Switched VDD control output
74	CDEJ	I	CD eject key sense input
75-80	NC		Not used
81	TESTIN	I	Test program mode input
82	BSREQ	I	P-BUS : Service request input
83	BRXEN	I	P-BUS : Reception enable input
84	BRST	I	P-BUS : Reset input
85	DDSTBY	O	LED driver : Stand-by input
86	DDDT	O	LED driver : Data output
87	DDCK	O	LED driver : Clock output
88	DDST	O	LED driver : Strobe input
89	DMI	I	Rheostat signal input
90	NC		Not used
91	SRSSW1	I	Steering switch 1 input
92,93	NC		Not used
94	TEMP		Temperature detect input
95	SRSSW2	I	Steering switch 2 input
96	AVSS		GND
97	SL	I	Tuner : SD level input
98	VREF	I	A/D converter reference voltage
99	AVCC		Analog power supply
100	PDI	I	Tuner : Data input

B

C

* PD5861A

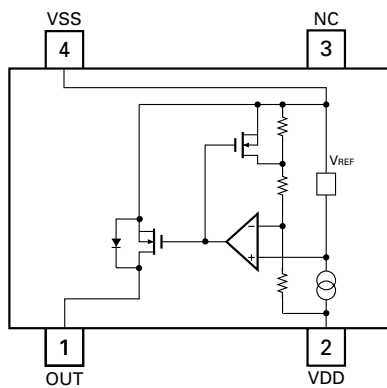


IC's marked by * are MOS type.

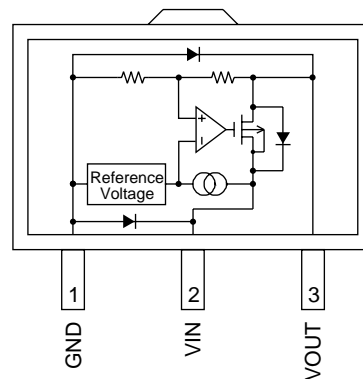
Be careful in handling them because they are very liable to be damaged by electrostatic induction.

D

* S-80835CNNB-B8U



* S-812C56AUA-C3K



E

F

Pin Function (PM2010A)

Pin No.	Pin Name	I/O	Function and Operation
1	XI	I	Crystal oscillator connection or clock input
2	XO	O	Crystal oscillator connection
3	VDX		Crystal oscillator power supply
4	GNDA1		DAC1GND
5	AOUT1	O	DAC1 volume output
6	DACO1	O	DAC1 output
7	VLI1	I	DAC1 volume input
8	VDD12		DAC1, DAC2 power supply
9	VLI2	I	DAC2 volume input
10	DACO2	O	DAC2 output
11	AOUT2	O	DAC2 volume output
12, 13	GNDA2, 3		DAC2, 3GND
14	AOUT3	O	DAC3 volume output
15	DACO3	O	DAC3 output
16	VLI3	I	DAC3 volume input
17	VREF		DAC operation amp reference potential connection pin
18	VDD34		DAC3, DAC4 power supply
19	VLI4	I	DAC4 volume input
20	DACO4	O	DAC4 output
21	AOUT4	O	DAC4 volume output
22, 23	GNDA4, 5		DAC4, 5GND
24	AOUT5	O	DAC5 volume output
25	DACO5	O	DAC5 output
26	VLI5	I	DAC5 volume input
27	VDD56		DAC5, DAC6 power supply
28	VLI6	I	DAC6 volume input
29	DACO6	O	DAC6 output
30	AOUT6	O	DAC6 volume output
31	GNDA6		DAC6GND
32	GND		Digital section GND
33-36	TEST0-3	I	Test setting 0-3
37	VDD		Digital section VDD
38-41	TP0-3	O	Test port 0-3
42	CKI0	I	DAC clock input 0
43	TP4	O	Test port 4
44	CKI1	I	DAC clock input 1
45	TP5	O	Test port 5
46	CKO0	O	General-purpose clock output 0
47	TP6	O	Test port 6
48	CKO1	O	General-purpose clock output 1
49	VDD		Digital section VDD
50	CKO2	O	Clock output 2
51, 52	ELRO0, 1	I	LRCK input for DOUT0, 1
53, 54	EBCO0, 1	I	BCK input for DOUT0, 1
55, 56	DOUT0, 1	O	Digital serial output 0, 1
57	GND		Digital section GND
58-60	DIN0-2	I	Digital serial input 0-2
61, 62	EBCI0, 1	I	BCK input for DIN0, 1
63, 64	ELRI0, 1	I	LRCK input for DIN0, 1
65	GND		Digital section GND
66	I2CS	I	Microcomputer I/F I2C select
67	\overline{CS}	I	Microcomputer I/F chip select
68	IFCK	I	Microcomputer I/F communication clock input
69	IFDI	I	Microcomputer I/F data input
70	IFDO	O	Microcomputer I/F data output
71	ACK	O	Microcomputer I/F acknowledge output
72	IFOK	O	Microcomputer I/F condition monitor output
73	\overline{ERR}	O	Overrun monitor output
74	BT	I	Boot setting

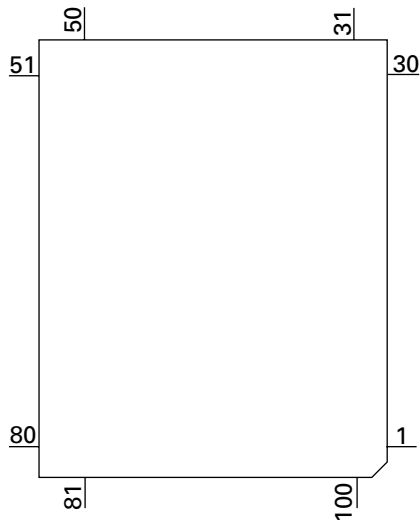
A

Pin No.	Pin Name	I/O	Function and Operation
75	RST	I	Reset
76	VDD		Digital section VDD
77	VDAM		ADC microphone input power supply
78	VARM		ADC microphone input operation amp reference potential
79	MIN	I	ADC microphone input
80	GNDM		ADC microphone input GND
81-86	LIN-1-6	I	ADC Lch input 1-6
87-92	RIN-1-6	I	ADC Rch input 1-6
93	GNDAL		ADC Lch input GND
94	OUTL	O	ADC Lch selector output
95	VRAL		ADC Lch operation amp reference potential
96	VDA		ADC input power supply
97	VRAR		ADC Rch operation amp reference potential
98	OUTR	O	ADC Rch selector output
99	GNDAR		ADC Rch input GND
100	GNDX		Crystal oscillator section GND

B

C

* PM2010A



D

E

F

Pin Functions (PE5370B)

Pin No.	Pin Name	I/O	Format	Function and Operation
1	BSO	O	C	P-Bus serial data output
2	BSCK	I/O	/C	P-Bus serial clock input/output
3-5	NC			Not used (Open)
6	EVDD			E power supply Positive power supply
7	EVSS			E power supply GND
8-10	NC			Not used (Open)
11-13	MEMO0-2	O	C	Shock proof memory buffer quantity output 0-2
14-16	NC			Not used (Open)
17	ADENA	O	C	A/D reference voltage supply control output
18	IC/VPP			IC : VSS direct connection/VPP : Pull-down
19	BRXEN	I/O	/C	P-Bus reception is possible
20	BSRQ	I/O	/C	P-Bus service request demand
21	XTALEN1	O	C	CD LSI 16.9344MHz oscillation permission output
22	NC			Not used (Open)
23	XRST	O	C	CD LSI reset control output
24	VDCONT	O	C	VD power supply control output
25	CD3VON	O	C	CD +3.3V power supply control output
26	CONT	O	C	Servo driver power supply control output
27	XWAIT	I		CD LSI wait control signal input
28	LOEJ	O	C	The direction change output of LOAD/EJECT
29	CLCONT	O	C	Driver input change output
30	CDMUTE	O	C	CD mute control output
31	RESET	I		System reset input
32	XT1	I		Connected to the oscillator for subclock (connected to VSS via the resistor)
33	XT2			Connected to the oscillator for subclock (Open)
34	REGC			Connected to the capacity stabilizing output of the regulator (an electrolytic capacitor of about 1μF)
35	X2			Oscillator connection for mainclock
36	X1	I		Oscillator connection for mainclock
37	VSS			GND
38	VDD			Positive power supply (5V)
39	CLKOUT	O	C	Internal system clock output (Open)
40	XWRITE	O		CD LSI write control signal output
41, 42	NC			Not used (Open)
43	XREAD	O		CD LSI read control signal output
44	XASTB	O		CD LSI address strobe output
45	LOCK	I		Spindle lock input
46	NC			Not used (Open)
47-54	AD0-7	I/O	/C	Address/Data bus 0-7
55	BVDD			B power supply Positive power supply (3.3V)
56	BVSS			B power supply GND
57-64	AD8-15	I/O	/C	Address/Data bus 8-15
65	XCS	O	C	CD LSI chip selection output
66	NC			Not used (Open)
67, 68	DBBWRDY0, 1	I		Connected to AVDD or AVSS via the resistor
69, 70	DBBRRDY0, 1	I		Connected to AVDD or AVSS via the resistor
71	AVDD			A power supply Positive power supply (5V)
72	AVSS			A power supply GND
73	AVREF			The reference voltage input for A/D converter
74	VDSSENS			VD power supply short sense input
75	DSCSNS			Disc state sense input
76	TEMP			Temperature information sense input
77	HOME	I		Home SW sense input
78	CSSENS	I		Flap closing sense input
79	RFOKIN	I		RFOK input chatter count input
80-82	NC			Connected to AVDD or AVSS via the resistor
83	WMAARI	I		Connected to AVDD or AVSS via the resistor
84	TYPE_A/D	I		Connected to AVDD or AVSS via the resistor
85	TESTIN	I		Chip check test program starting input

A

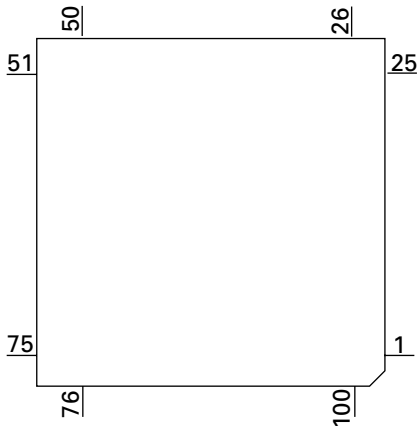
Pin No.	Pin Name	I/O	Format	Function and Operation
86	NC			Connected to EVDD or EVSS via the resistor
87	XINT			CD LSI interruption signal input
88	WINT			Connected to EVDD or EVSS via the resistor
89	BRST	I		P-Bus reset input
90	EJSW	I		Eject key input
91	4/16	I	C	DRAM 4M/16M selection (L : 4M, H : 16M)
92	NC			Open
93	CLAMP	I	C	CLAMP SW sense input
94	ROMDATA	I/O	/C	E2PROM data input/output
95	ROMCS	O	C	E2PROM chip selection output
96	ROMCK	O	C	E2PROM clock output
97	FRXD	I		For flash rewriting (received signal)
98	FTXD	O	C	For flash rewriting (transmitted signal)
99	NC			Open
100	BSI	I		P-Bus serial data input

B

* PE5370B

Format	Meaning
C	CMOS

C



D

E

F

Pin Functions (UPD63760GJ)

Pin No.	Pin Name	I/O	Function and Operation
1	R.GND		GND for DRAM I/F
2	RST	I	Input of reset
3-7	AB12-8	I	Address bus 12-8 from the microcomputer
8-15	AD7-0	I/O	Address/data bus 7-0 to the microcomputer
16	CS	I	Chip selection
17	ASTB	I	Address strobe
18	READ	I	Control signals (read)
19	WRITE	I	Control signals (write)
20	WAIT	O	Control signals (wait)
21	INTQ		Interruption signals to the external microcomputer
22	IFMODE	I	Switching between the data buses (16bit/8bit)
23	D.VDD		Power supply for digital circuits
24	XTALEN1	I	Permission to oscillate 16.9344MHz
25	XTALEN2	I	Permission to oscillate 24.576MHz
26	DA.VDD		Power supply for DAC
27	ROUT	O	Output of audio for the right channel
28	DA.GND		GND for DAC
29	R+	O	Output of the right channel audio PWM
30	R-	O	Output of the right channel audio PWM
31	REGC		Connected to the capacitor for band gap
32	L-	O	Output of the left channel audio PWM
33	L+	O	Output of the left channel audio PWM
34	DA.GND		GND for DAC
35	LOUT	O	Output of audio for the left channel
36	DA.VDD		Power supply for DAC
37	X.VDD		Power supply for the crystal oscillator
38	XTAL1		Connected to the crystal oscillator (16.9344MHz)
39	XTAL1		Connected to the crystal oscillator (16.9344MHz)
40, 41	X.GND		Ground for the crystal oscillator
42	XTAL2		Connected to the crystal oscillator (24.576MHz)
43	XTAL2		Connected to the crystal oscillator (24.576MHz)
44	X.VDD		Power supply for the crystal oscillator
45	D.GND		GND for digital circuits
46	DIN	I	Input of audio data
47	DOUT	O	Output of audio data
48	SCKIN	I	Clock input for audio data
49	SCKO	O	Clock output for audio data
50	LRCKIN	I	Input of LRCK for audio data
51	LRCK	O	Output LRCK for audio data
52	TESTX	O	Output for tests
53	RFOK	O	Output of RFOK
54	C16M	O	Output of 16.9344MHz
55	TESTEN	I	Connected to GND
56	TEST4	I	Connected to GND
57	D.VDD		Power supply for digital circuits
58	RFCK/HOLD	O	Output of RFCK/HOLD signal
59	WFCK/MIRR	O	Output of WFCK/MIRR signal
60	PLCK	O	Output of PLCK
61	LOCK	O	Output of LOCK
62	C1D1	O	Information on error correction
63	C1D2	O	Information on error correction
64	C2D1(RMUTE)	O	Information on error correction (mute for Rch)
65	C2D2(LMUTE)	O	Information on error correction (mute for Lch)
66	C2D3	O	Information on error correction
67	D.GND		Ground for digital circuits
68	RAS	O	Output of DRAM RAS
69	CAS0	O	Output of DRAM Lower CAS
70	CAS1	O	Output of DRAM Upper CAS
71	WE	O	Output of DRAM WE
72	OE	O	Output of DRAM OE

A

Pin No.	Pin Name	I/O	Function and Operation
73-88	RDB0-15	I/O	Input/output of DRAM Data0-15
89	D.GND		Ground for digital circuits
90-99	RA0-9	O	Output of DRAM Address0-9
100	D.VDD		Power supply for digital circuits
101-104	TEST0-3	I	Connected to GND
105	FD	O	Output of focus drive PWM
106	TD	O	Output of tracking drive PWM
107	SD	O	Output of thread drive PWM
108	MD	O	Output of spindle drive PWM
109	A.VDD		Power supply for the analog system
110	ATEST	O	Analog tests
111	EFM	O	Output of EFM signals
112	ASY	I	Input of asymmetry
113	C3T		Connection to the capacitor for detecting 3T
114	A.GND		Ground for the analog system
115	RFI	I	Input of RF
116	AGCO	O	Output of RF
117	AGCI	I	Input of AGC
118	RFO	O	Output of RF(AGC)
119, 120	EQ2, 1		Equalizer 2, 1
121	RF2-	I	Reversal input of RF2
122	RF-	I	Reversal input of RF
123	A.GND		Ground for the analog system
124	A	I	Input of A
125	C	I	Input of C
126	B	I	Input of B
127	D	I	Input of D
128	F	I	Input of F
129	E	I	Input of E
130	A.VDD		Power supply for the analog system
131	REFOUT	O	Output of reference voltage
132	REFC		Connected to the capacitor for output of REFOUT
133	FE-	I	Reversal input of FE
134	FEO	O	Output of FE
135	TE-	I	Reversal input of TE
136	TEO	O	Output of TE
137	TE2	O	TE2
138	TEC	I	TEC
139	A.GND		Ground for the analog system
140	LDREGO	O	Output of REG voltage for APC
141	PD	I	Input of PD
142	LD	O	Output of LD
143	PN	I	Assignment of pickup polarity
144	A.VDD		Power supply for the analog system

B

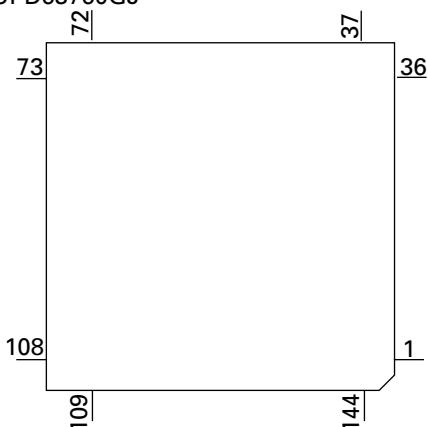
C

D

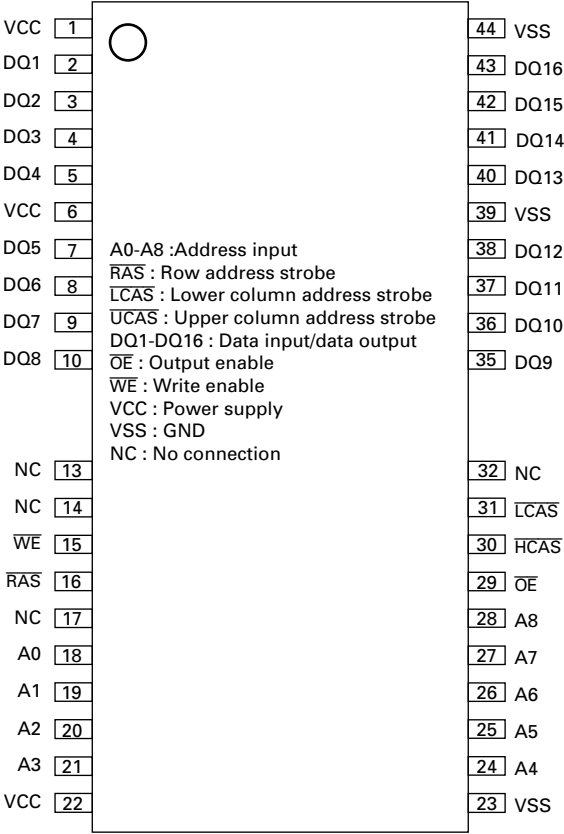
E

F

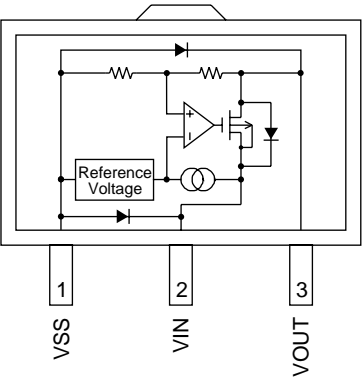
* UPD63760GJ



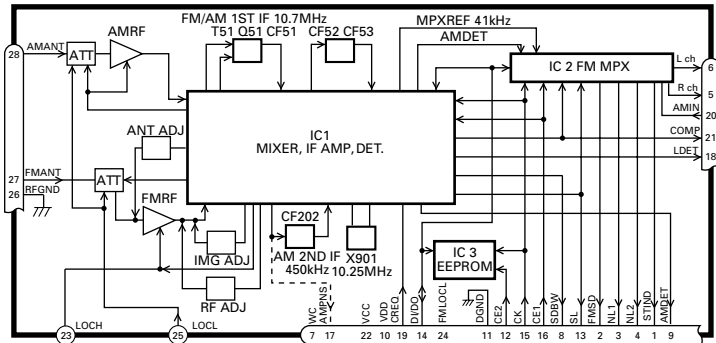
* MSM51V4265EP-70TS



* S-812C33AUA-C2N



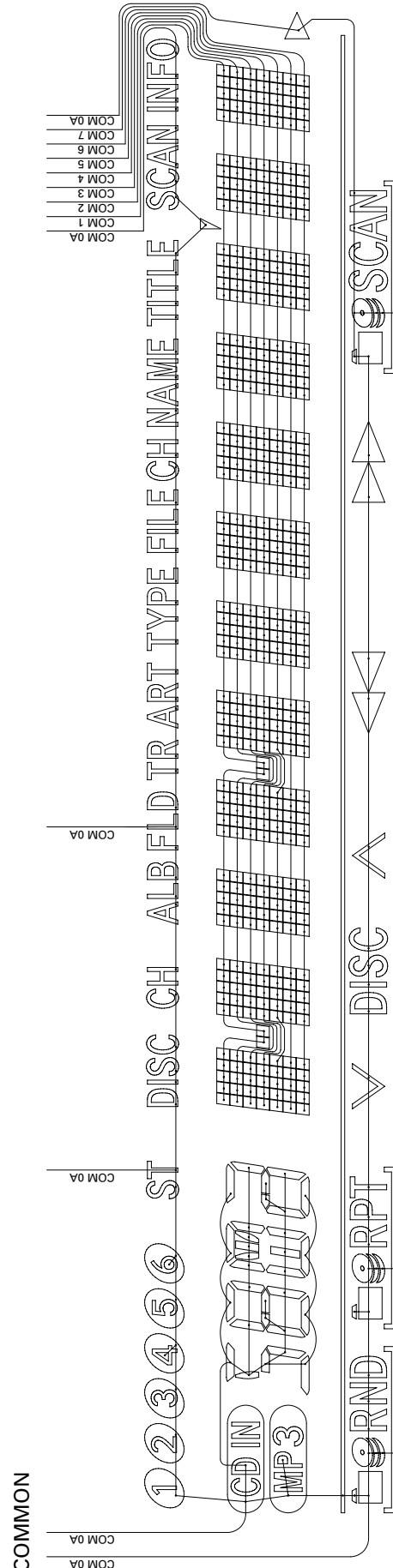
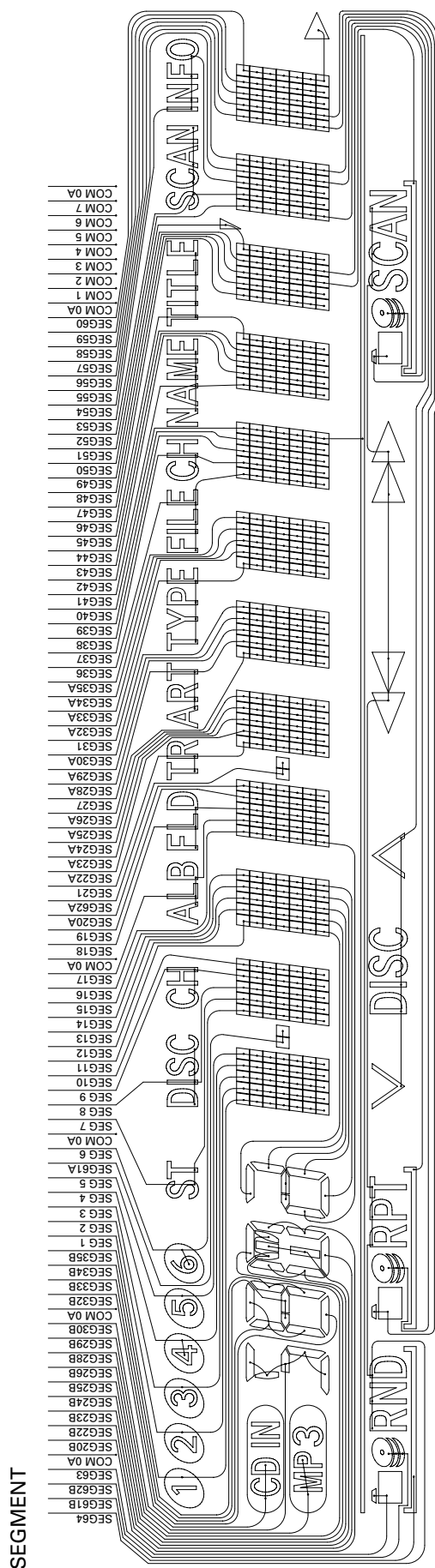
● FM/AM Tuner Unit



No.	Symbol	I/O	Explain
1	STIND	O	stereo indicator "Low" when the FM stereo signals are received. To be pulled up to the "VDD" at 47kΩ.
2	FMSD	O	FM station detector "High" when signals are received. To be pulled up to the "VDD" at 47kΩ Meanwhile, 10kΩ should be used when taking diver FIX trigger from here and "High: 0.9VDD or more" and "Low: 250mV or less". (Should satisfy the diver IC specifications)
3	NL1	O	noise level-1 "High" when noise is received. Output for the RDS. GND at 47kΩ//1,800pF.
4	NL2	O	noise level-2 "High" when noise is received. Output for the RDS. GND at 36kΩ//330pF.
5	Rch	O	R channel output FM stereo "R-ch" signal output or AM audio output. Add the specified de-emphasis constant.
6	Lch	O	L channel output FM stereo "L-ch" signal output or AM audio output. Add the specified de-emphasis constant.
7	WC		write control EEPROM write control. Writing permissible at "Low". Normally open.
8	SDBW	O	SD bandwidth SD bandwidth signal output. For detection of detuning data for the RDS.
9	AMDET	O	AM detector output AM detector output. r out < 100Ω
10	VDD		power supply Power supply pin for the digital section. DC 5V +/- 0.25V. Be careful about overlapping noise in the logic section.
11	DGND		digital ground Grounding for the digital section.
12	CE2	I	chip enable-2 EEPROM chip enable. Active a "Low" To be pulled up to the "VDD" at 47kΩ
13	SL	I/O	signal level Received FM/AM signal level (strength) output. Connect the specified load resistor and capacitor (10k Ω+ 39k Ω//4,700pF)
14	DI/DO	I/O	data input/ data output Data input/Data output To be pulled up to the "VDD" at 47kΩ
15	CK	I	clock Clock input To be pulled up to the "VDD" at 47kΩ
16	CE1	I	chip enable-1 AF-RF chip enable. Active at "High" To be grounded at 47kΩ
17	AMPNS	O	AM PNS IF signal IF signal output for AM PNS circuit.
18	LDET	O	lock detector Active at "Low". To be pulled up to the "VDD" at 47kΩ
19	CREQ	I	current request Active at "Low". To be grounded at 47kΩ
20	AMINI		AM audio input The frequency response and the level are set by connecting an external CR network with terminal AMIN as terminal AMDET. r in = 50kΩ
21	COMP	O	composite signal FM composite signal output. r out < 100Ω
22	VCC		power supply Analog section power supply pin.DC 8.4V +/- 0.3V
23	LOCH	I	local high FM local high pin. When seeking local high, apply 5V together with "LOCL".
24	FMLOCL	I	FM local low FM local low pin. When seeking local low, apply 5V to the base of the NPN transistor with which the specified resistor is being connected to the emitter. Keep it open in case of ordinary marketed models.
25	LOCL	I	local low FM/AM local low pin. When seeking local low, apply 5V to the base of the NPN transistor.Since this pin is exclusive for AM when the FMLOCL is in use, do not drive it under FM.
26	RFGND		RF ground Grounding for the antenna section.
27	FMANT	I	FM antenna input FM antenna input. 75Ω. Surge absorber (DSP-201M-S00B) is necessary.
28	AMANT	I	AM antenna input AM antenna input. High impedance. Connect to the antenna through an L (LAU type) of 4.7μH.To cope with the power transmission line hums, insert a series circuit consisting of an L (a coil of about 100mH) + R (a resistor of 470 Ω to 2.2kΩ) between the GND.

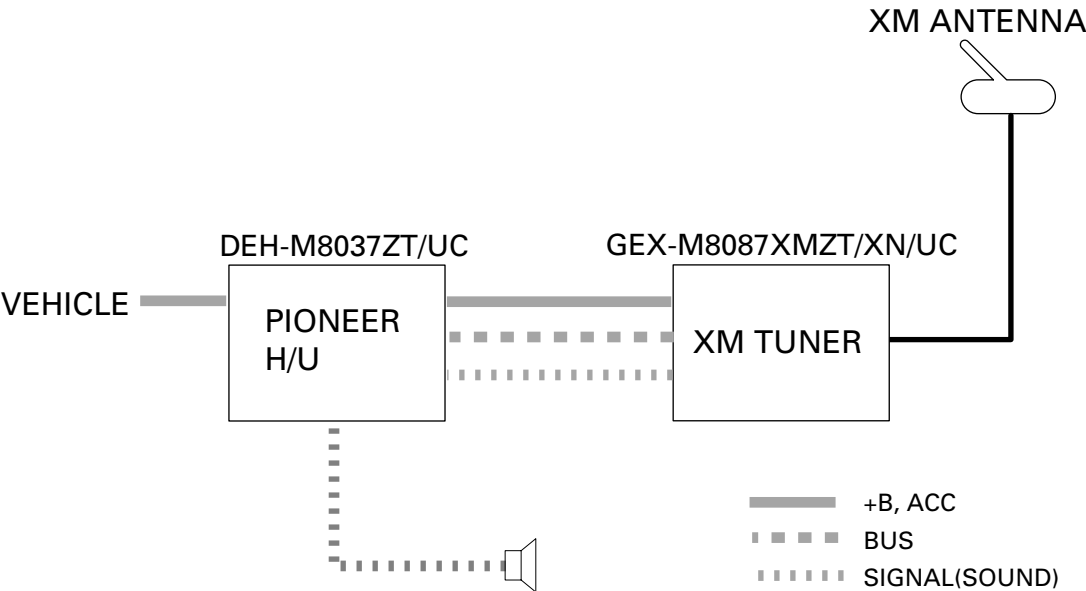
7.2.2 DISPLAY

● LCD(CAW1809)

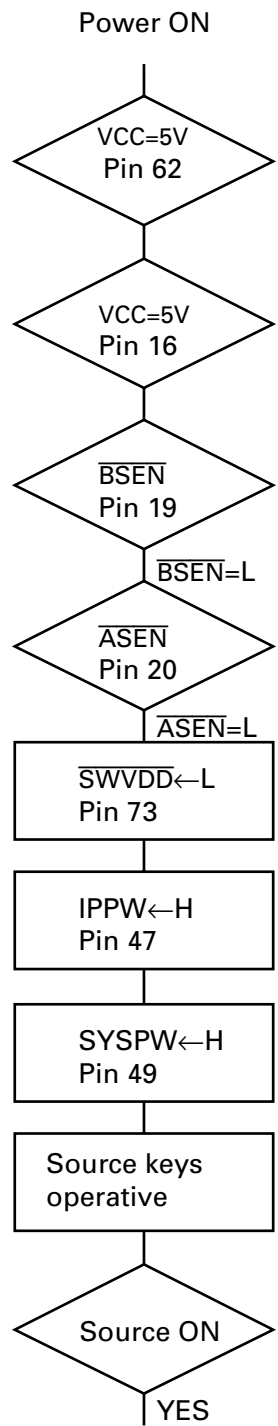


7.3 EXPLANATION

7.3.1 SYSTEM BLOCK DIAGRAM



7.3.2 OPERATIONAL FLOW CHART



Completes power-on operation.
(After that, proceed to each source operation)

A 7.4 CLEANING



Before shipping out the product, be sure to clean the following portions by using the prescribed cleaning tools:

Portions to be cleaned	Cleaning tools
CD pickup lenses	Cleaning liquid : GEM1004 Cleaning paper : GED-008

B

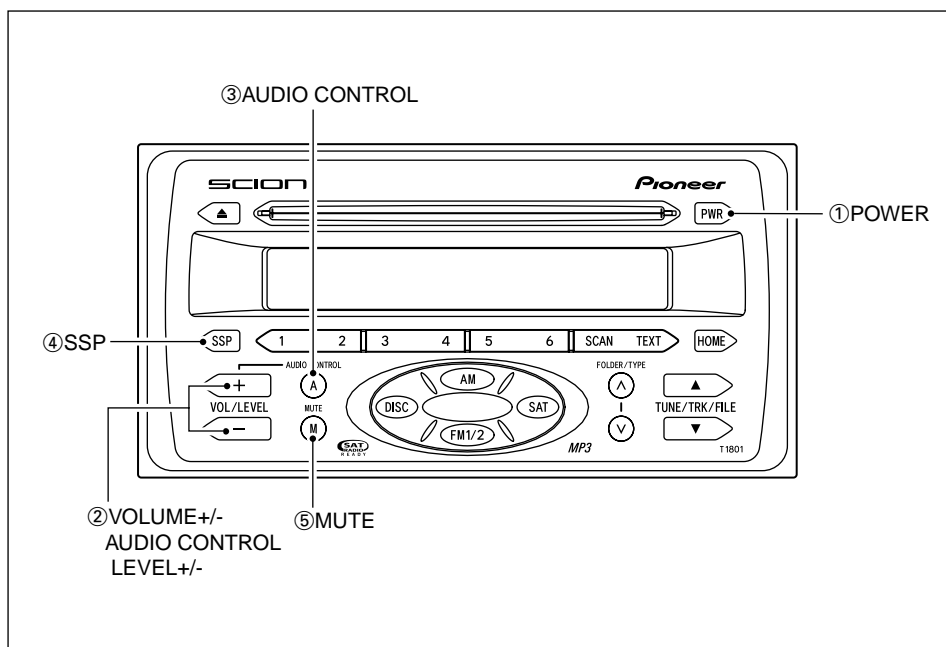
C

D

E

F

8. OPERATIONS



② SSP is an abbreviation of Scion Sound Processing.

Basic Operation

Your audio system works when the ignition switch is in the "ACC" or "ON" position.

NOTICE

In order to prevent too much electric discharge, do not leave the car audio on longer than necessary when the engine is not running.

① PWR

Press to turn the unit on or off.

② VOLUME/LEVEL + -

When the Audio Control mode is OFF, raises / lowers volume (total volume step is 64).

When the Audio Control mode is ON, raises / lowers audio control levels.

③ AUDIO CONTROL

Press and the Audio Control mode cycles through the following order:

BAS (Bass) → TRE (Treble) → FAD (Fader) → BAL (Balance) → VOL (volume) → BAS (Bass)

BAS : Adjust low-pitched tones. The display ranges from -5 to 5.

TRE : Adjust high-pitched tones. The display ranges from -5 to 5.

FAD : Adjust the sound balance between the rear and front speakers. The display ranges from -R7 to -F7.

BAL : Adjust the sound balance between the left and right speakers. The display ranges from -L7 to -R7.

④ SSP (Scion Sound Processing)

SSP is a modified DSP (Digital Signal Processing) system that provides a customized sound for your vehicle. You can select from the modes below.

SSP Neutral : A subdued sound that does not interfere with conversations.

SSP Hear : A powerful, energetic, "live" sound.

SSP Feel : Player sound — reproduces the sound on the stage that musicians hear.

For more details, please visit the SCION Web site at <http://www.scion.com/>.

Each time you press it, the SSP changes in the following order:

SSP Neutral → SSP Hear → SSP Feel → SSP Neutral

⑤ MUTE

To reduce the volume instantaneously, press the MUTE button. **MUTE** will flash on and off.

To cancel this mode, press the MUTE button again.

Listening to the RADIO

NOTICE

Attaching any film or window tint film (especially conductive or metallic type) on the rear glass will noticeably reduce the sensitivity of the radio.

*The car with a pole antenna is object outside.

① AM

Switches to the AM mode.

② FM1/2

Switches between FM1/2 modes.

③ TUNE▲<UP>

Press to manually select (one step at a time) the station with the next higher frequency.

Press and hold until you hear a beep, and automatic station selection begins to select stations in order of increasing frequency.

④ TUNE▼<DOWN>

Press to manually select (one step at a time) the station with the next lower frequency.

Press and hold until you hear a beep, and automatic station selection begins to select stations in order of decreasing frequency.

⑤ PRESET 1-6

Press to recall previously memorized stations (Preset Channels).

Press and hold until you hear a beep, and the station you are currently tuned to is memorized as a Preset Channel.

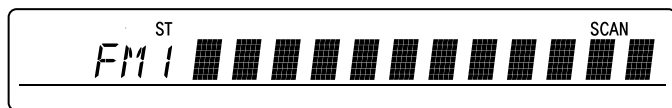
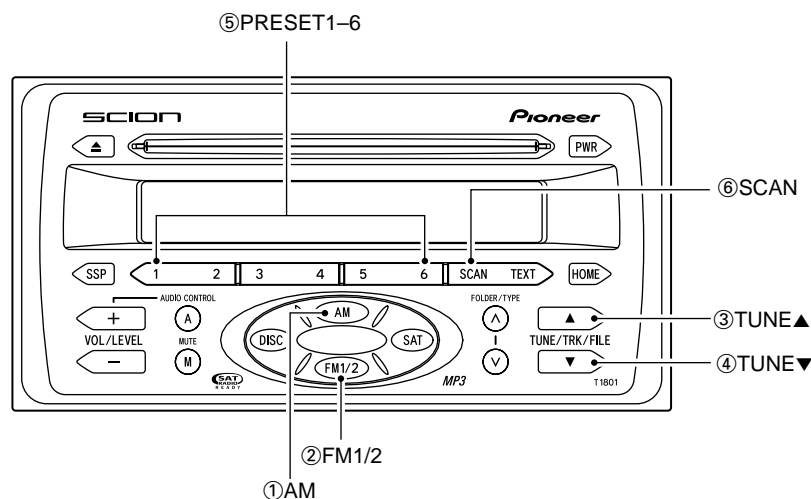
NOTICE

You can store up to 6 stations per band.

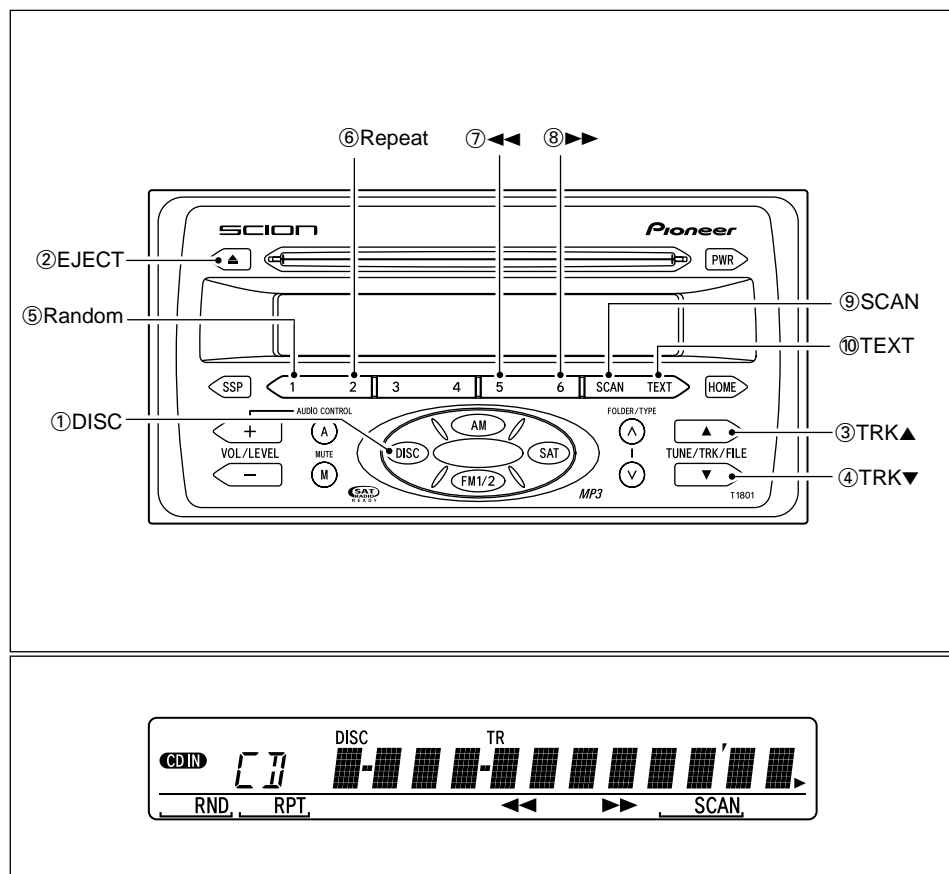
⑥ SCAN

If you press, **SCAN** is indicated in the display and SCAN begins searching for stations with good reception.

If you press and hold until you hear a beep, **SCAN** is indicated in the display and SCAN of preset channels begins.



Listening to a CD



① DISC

Switches to the CD mode. (Only effective if a disc is loaded)

② EJECT

Press to eject the disc currently playing.

③ TRK▲ <UP>

Press to proceed to the next track.

④ TRK▼ <DOWN>

Pressing once takes you back to the start of the track currently playing. Continuing to press takes you back one track at a time.

⑤ PRESET 1 (Random)

If you press this, **RND** is indicated in the display and starts to play tracks on the disc being played in random order. Press again to cancel. **"RND"** is always displayed regardless of this operation.

⑥ PRESET 2 (Repeat)

If you press this, **RPT** is indicated in the display and starts to repeat the track being played. Press again to cancel. **"RPT"** is always displayed regardless of this operation.

⑦ PRESET 5 (<<)

While this is pressed, play of the track is reversed.

⑧ PRESET 6 (>>)

While this is pressed, play of the track is fast forwarded.

⑨ SCAN

If you press this, **SCAN** is indicated in the display and starts to play the first 10 seconds of each track on the CD being played. Press again to cancel.

"SCAN" is always displayed regardless of this operation.

⑩ TEXT

Press, and display indications change as follows:

ELAPSED TIME → DISC TITLE → TR TITLE (track title)

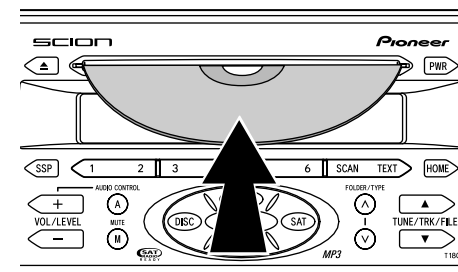
If you press and hold until hear a beep, the page of a display can be changed. A maximum of 2 pages (24 characters) title can be displayed.

NOTICE

- Never try to disassemble or oil any part of the compact disc player. Do not insert anything except a compact disc into the slot.
- You can load an 8 cm disc without using an adaptor. Never use an adaptor.

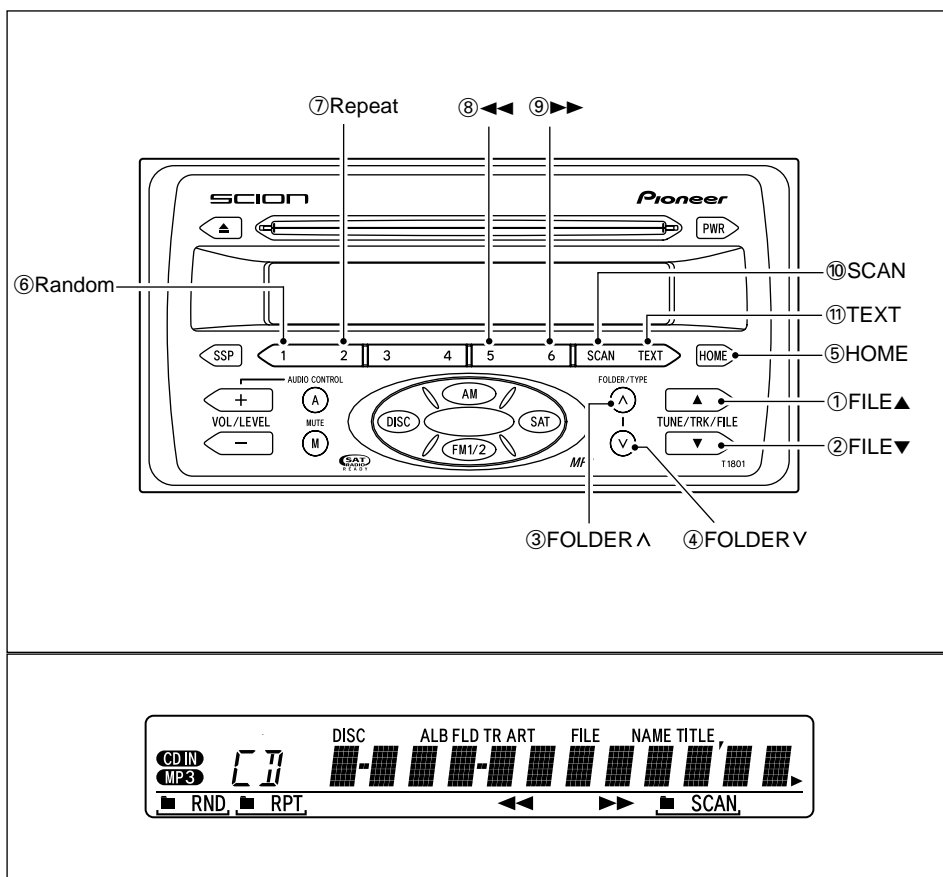
Load a CD in the CD slot.

(**CD IN** lights.)



⚠ CAUTION

Compact disc players use an invisible laser beam which could cause hazardous radiation exposure if directed outside the unit. Be sure to operate the player correctly.



Listening to a MP3 DISC

If you select a MP3 disc, **MP3** is indicated in the display.

① FILE ▲ <UP>

Press to proceed to the next file.

② FILE ▼ <DOWN>

Pressing once takes you back to the start of the file currently playing. Continuing to press takes you one file back at a time.

③ FOLDER ▲ <UP>

Press to proceed to the next folder. (While playing a CD that includes MP3 files, press and hold to switch between CD-DA and MP3 files.)

④ FOLDER ▼ <DOWN>

Press to return to the previous folder.

⑤ HOME

Press to jump to HOME.

⑥ PRESET 1 (Random)

If you press this, **RND** is indicated in the display and starts to play files in the folder being played in random order. Press again to cancel.

If you press and hold until you hear a beep, **RPT** is indicated in the display and starts to play files in all folders on the disc being played in random order. Press again to cancel. "RND" is always displayed regardless of this operation.

⑦ PRESET 2 (Repeat)

If you press this, **RPT** is indicated in the display and starts to repeat the file being played. Press again to cancel. If you press and hold until you hear a beep, **RND** is indicated in the display and starts to repeat the folder being played. Press again to cancel. "RPT" is always displayed regardless of this operation.

⑧ PRESET 5 (◀◀)

While this is pressed, play of the track is reversed. (There is no sound.)

⑨ PRESET 6 (▶▶)

While this is pressed, play of the track is fast forwarded. (There is no sound.)

⑩ SCAN

If you press this, **SCAN** is indicated in the display and starts to play the first 10 seconds of each file in the folder being played. Press again to cancel.

If you press and hold until you hear a beep, **RND** is indicated in the display and starts to play the first 10 seconds of the first file of each folder. Press again to cancel.

"SCAN" is always displayed regardless of this operation.

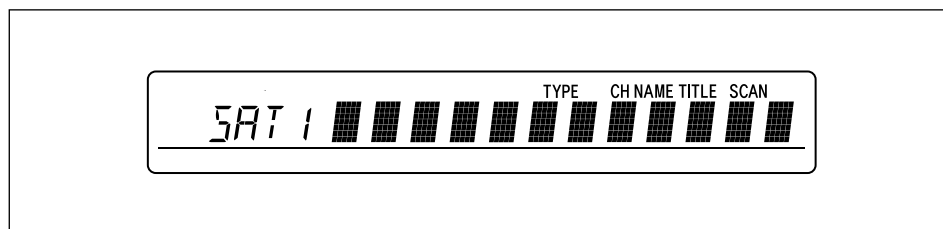
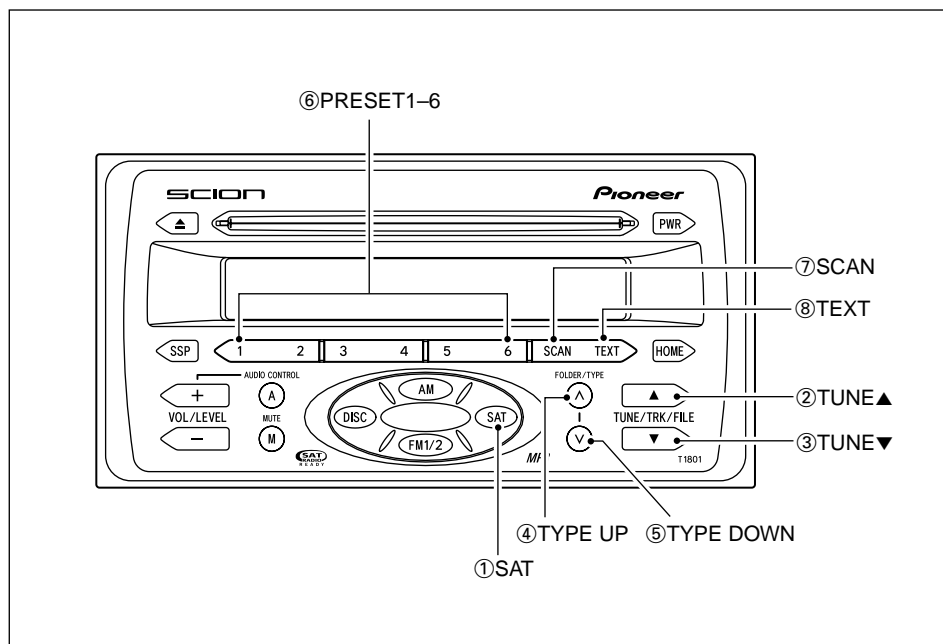
⑪ TEXT

Press and display indications change as follows:

ELAPSED TIME → FLD NAME (Folder name) → FILE NAME → ALB TITLE (Album Title) → TR TITLE (Track Title) → ART NAME (Artist Name)

If you press and hold until hear a beep, the page of a display can be changed. A maximum of 2 pages (24 characters) title can be displayed.

Listening to a XM Satellite Radio broad- cast



④ TYPE <UP>

Press to see Channel Category of channel that is currently received. When Channel Category is displayed (**TYPE** is indicated), press again to switch to the next category.

⑤ TYPE <DOWN>

Press to see Channel Category of channel that is currently received. When Channel Category is displayed (**TYPE** is indicated), press again to switch to the previous category.

⑥ PRESET 1-6

Press to recall previously memorized channels (Preset Channels). Press and hold until you hear a beep, and the channel you are currently receiving will be memorized as a Preset Channel.

NOTICE

You can store up to 6 channels per band.

⑦ SCAN

Press and SCAN of the currently selected type (Channel Category) starts. At this time, **SCAN** is indicated in the display. If you press and hold until you hear a beep, SCAN of preset channels starts.

Also at this time, **SCAN** is indicated in the display.

⑧ TEXT

Press and indication in the display changes as follows:

CH NAME → **TITLE** (SONG/PROGRAM
TITLE) → **NAME** (ARTIST NAME/FEA-
TURE) → **CH NUMBER** → **CH NAME** →

NOTICE

About the display

Up to a maximum of 10 alphanumeric characters can be displayed. (Some information will not be fully displayed.)

① SAT

Switches between the SAT 1/2/3 modes.

② TUNE <UP>

Pressing this lets you select the next higher channel.

If you press and hold, you can rapidly scroll forward through the channels. While displaying Channel Category by TYPE UP/DOWN, pressing this lets you select upward the next channel within currently selected type (Channel Category).

③ TUNE <DOWN>

Pressing this lets you select the previous channel.

If you press and hold, you can rapidly scroll down through the channels. While displaying Channel Category by TYPE UP/DOWN, pressing this lets you select downward the next channel within currently selected type (Channel Category).



Service Manual

ORDER NO.
CRT3026

CD MECHANISM MODULE(S10MP3)

CX-3057

- This service manual describes the operation of the CD mechanism module incorporated in models listed in the table below.
- When performing repairs use this manual together with the specific manual for model under repair.

Model	Service Manual	CD Mechanism Module
DEH-P450MP/XM/UC DEH-P4500MP/XM/UC DEH-P3550MP/XM/ES	CRT3019	CXK5660
DEH-P3500MP/XM/EW	CRT3020	
DEH-P550MP/XN/UC DEH-P5500MP/XN/UC DEH-P5550MP/XN/ES	CRT3002	CXK5661
DEH-P5530MP/XN/EW DEH-P5500MP/XN/EW	CRT3003	

CONTENTS

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2. MECHANISM DESCRIPTIONS.....	20
3. DISASSEMBLY	22

1. CIRCUIT DESCRIPTIONS

Recently, most CD LSI's have included DAC, RF amplifier and other peripheral circuits, as well as the core circuit DSP. This series of mechanisms employ a multi-task LSI UPD63760GJ, which has CD-ROM decoder and MP3 decoder in addition to the CD block as shown in the Fig.1.0.1. This enables to reproduce a CD-ROM where MP3 data is recorded.

Plus, in this lineup, there are WMA supported models available where WMA decoder UPD61002GC is added.

CXK5660 --- WMA non-supported

CXK5661 --- WMA supported

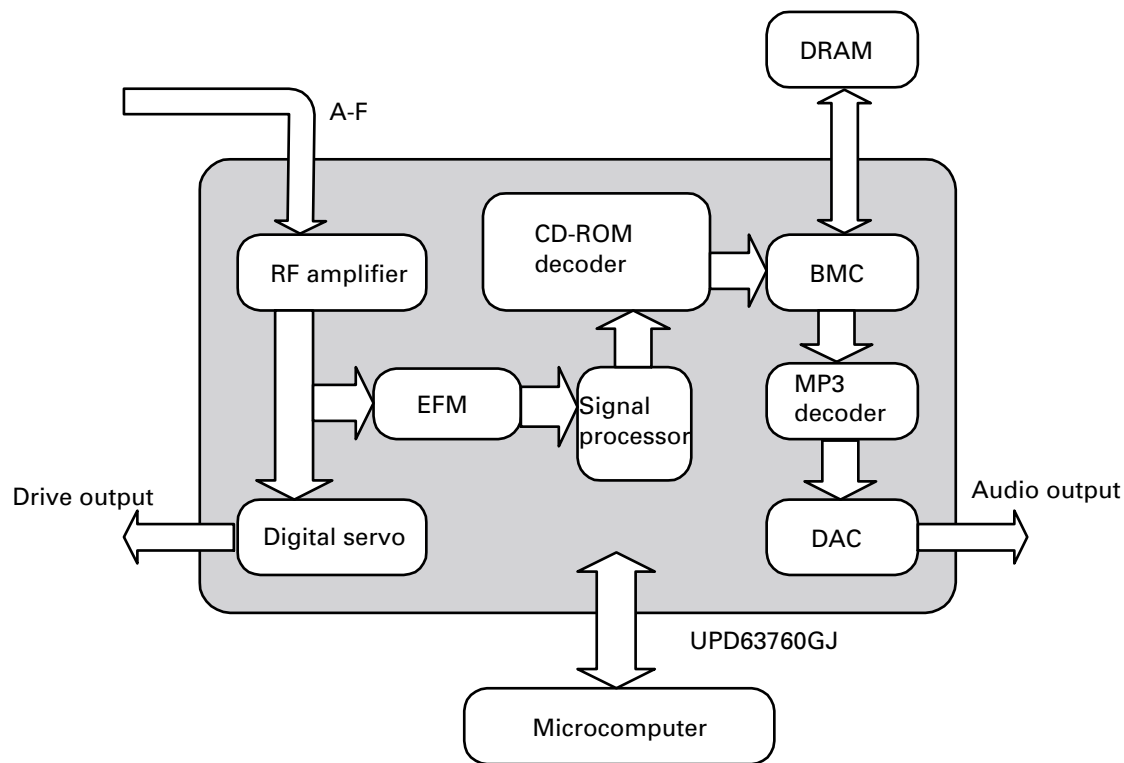


Fig.1.0.1 Block diagram of CD LSI UPD63760GJ

1.1.2 RF and RFAGC amplifiers

The photo-detector outputs (A + C) and (B + D) are added, amplified, and equalized inside this LSI, and then provided as the RF signal from the RFI terminal. The RF signal can be used for eye-pattern check.

The low frequency component of the RFO voltage is:

$$RFO = (A + B + C + D) \times 2$$

The RFO is used for the FOK generation circuit and RF offset adjustment circuit.

The RFI output from the pin 118 is A/C-coupled outside this LSI, and returned to the pin 117 of this LSI. The signal is amplified in the RFAGC amplifier to obtain the RFAGC signal. This LSI is equipped with the RFAGC auto-adjustment function as explained below. This function automatically controls the RFO level to keep at 1.5V by switching the feed-back gain for the RFAGC amplifier.

The RFO signal is also used for the EFM, DFCT, MIRR, and RFAGC auto-adjustment circuits.

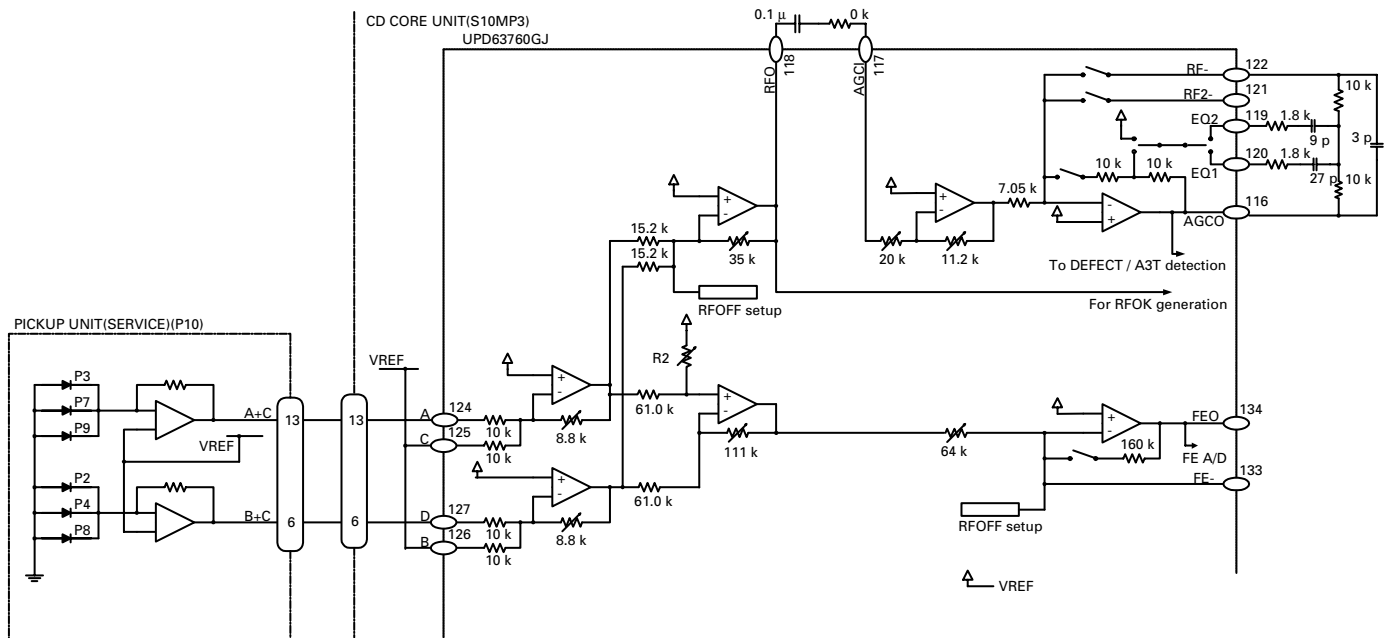


Fig. 1.1.2 RF/AGC/FE

1.1.3 Focus error amplifier

The photo-detector outputs (A + C) and (B + D) are applied to the differential amplifier and the error amplifier to obtain the (A + C - B - D) signal, which is then provided from the pin 91 as the FE signal.

The low frequency component of the FE voltage is:

$$\begin{aligned} FE &= (A + C - B - D) \times 8.8/10k \times 111k/61k \times 160k/64k \\ &= (A + C - B - D) \times 6.0 \end{aligned}$$

The FE output shows 1.5Vp-p S-shaped curve based on the REFO. For the next-stage amplifiers, the cutoff frequency is 14.6kHz.

1.1.4 RFOK

The RFOK circuit generates the RFOK signal, which indicates focus-close timing and focus-close status during the play mode, and outputs from the pin 53. This signal is shifted to "H" when the focus is closed and during the play mode.

The DC level of the RFI signal is peak-held in the digital block and compared with a certain threshold level to generate the RFOK signal. Therefore, even on a non-pit area or a mirror-surface area of a disc, the RFOK becomes "H" and the focus is closed.

This RFOK signal is also applied to the microcomputer via the low-pass filter as the FOK signal, which is used for protection and RF amplifier gain switching.

1.1.5 Tracking error amplifier

The photo-detector outputs E and F are applied to the differential amplifier and the error amplifier to obtain the (E - F) signal, and then provided from the pin 136 as the TE signal.

The low frequency component of the TE voltage is:

$$\begin{aligned} TEO &= (E - F) \times 160k/112k \times 81k/45.4k \times 160k/80k \\ &= (E - F) \times 5.1 \end{aligned}$$

The TE output provides the TE waveform of about 1.3Vp-p based on the REFO. For the next-stage amplifiers, the cut-off frequency is 21.1kHz.

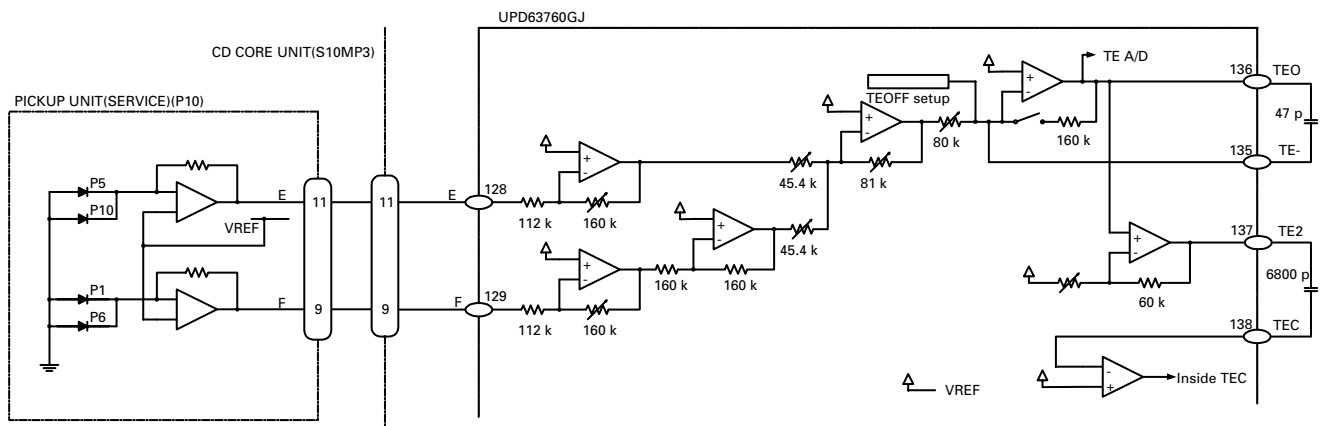


Fig. 1.1.3 TE

1.1.6 Tracking zero-cross amplifier

The tracking zero-cross signal (hereinafter TEC signal) is obtained by amplifying the TE signal 4 times, and used to detect the tracking-error zero-cross point.

By using the information on this point, the following two operations can be performed:

1. Track counting in the carriage move and track jump modes
2. Sensing the lens-moving direction at the moment of the tracking close (The sensing result is used for the tracking brake circuit as explained below.)

The frequency range of the TEC signal is between 300Hz and 20kHz.

TEC voltage = TE level x 4

The TEC level can be calculated at 5.2V. This level exceeds the D range of the operational amplifier, and the signal gets clipped. However, it can be ignored because the CD LSI only uses the signal at the zero-cross point.

1.1.7 EFM

The EFM circuit converts the RF signal into a digital signal expressed in binary digits 0 and 1. The AGCO output from the pin 116 is A/C-coupled in the peripheral circuit, fed back to the LSI from the pin 115, and sent to the EFM circuit inside the LSI.

On scratched or dirty discs, part of the RF signal recorded may be missing. On other discs, part of the RF signal recorded may be asymmetric, which was caused by dispersion in production quality. Such lack of information cannot be completely eliminated by this AC coupling process. Therefore, by utilizing the fifty-fifty occurrence ratio of binary digits (0 and 1) in the EFM signal, the EFM comparator reference voltage ASY is controlled, so that the comparator level always stays around the center of the RFO signal. The reference voltage ASY is made from the EFM comparator output via the low-pass filter. The EFM signal is put out from the pin 111.

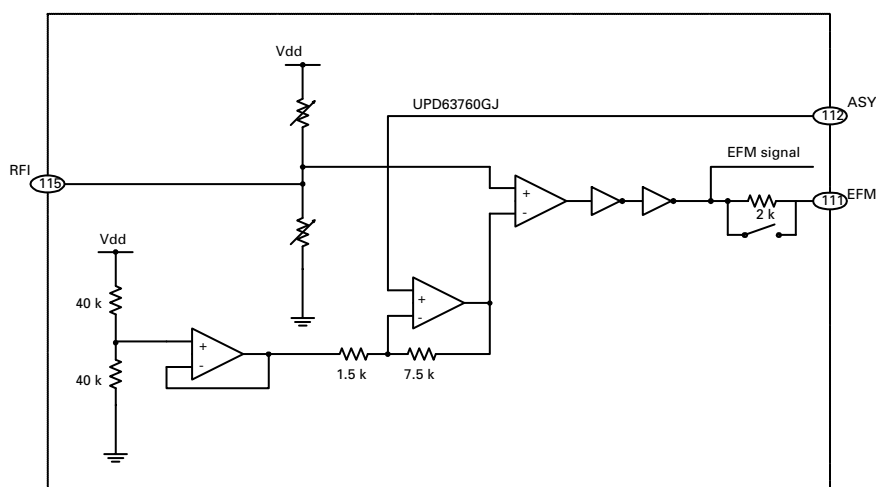


Fig. 1.1.4 EFM

1.2 SERVO BLOCK (UPD63760GJ: IC201)

The servo block controls the servo systems for error signal equalizing, in-focus, track jump and carriage move and so on. The DSP block is a signal-processing block, where data decoding, error correction, and compensation are performed.

After A/D-converted, the FE and TE signals (generated in the preamplifier block) are applied to the servo block and used to generate the drive signals for the focus, tracking, and carriage servos.

The EFM signal is decoded in the DSP block, and finally sent out as the audio signal after D/A-converted. In this decoding process, the spindle servo error signal is generated, supplied to the spindle servo block, and used to generate the spindle drive signal.

The drive signals for focus, tracking, carriage, and spindle servos (FD, TD, SD, and MD) are provided as PWM3 data, and then converted to the analog data by the low-pass filter which uses the operational amplifier embedded in the driver IC BA5996FM (IC301). These analog drive signals can be monitored by the FIN, TIN, CIN, and SIN signals respectively. Afterwards, the signals are amplified and applied to each servo's actuator and motor.

1.2.1 Focus servo system

In the focus servo system, the digital equalizer block works as its main equalizer. The figure 1.2.1 shows the block diagram of the focus servo system.

To close the focus loop circuit, the lens should be moved to within the in-focus range. While moving the lens up and down by using the focus search triangular signal, the system tries to find the in-focus point. In the meantime, the spindle motor rotation is kept at the prescribed one by using the kick mode.

The servo LSI monitors the FE and RFOK signals and automatically performs the focus close operations at an appropriate timing. The focus loop will close when the following three conditions are satisfied at the same time:

- 1) The lens moves toward the disc surface.
- 2) The RFOK signal is shifted to "H".
- 3) The FE signal is zero-crossed. At last, the FE signal comes to the zero level (or REFO).

When the focus loop is closed, the FSS bit is shifted from "H" to "L". The microcomputer starts monitoring the RFOK signal obtained through the low-pass filter 10msec after that.

If the RFOK signal is detected as "L", the microcomputer will take several actions including protection.

The timing chart for focus close operations is shown in fig. 1.2.2.

In the test mode, the S-shaped curve, search voltage, and actual lens movement can be confirmed by pressing the focus close button when the focus mode selector displays 01.

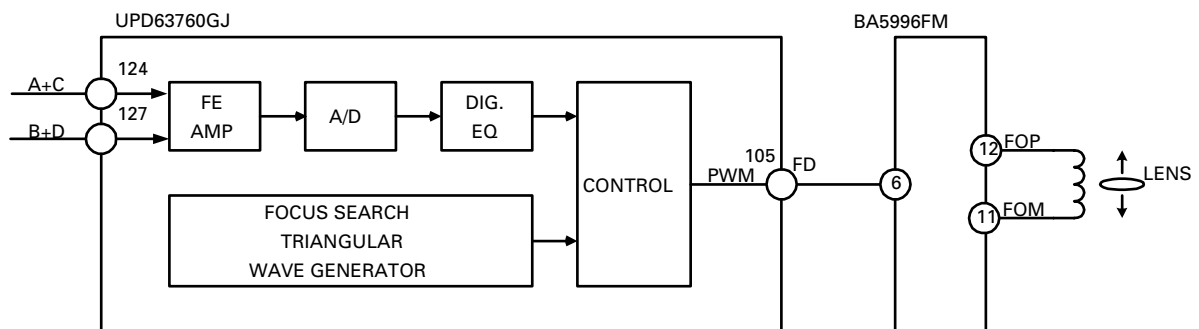


Fig. 1.2.1 Block diagram of the focus servo system

A

B

C

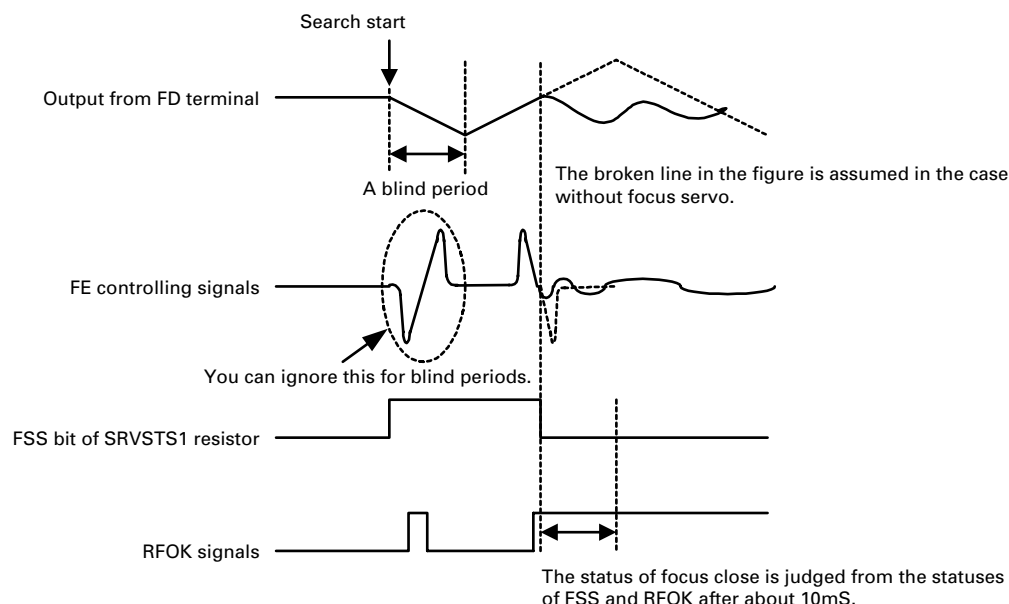


Fig. 1.2.2 Timing chart for focus close operations

1.2.2 Tracking servo system

In the tracking servo system, the digital equalizer block is used as its main equalizer. The figure 1.2.3 shows the block diagram of the tracking servo system.

(a) Track jump

Track jump operation is automatically performed by the auto-sequence function inside the LSI with a command from the microcomputer. In the search mode, the following five track jump modes are available: 1, 4, 10, 32, and 32×3

In the test mode, 1, 32, and 32×3 track jump modes, and carriage move mode are available and can be switched by selecting the mode.

For track jumps, first, the microcomputer sets about half the number of tracks to be jumped as the target. (Ex. For 10 track jumps, it should be 5 or so.) Using the TEC signal, the microcomputer counts up tracks. When the counter reaches the target set by the microcomputer, a brake pulse is sent out to stop the lens. The pulse width is determined by the microcomputer. Then, the system closes the tracking loop and proceeds to the normal play. At this moment, to make it easier to close the tracking loop, the brake circuit is kept ON for 50msec after the brake pulse, and the tracking servo gain is increased.

In the normal operation mode, the FF/REW operation is realized by continuously repeating single jumps about 10 times faster than the normal single jump operation.

(b) Brake circuit

The brake circuit stabilizes the servo-loop close operation even under poor conditions, especially in the setting-up mode or track jump mode. This circuit detects the lens-moving direction and emits only the drive signal for the opposite direction to slow down the lens. Thus, this makes it easier to close the tracking servo loop. The off-track direction is detected from the phases of the TEC and MIRR signals.

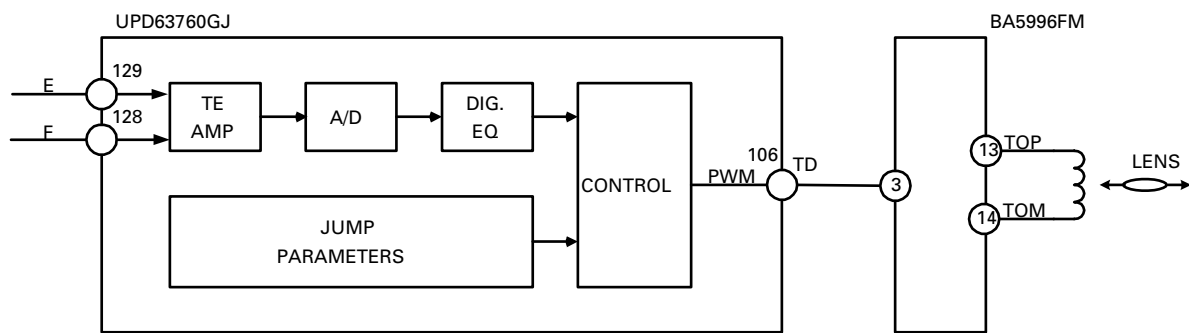


Fig. 1.2.3 Block diagram of the tracking servo system

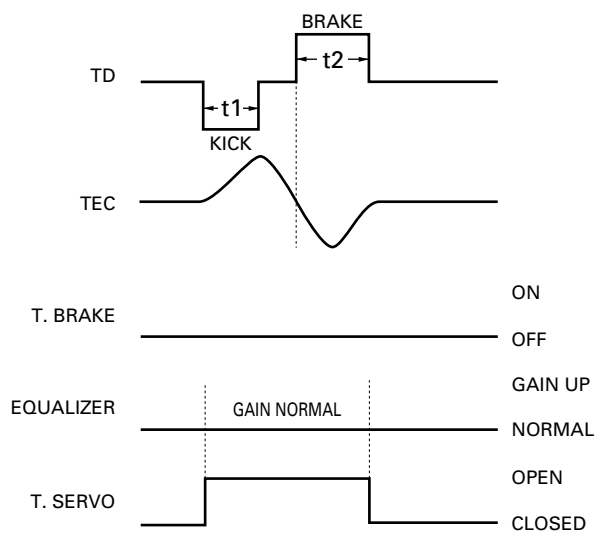


Fig. 1.2.4 Single-track jump

A

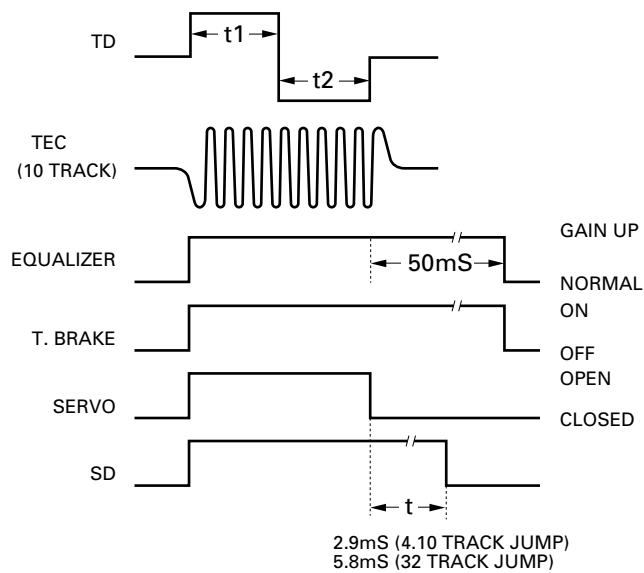
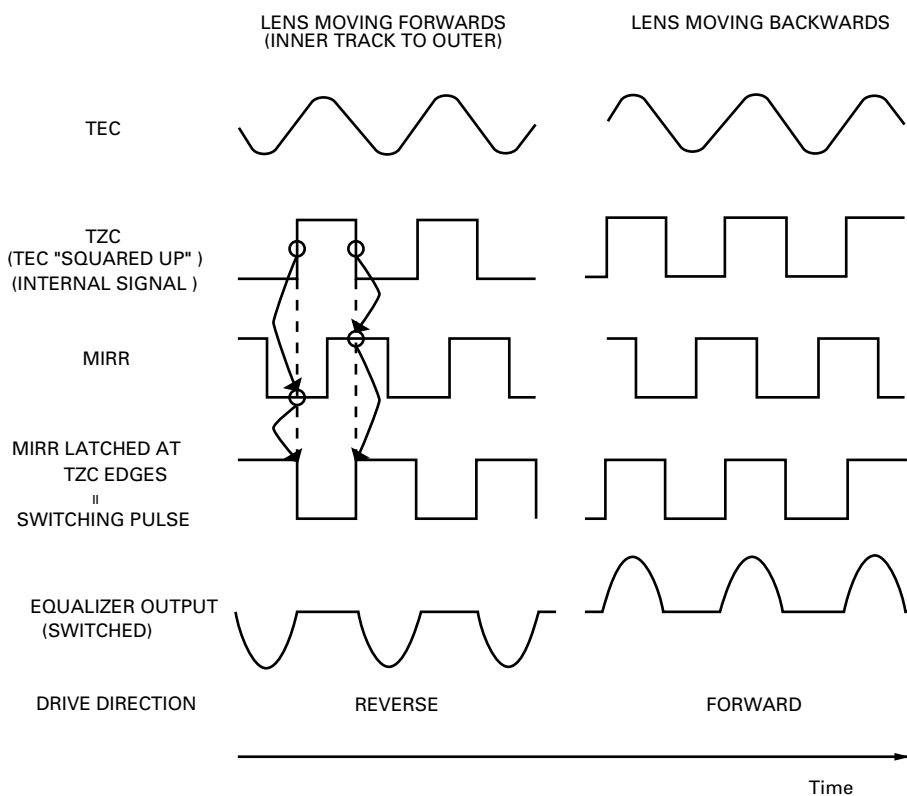


Fig. 1.2.5 Multi-track jump

C

D

E



Note : Equalizer output assumed to have same phase as TEC.

F

Fig. 1.2.6 Track brake

1.2.3 Carriage servo system

In the carriage servo system, the low frequency component from the tracking equalizer (the information on the lens position) is transferred to the carriage equalizer, where the gain is increased to a certain level, and then sent out from the LSI as the carriage drive signal. This signal is applied to the carriage motor via the driver IC.

During the play mode, when the lens offset reaches a certain level, it is necessary to move the pickup toward the FORWARD direction. The equalizer gain is adjusted so that the output over the carriage motor starting voltage is sent out in such a case. In actual operations, only when the equalizer output exceeds the threshold level preset in the servo LSI, the drive signal is sent out. This can reduce the consumption power.

With an eccentric disc loaded, before the whole pickup starts moving, the equalizer output may exceed the threshold level a few times. In this case, the drive signal applied from the LSI shows pulse-like waveforms.

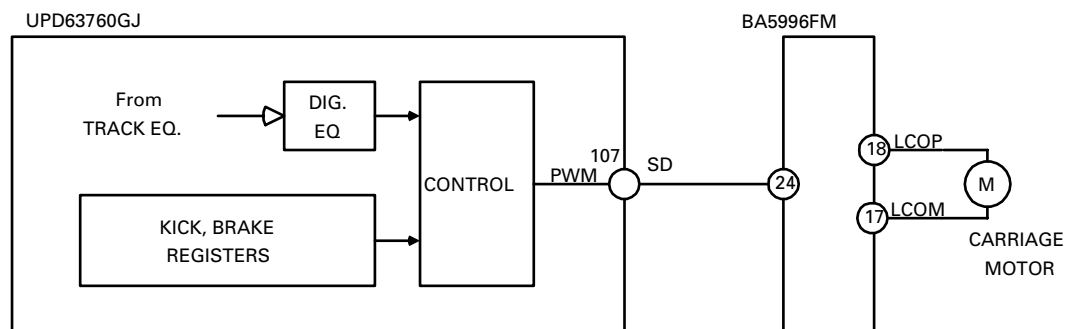


Fig. 1.2.7 Block diagram for the carriage servo block

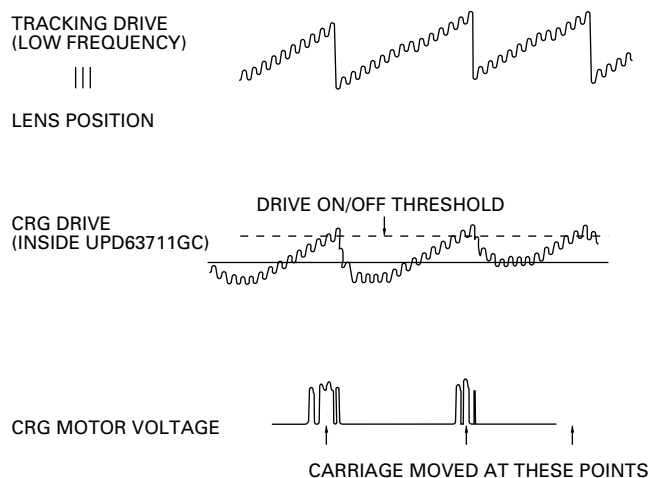


Fig. 1.2.8 Waveforms of the carriage signal

1.2.4 Spindle servo system

In the spindle servo system, the following seven modes are available:

1) Kick

Used to accelerate the disc rotation in the setting-up mode.

2) Offset

a. Used in the setting-up mode until the AGC completes after the kick mode.

b. Used when the focus loop is unlocked during the play mode and until it is locked again.

In both cases, the mode is to keep the disc rotation near to the appropriate one.

3) Applicable servo

In the normal operation, the CLV servo mode is used.

The EFM demodulation block detects through WFK/16 sampling whether or not the frame sync signal and the internal frame counter output are synchronized, and generates the status signal based on the sampling result, synchronized or non-synchronized. If eight consecutive "non-sync" signals are obtained, the system senses the status as "non-sync". If not, the system senses as "sync". In the applicable servo mode, the leading-in servo mode is automatically selected at the non-sync status, and the normal servo mode is at the sync status.

4) Brake

Used to stop the spindle motor.

In accordance with the microcomputer's command, the brake voltage is sent out from the servo LSI. At this moment, the EFM waveform is being monitored in this LSI. When the longest EFM pattern exceeds a certain cycle (or the rotation slows down enough), a flag is set inside the LSI, and the microcomputer switches off the brake voltage. If a flag is not set within a certain period, the microcomputer shifts the mode from the brake mode to the stop mode, and keeps this for a certain period. In the eject mode, after the mode is shifted to the stop mode and a certain period passes, the loaded disc is ejected.

5) Stop

Used when the power is turned on and during the eject mode. At this moment, the voltage through the spindle motor is 0V.

6) Rough servo

Used when the carriage is moved (or in the carriage move mode such as long search).

By obtaining the linear velocity from the EFM waveform, "H" or "L" is applied to the spindle equalizer. In the test mode, this mode is used for grating confirmation.

7) Rotation speed

CD-DA and CD-ROM are controlled differently at their rotation speeds. Both of them are done by the double speed in the setting-up mode when a disc gets inserted. However, CD-DA is done by the standard speed in the setting-up mode starting from SOURCE ON/ACC ON with the disc inside, while CD-ROM is still done by the double speed. During the play mode, the rotation speed of CD-DA is always the standard speed, while that of CD-ROM is always the double speed.

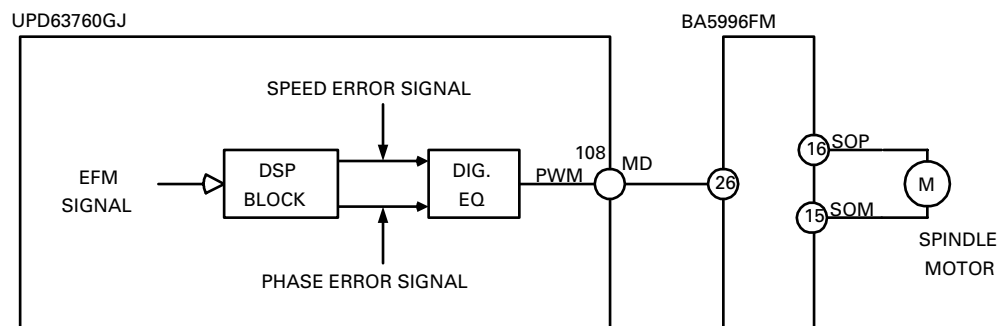


Fig.1.2.9 Block diagram of the spindle servo system

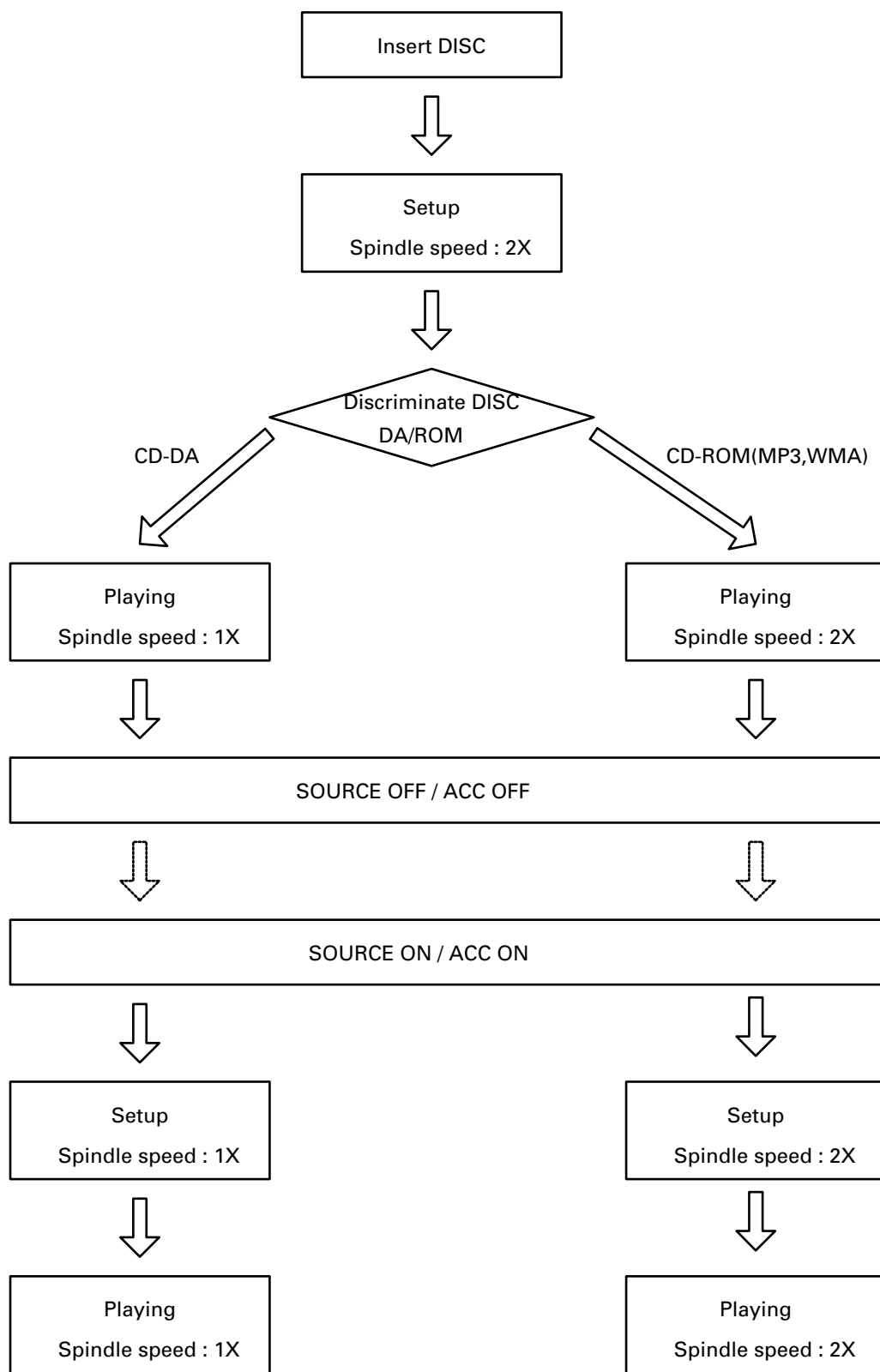


Fig.1.2.10 Dual spindle drive(x1 / x2)

1.3 AUTOMATIC ADJUSTMENT FUNCTION

This system automatically handles the circuit adjustment inside the CD LSI. All adjustments are performed whenever a disc is inserted or the CD mode is selected by pressing the source key. Each adjustment will be explained below.

1.3.1 TE, FE, and RF offset auto-adjustment

This adjustment is made to adjust the offsets of the TE, FE, and RF amplifiers in the preamplifier block to their target values on the basis of the REFO when the power is turned on. (The target values for TE, FE, and RE offsets are 0V, 0V, and -0.8V respectively.)

<Adjusting procedures>

- 1) With the LD OFF status, the microcomputer reads each offset through the servo LSI.
- 2) The microcomputer calculates the voltages for correction from the measured values, and inputs the calculated results as the offset adjustment values.

1.3.2 Tracking balance (T.BAL) auto-adjustment

This adjustment is to equalize the pickup output offsets for E-ch and F-ch by changing the amplifier gain inside the LSI. Actually, the gain is adjusted so that the TE waveform becomes symmetrical on each side of the REFO.

<Adjusting procedures>

- 1) The focus loop is closed.
- 2) The lens is kicked in the radial direction to make certain that the TE waveform is generated.
- 3) The microcomputer reads the TE offset calculated in the LSI through the servo LSI.
- 4) The microcomputer takes either of the following steps depending on the calculated offset:
 - When the offset is 0, the adjustment completes.
 - When the offset is positive or negative, the amp gains for E-ch and F-ch should be changed.

The steps 2) to 4) are repeatedly taken until the offset becomes 0 or the repeating time reaches the limit frequency.

1.3.3 EF bias auto-adjustment

This adjustment obtains the best focus point during the play mode and maximizes the RFI level by utilizing the phase difference between the 3T level of the RF signal and that of the signal obtained when focus error disturbance is applied to the focus loop. At this moment, the auto-gain control (AGC), where focus error disturbance is applied to the focus and tracking loops, is also performed as explained below.

<Adjusting procedures>

- 1) The microcomputer transmits the command to apply disturbance component to the focus loop (inside the servo LSI).
- 2) In the LSI, the 3T-offset component of the RF signal is detected.
- 3) From the relation between the 3T detected component and the disturbance, the LSI obtains the volume and direction of the focus offset.
- 4) The microcomputer transmits the command and reads out the detecting result from the servo LSI.
- 5) The microcomputer calculates the necessary correction and inputs the result as the bias adjustment value to the servo LSI.

The adjusting steps are repeated a few times for higher adjustment accuracy as same as those for the AGC.

1.3.4 Focus and tracking AGC

This function automatically adjusts the focus and tracking servo loop gains.

<Adjusting procedures>

- 1) Disturbance component is applied to the servo loop.
 - 2) The error signals (FE and TE) are extracted through the band pass filter as the G1 and G2 signals.
 - 3) The microcomputer reads the G1 and G2 signals through the servo LSI.
 - 4) The microcomputer calculates the necessary correction and performs the loop gain adjustment inside the servo LSI.
- For higher adjustment accuracy, the above steps are repeated a few times.

1.3.5 RF level auto-adjustment (RFAGC)

This adjustment minimizes the dispersion of the RF level (RFO), which may be caused by disc-related errors, for more stable signal transmission by changing the amp gain between RFI and RFO.

<Adjusting procedures>

- 1) The microcomputer sends the command to the servo LSI to read out the output from the RF level detecting circuit inside the servo LSI.
- 2) The microcomputer calculates the appropriate amp gain by using the output read out to adjust the RFO level at the prescribed one.
- 3) The microcomputer sends the command to the servo LSI to adjust the amp gain into the calculated one.

This adjustment is automatically performed when:

- 1) During the setting-up mode, only the focus close operation ends.
- 2) Immediately before the setting-up ends (or right before the play mode starts)
- 3) During the play mode, the focus loop is locked again after unlocked.

1.3.6 Preamplifier gain adjustment

In this adjustment, when the reflected beams from disc surface are extremely weak (ex. when the lens is dirty, and a CD-RW is loaded), the whole gain in the RFAMP block (FE, TE, and RF amplifiers) is increased by +6dB or +12dB.

<Adjusting procedures>

When the system senses that the reflected beams from disc surface are extremely weak during the setting-up mode, the whole RFAMP gain is increased by +6dB or +12dB.

After the gain is changed, the setting-up mode is restarted.

If the whole RFAMP gain is always increased to the +6dB level in the play mode, the +6dB level will be employed at the starting of the setting-up mode from the next playback.

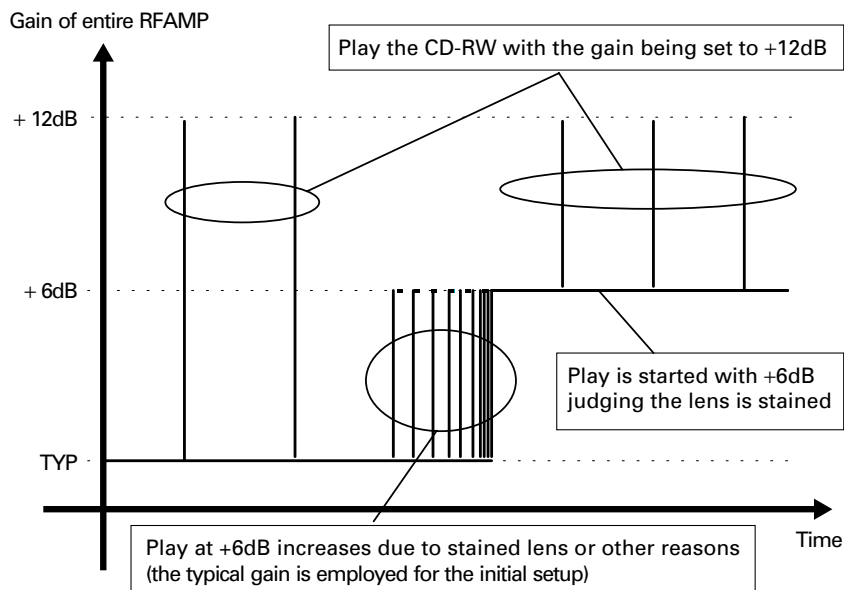


Fig.1.3.1 Pre-amp gain adjustment

1.3.7 Initial values in adjustment

For each auto-adjustment, the last adjustment results are basically used as the initial settings of the next adjustment unless the microcomputer is turned off (or the backup is off). When the microcomputer (or the backup) is turned off, the last adjustment results are not used, but the factory settings.

1.3.8 Adjustment result display

For some of the adjustments (FE and RF offset, FZD cancel, F and T gain, and RFAGC), the adjustment results can be displayed and confirmed in the test mode.

1) FE and RF offset

Reference coefficient = 32 ("32" indicates no adjustment required)

The display is expressed in the unit of about 32mV.

Ex. When the FE offset coefficient is 35:

$$35 - 32 = 3 \times 32\text{mV} = 96\text{mV}$$

This means that the correction is about +96mV, and the FE offset before adjustment is -96mV.

2) F and T gain adjustment

Reference coefficient for focus and tracking = 20

The displayed coefficient / the reference coefficient indicates the adjusted gain.

Ex. When the AGC coefficient is 40:

$$40/20 = 2 \text{ times (+6dB)}$$

That is, the gain was adjusted by +6dB.

(The original loop gain was half the target one. So, the whole gain was doubled.)

3) RF level adjustment (RFAGC)

Reference coefficient = 8

The coefficient 9 to 15 indicates increasing the RF level.

The coefficient 0 to 7 indicates decreasing the RF level.

When the coefficient display changes by 1, the gain changes by 0.7 to 1dB.

When the coefficient is 15, the gain is maximum or TYP + 6.5dB.

When the coefficient is 0, the gain is minimum or TYP - 6.0dB.

1.4 POWER SUPPLY AND LOADING BLOCK

The VD ($8.3 \pm 0.5V$), the VD2 ($5.6 \pm 0.5V$) and the VDD ($5.0 \pm 0.25V$), which are supplied from the mother PC board, are used for the power supply. In this system, the following four power-supply signals are available: the VD (for the drive system), the V3R3 obtained from the VD2 via the 3.3V regulator (for the control system: 3.3V), the VDD (for the microcomputer: 5V), and the 3VDD obtained from the VDD via the 3.3V regulator (for the microcomputer: 3.3V).

In the WMA-supported mechanism CXK5661, the V2R5 obtained from the VD2 via the 2.5V regulator (for WMA decoder: 2.5V) is also used.

The microcomputer can turn on/off the CD driver (except for the load and eject modes) and the 3.3V signal by controlling the "CONT" and "CD3VON" signals respectively. To turn on/off the loading drive, there is no control terminal in the microcomputer, but the "LOEJ" input signal works as the control one. In the LCO output block, the "CLCONT" signal is used to switch between the loading mode and carriage mode.

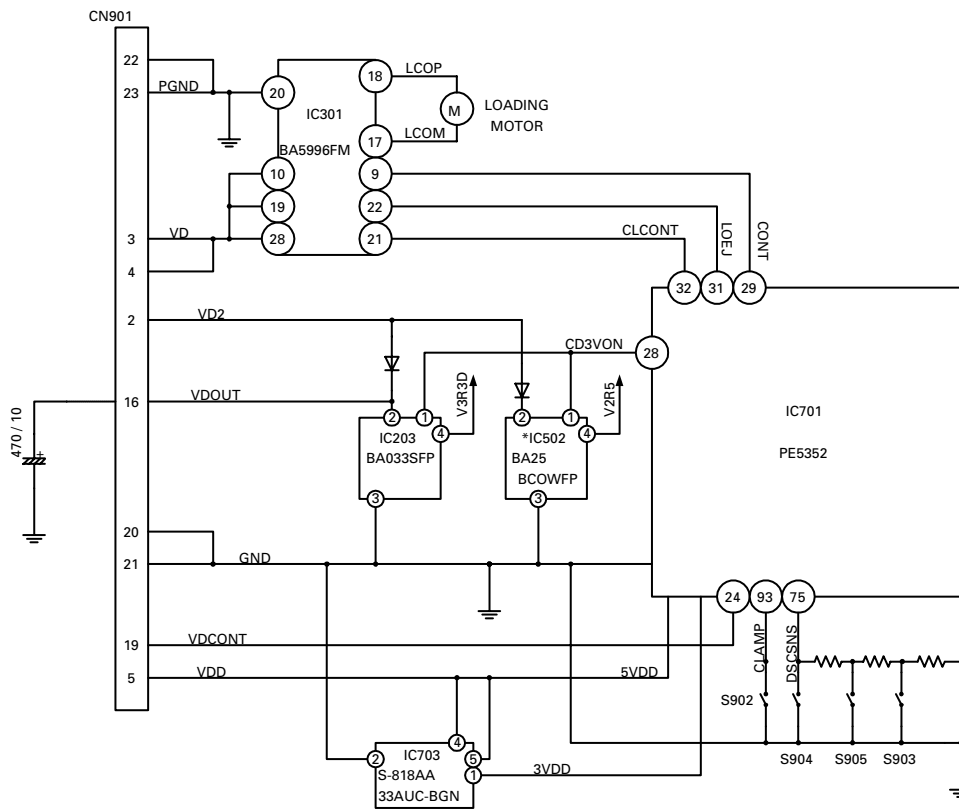


Fig. 1.4.1 Power supply/loading block (*: CXK5661)

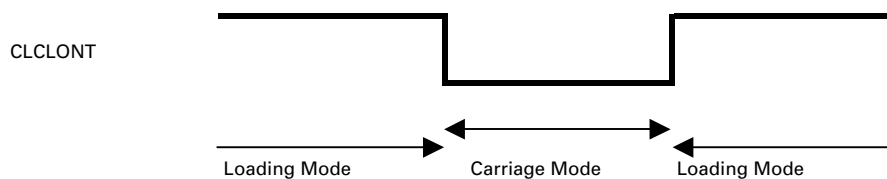


Fig. 1.4.2 Loading/carriage mode shift

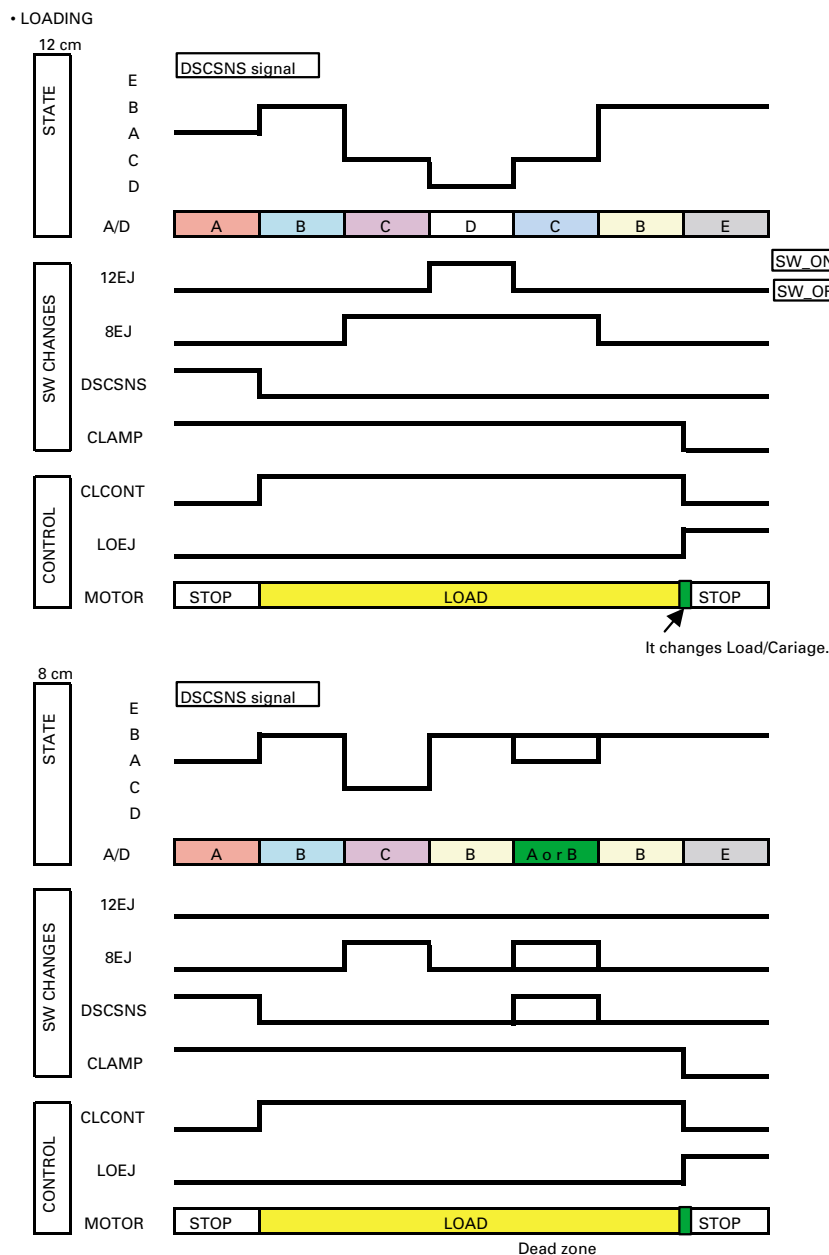
To control the load and eject operations, the clamp switch located in the mechanism unit and the three detecting switches located in the control unit are used. Depending on the combination of these switches' ON/OFF status, the DSCSNS voltage changes.

The microcomputer can detect the status (A to E) by observing the voltage at the A/D port. The disc size detection (8 or 12cm) is also performed through this status change. The DSCSNS status and the status change in the load and

Status	A	B	C	D	E
SW1 S904	0	0	0	1	0
SW2 S905	0	0	1	1	0
SW3 S903	1	0	0	0	0
SW4 S902	1	1	1	1	0
Mecha	No DISC				CLMP

eject modes are shown in the figures 1.4.3 and 1.4.4 respectively.

Fig.1.4.3 DSCSNS status



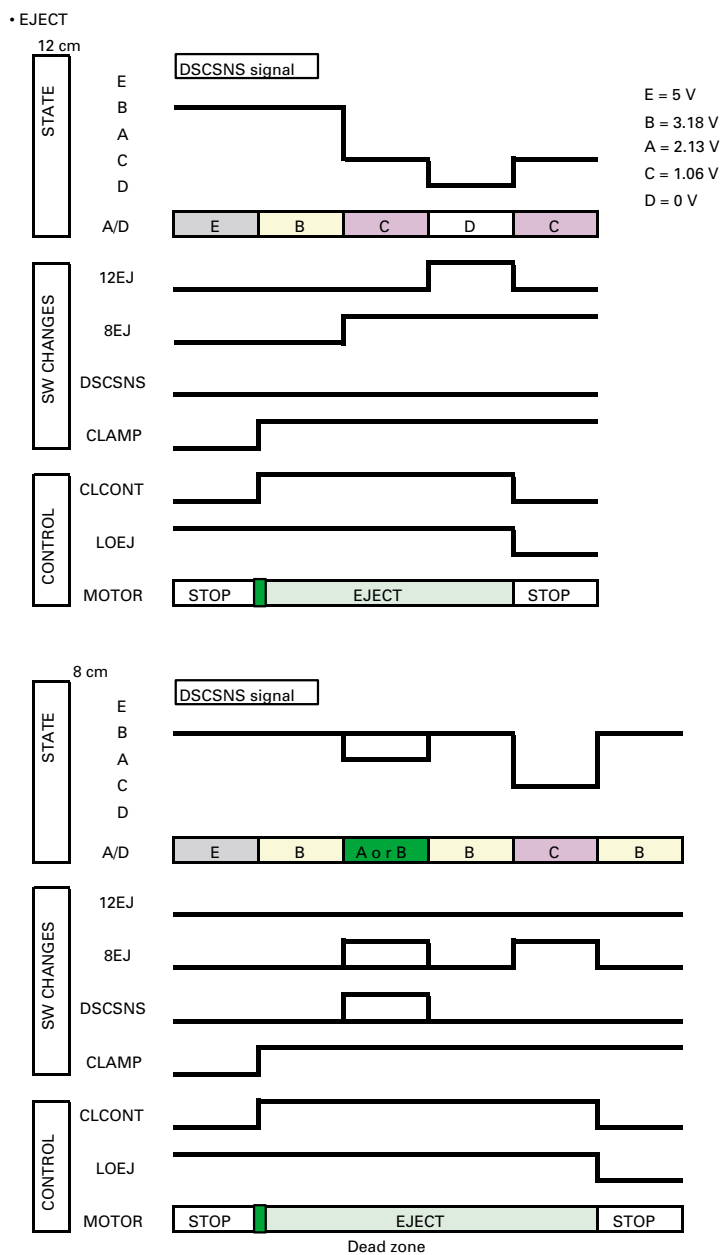
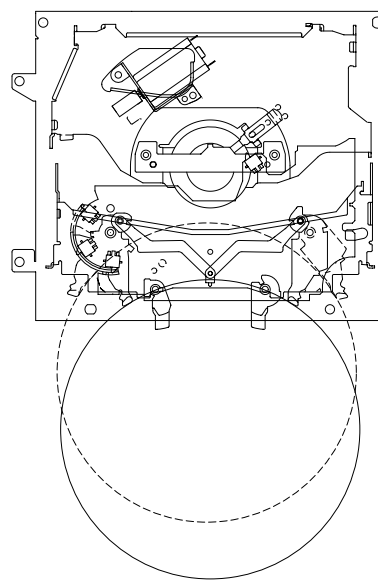
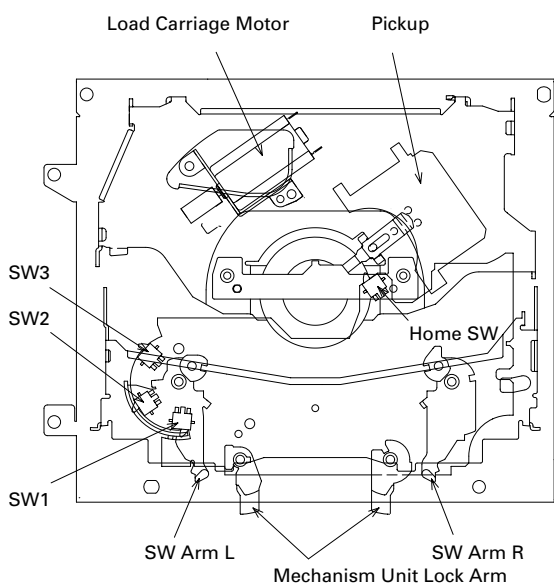


Fig.1.4.4 Status change in LOAD and EJECT modes

2. MECHANISM DESCRIPTIONS

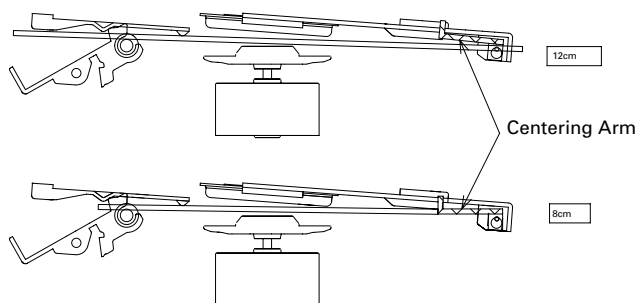
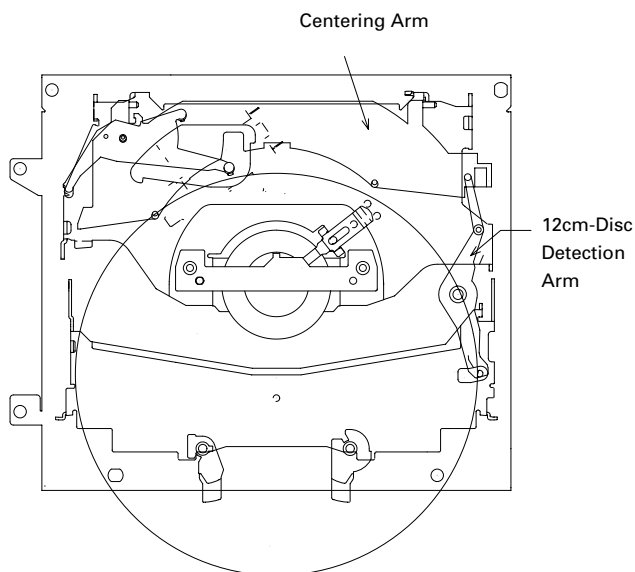
● Loading actions

1. When a disc is inserted, SW Arm L and R rotate. Due to the rotation of Arm L, SW1 is switched from ON to OFF and the Load Carriage Motor starts.
 2. If the disc is 12cm-disc, when it is carried to the position shown with the dotted line in the drawing, SW 3 switches to ON due to such rotation of Arm. Then, the microcomputer judges that the disc is 12cm-disc.
 3. In case of 8cm-disc, the disc cannot reach such dotted line position, and from such limitation of approach, the microcomputer judges that the disc is 8cm-disc and simply triggers clamp actions.
- (Movement of SW Arm L and R are connected together. So, if pushing force is fed to only one arm, the distance between tow arms cannot be widened beyond the specific degree, because the coupling part is locked in such case.)



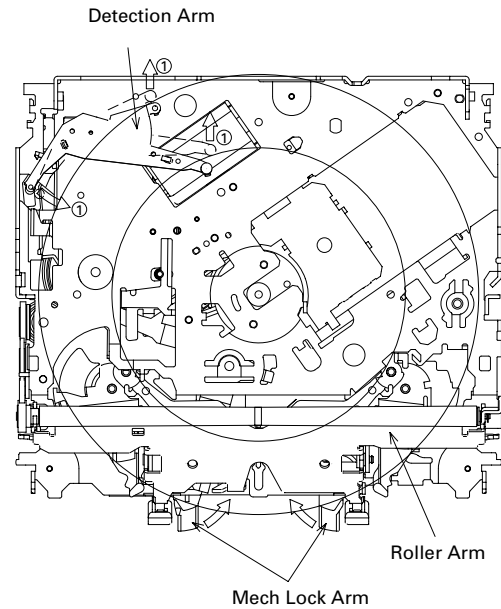
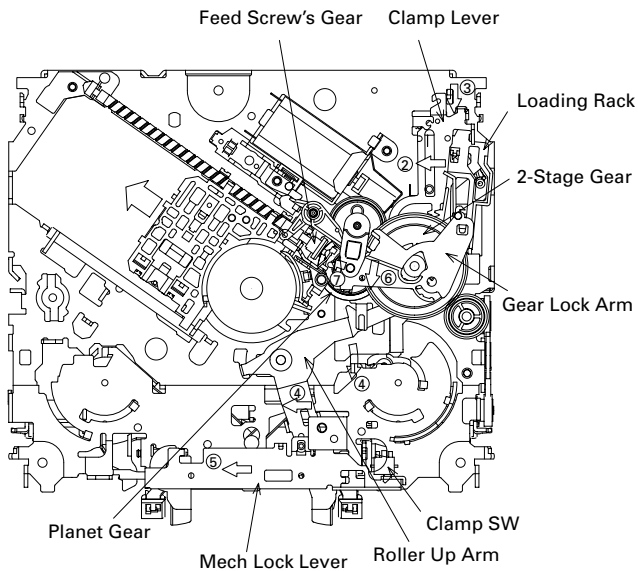
● Disc centering mechanism

1. In case of 12cm-disc, the 12cm-Disc Detection Arm rotates, and with such rotation, it raises the Centering Arms to retreat the arms from disc's trace. The disc passes through under the arms, and at the inner part, it is centered.
2. In case of 8cm-disc, it is just centered at the position where its edge touches the front portion of the Centering Arm.



● Clamp actions

1. When an 8 or 12cm disc is placed on the center of the spindle, the detection arm starts moving.
2. The movement of the detection arm engages the loading rack with the 2-stage gear.
3. The clamp lever slides to lower the clamp arm. At this time, the roller up arm rotates to separate the roller arm from the disc. The roller arm moves the mech lock lever and turns the mech lock arm to release the mech lock. At the position where the clamp switch is turned off, the clamp operation ends.
4. After the clamp operation, the clamp lever moves to rotate the gear lock arm. The planet gear separates from the 2-stage gear to get engaged with the pickup feed screw's gear. Then the carriage operation will start.



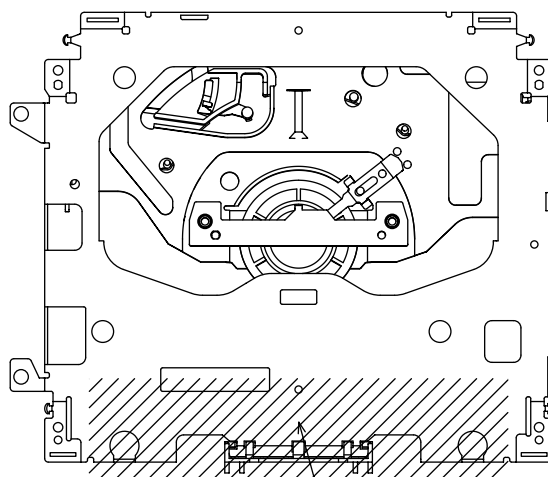
● Eject actions

1. Eject actions start when the Pickup is fed to the position inner than "Home SW ON" point in the internal circumference of the circle, caused by backward rotation of the Load Carriage Motor. Eject actions follow the foregoing procedures (steps taken in loading, centering and clamping actions), but each action in those steps is performed in reversed manner.
2. In case of 12cm-disc, Eject is completed when SW3 completes its condition- transition of OFF → ON → OFF.
3. For 8cm-disc, Eject is completed when SW2 completes its condition-transition of OFF → ON → OFF.

3. DISASSEMBLY

● How to hold the Mechanism Unit

1. Hold the top and bottom frame.
2. Do not squeeze top frame's front portion too tight, because it is fragile.

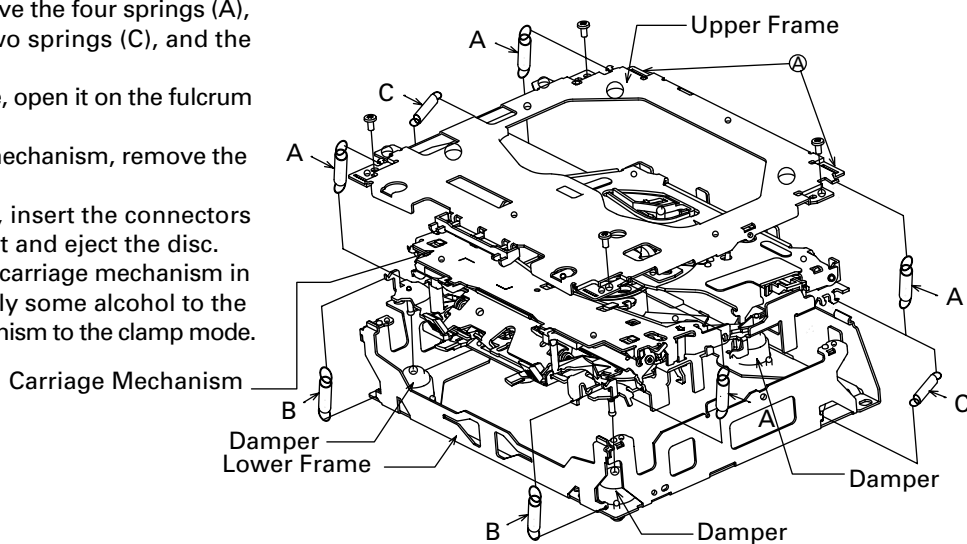


Do not squeeze.

● Removing the Upper and Lower Frames

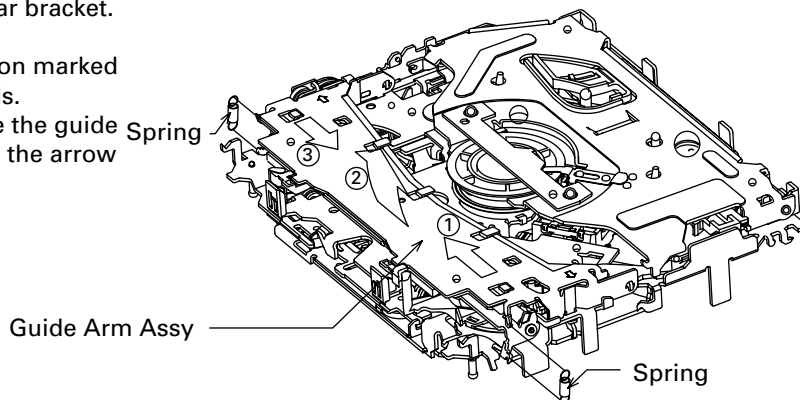
1. With a disc clamped, remove the four springs (A), the two springs (B), the two springs (C), and the four screws.
2. To remove the upper frame, open it on the fulcrum A.
3. While lifting the carriage mechanism, remove the three dampers.
4. With the frames removed, insert the connectors coming from the main unit and eject the disc.

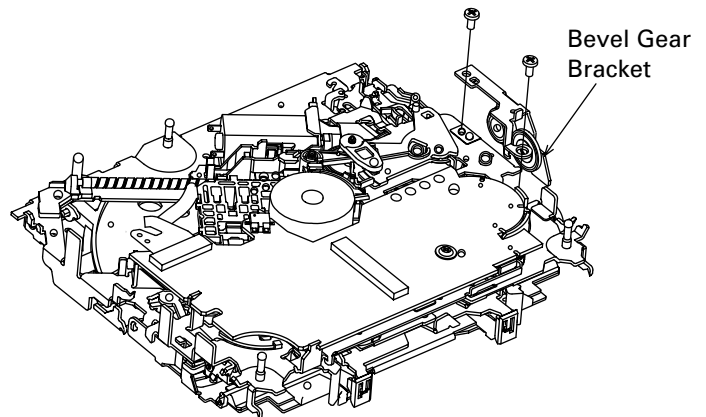
Caution: Before installing the carriage mechanism in the frames, be sure to apply some alcohol to the dampers and set the mechanism to the clamp mode.



● Removing the Guide Arm Assy

1. Remove the upper and lower frames and set the mechanism to the clamp mode.
2. Remove the two springs.
3. Remove the two screws and bevel gear bracket. Note that the gears come off.
4. Slide the guide arm assy in the direction marked with the arrow (1) and open it upwards.
5. At the angle of about 45 degrees, slide the guide arm assy in the direction marked with the arrow (3) to remove it.

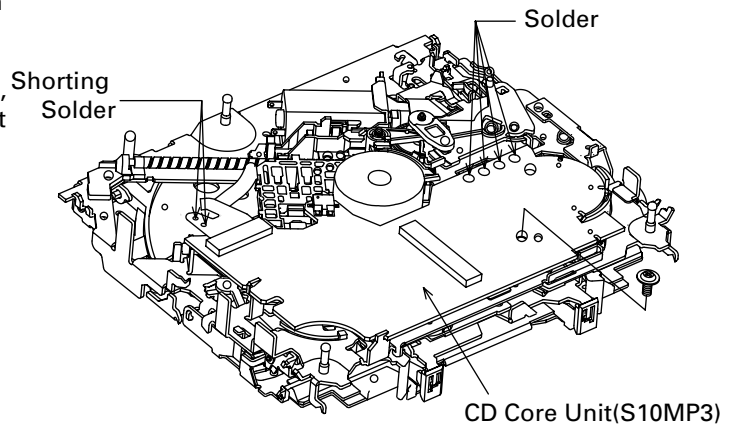




● Removing the CD Core Unit(S10MP3)

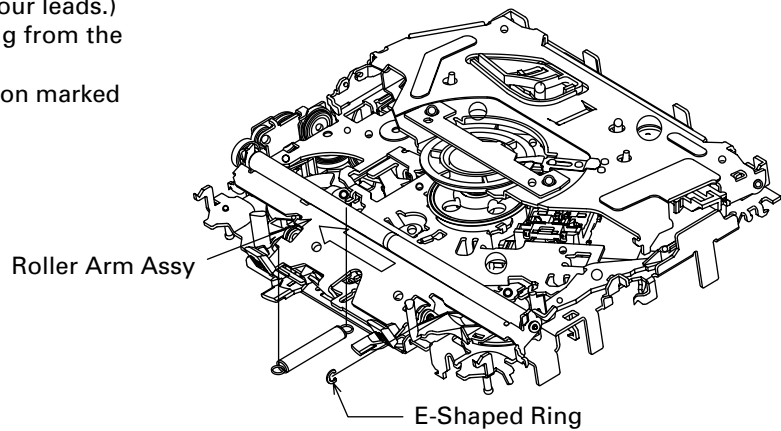
1. Apply shorting solder to the Pickup flexible cable. Disconnect the cable.
2. Remove the solder from the four leads, and loosen the screw.
3. Remove the CD core unit(S10MP3).

Caution: When assembling the CD core unit(S10MP3), set the mechanism to the clamp mode to protect the switches from any damage.



● Removing the Roller Arm Assy

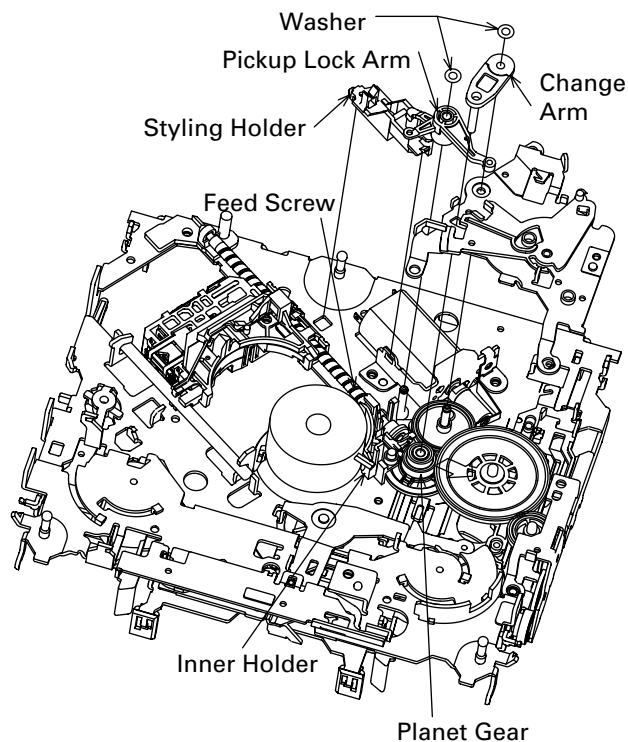
1. Remove the guide arm assy and set the mechanism to the eject mode.
2. Remove the CD core unit(S10MP3). (You do not have to remove the solder from the four leads.)
3. Remove the spring and E-shaped ring from the fulcrum shaft.
4. Slide the roller arm assy in the direction marked with an arrow.



● Removing the Pickup Unit

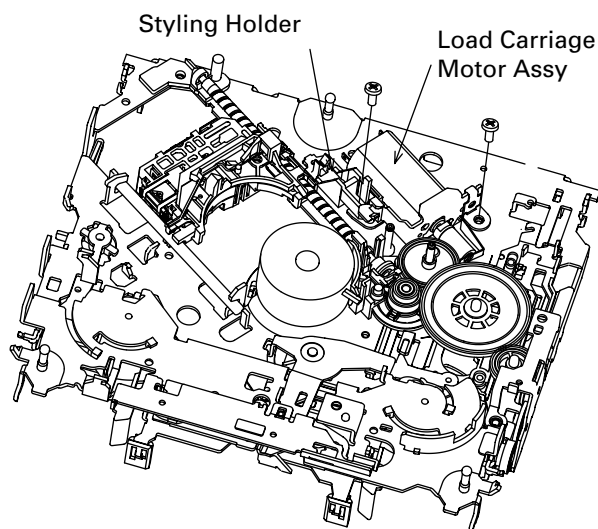
1. Set the mechanism to the clamp mode.
2. Remove the lead wires from the inner holder.
3. Remove the two washers, styling holder, change arm, and pickup lock arm.
4. While releasing from the hook of the inner holder, lift the end of the feed screw.

Caution: In assembling, move the planet gear to the load/eject position before setting the feed screw in the inner holder.



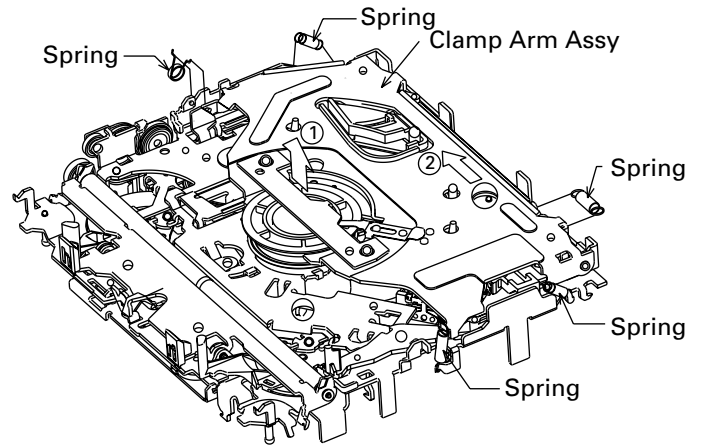
● Removing the Load Carriage Motor Assy

1. Release the leads from the styling holder and remove the holder.
2. Remove the two screws.
3. Remove the load carriage motor assy.



● Removing the Clamp Arm Assy

1. Remove the five springs.
2. While lifting the clamp arm assy, slide it in the direction marked with the arrow (2) to remove it.



● Removing the Spindle Motor

1. Remove the two screws. Take off the spindle motor.

